



Land Retrieval from PolSAR

Eric POTTIER
20 / 11 / 2019

ESA–MOST China Dragon 4 Cooperation

2019 ADVANCED INTERNATIONAL TRAINING COURSE IN LAND REMOTE SENSING

中欧科技合作“龙计划”第四期 2019年陆地遥感高级培训班

18 to 23 November 2019 | Chongqing University, P.R. China



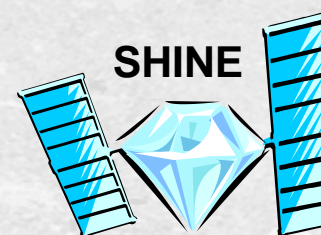
培训时间: 2019年11月18日-23日 主办方: 重庆大学



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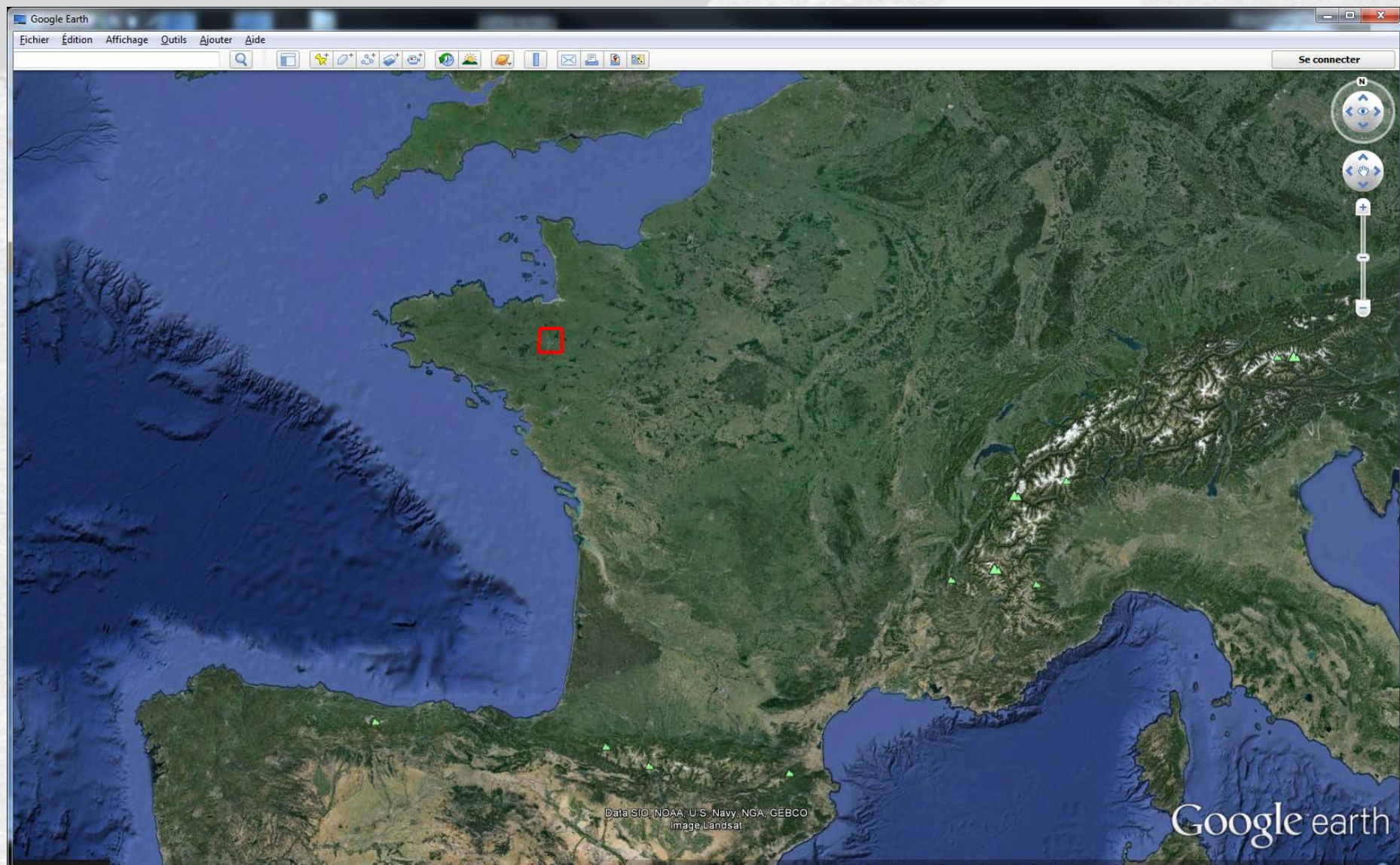


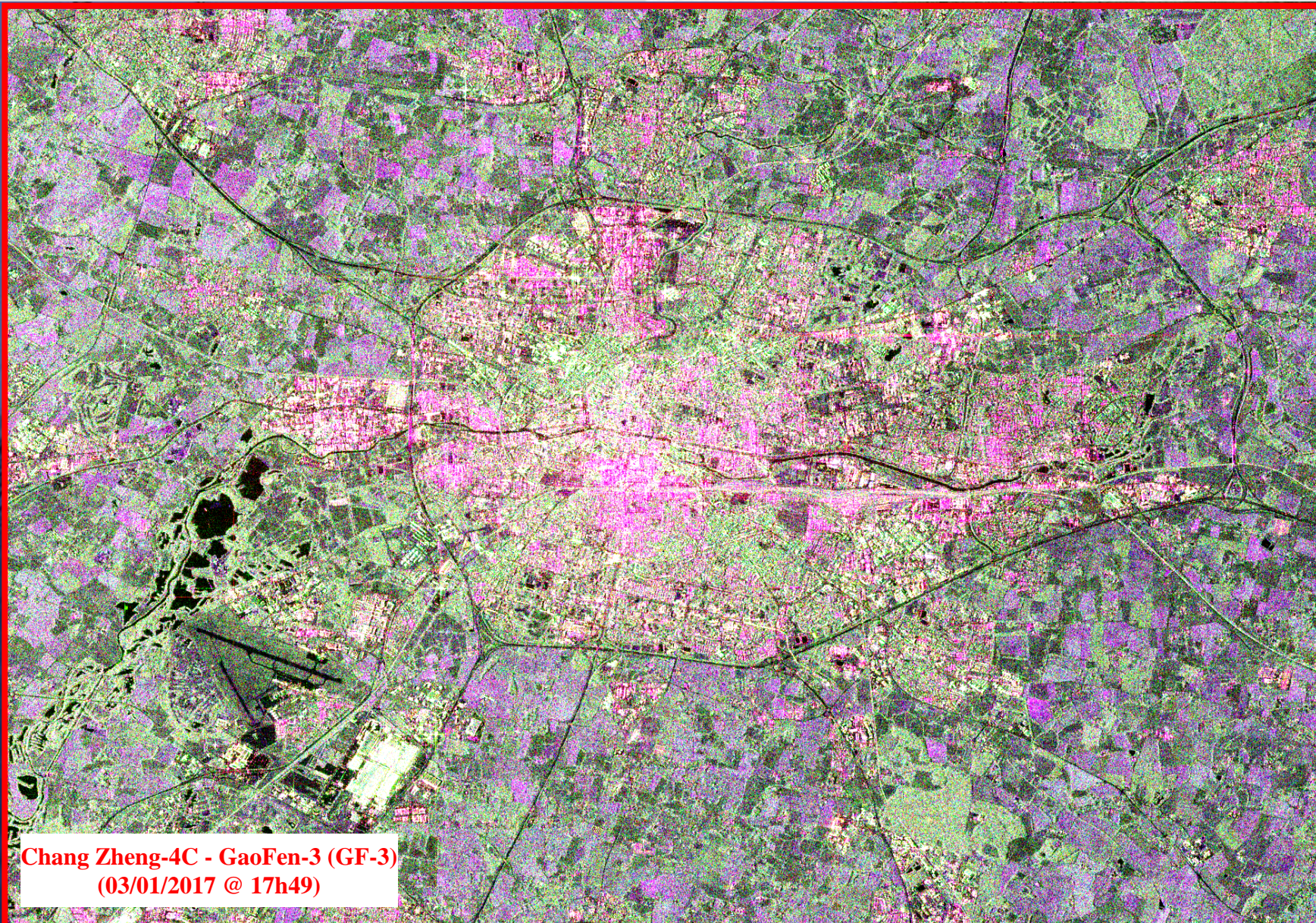
I.E.T.R. - UMR CNRS 6164
Université de Rennes I - Campus de Beaulieu
Pôle Micro Ondes Radar - Bat 11D
263 Avenue Général Leclerc
CS 74205 - 35042 Rennes Cedex – France



**SAR & Hyperspectral multi-modal Imaging
and sigNal processing,
Electromagnetic modeling**



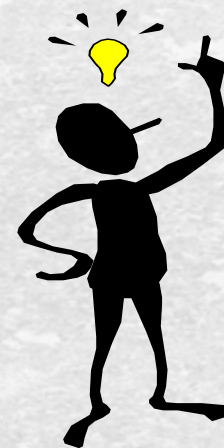




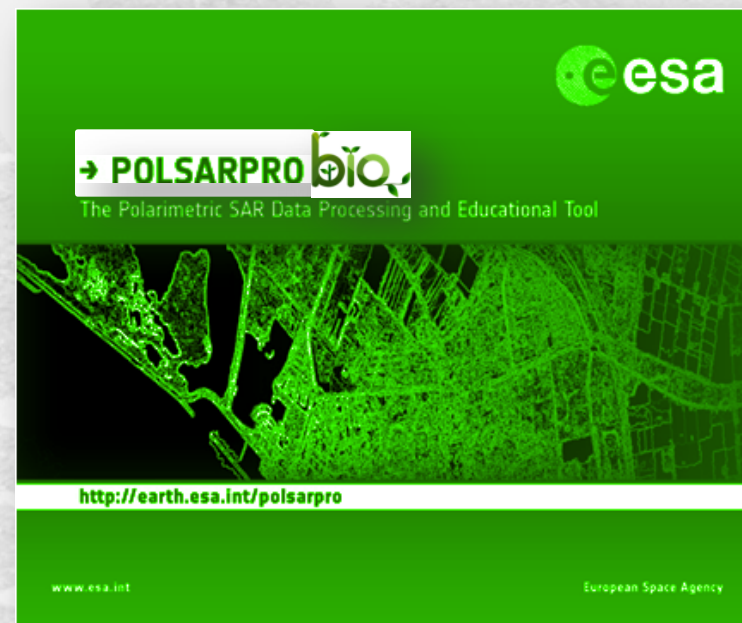
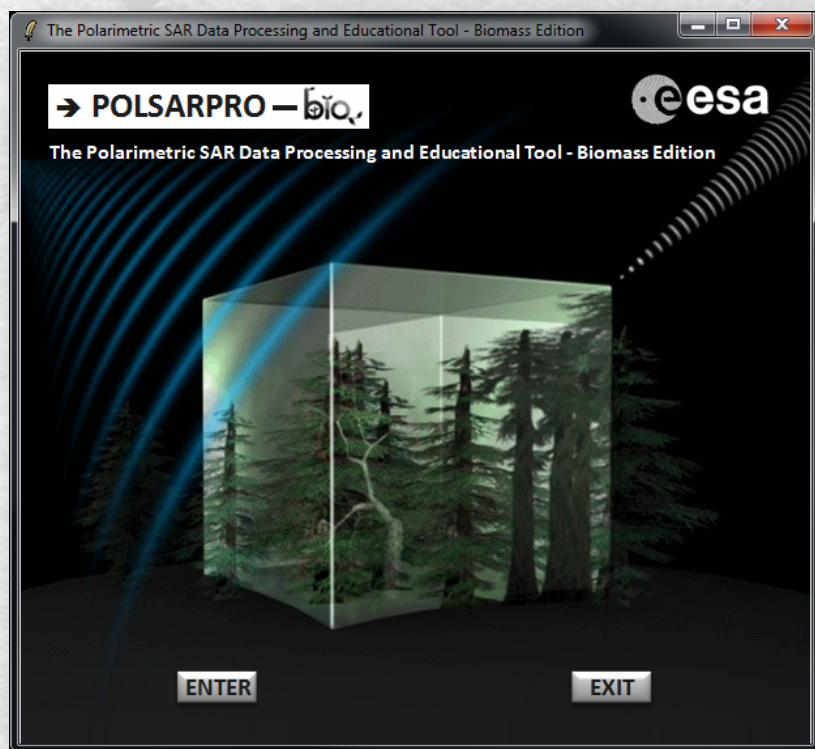
Chang Zheng-4C - GaoFen-3 (GF-3)
(03/01/2017 @ 17h49)

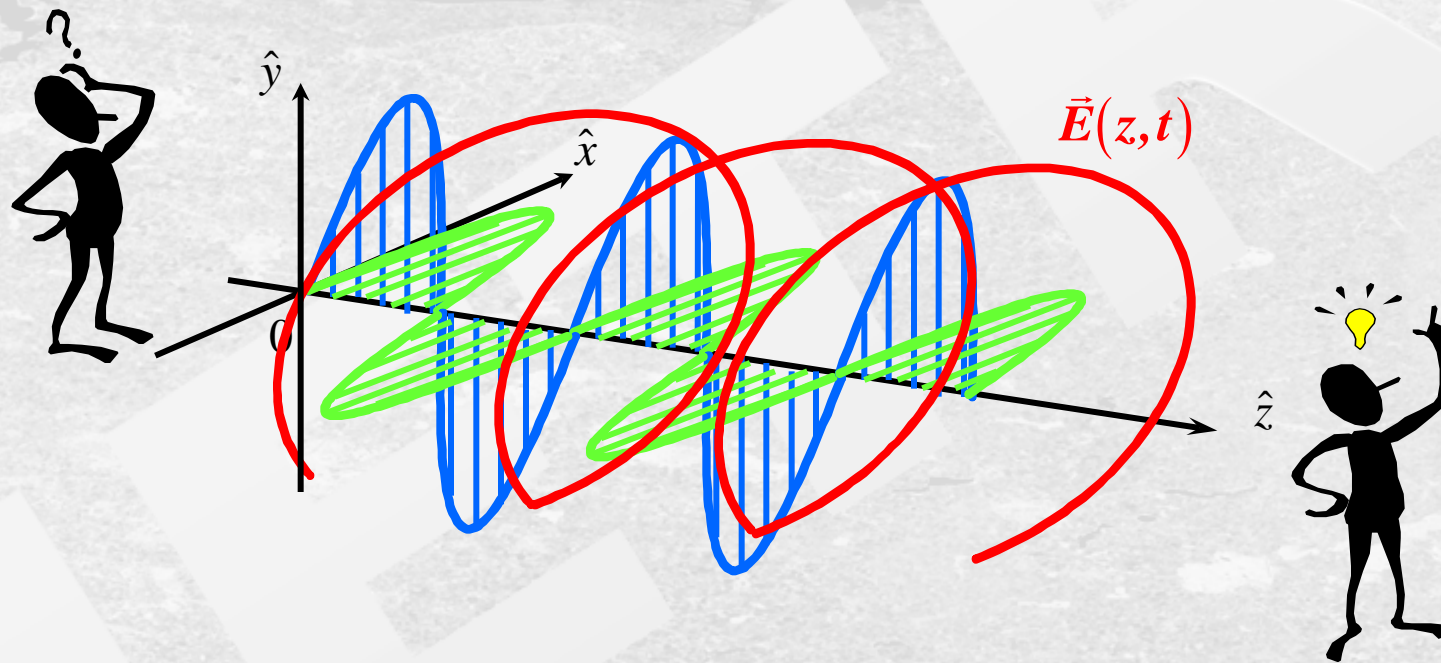


Objective
To provide
the minimum, but necessary,
amount of knowledge required
to understand
scientific works on
Radar Polarimetry



Practicals





DATASETS



AIRSAR **JPL**

DC8

P, L, C-Band (Quad)



© Google Earth



© Google Earth



|HH+VV|
 $T_{11}=2A_0$

|HV|
 $T_{33}=B_0-B$

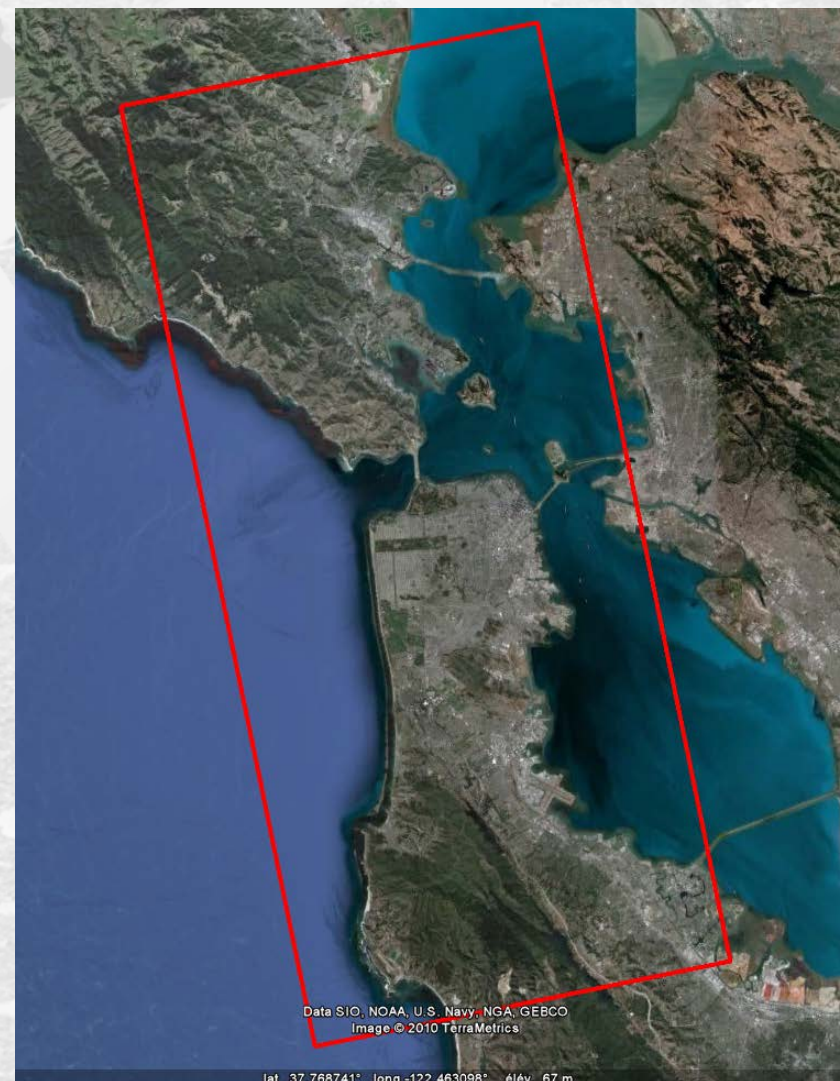
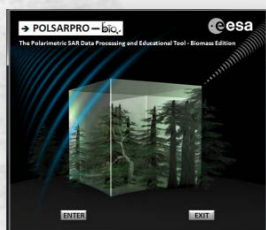
|HH-VV|
 $T_{22}=B_0+B$



ALOS - PALSAR

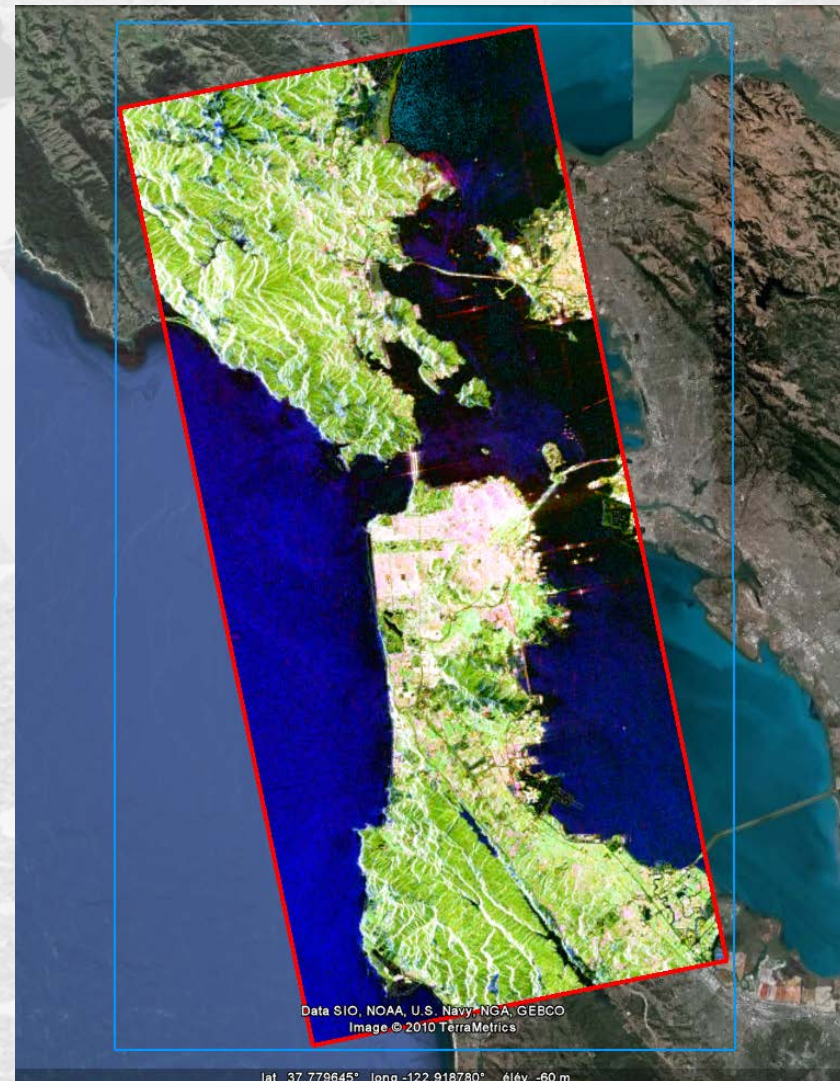
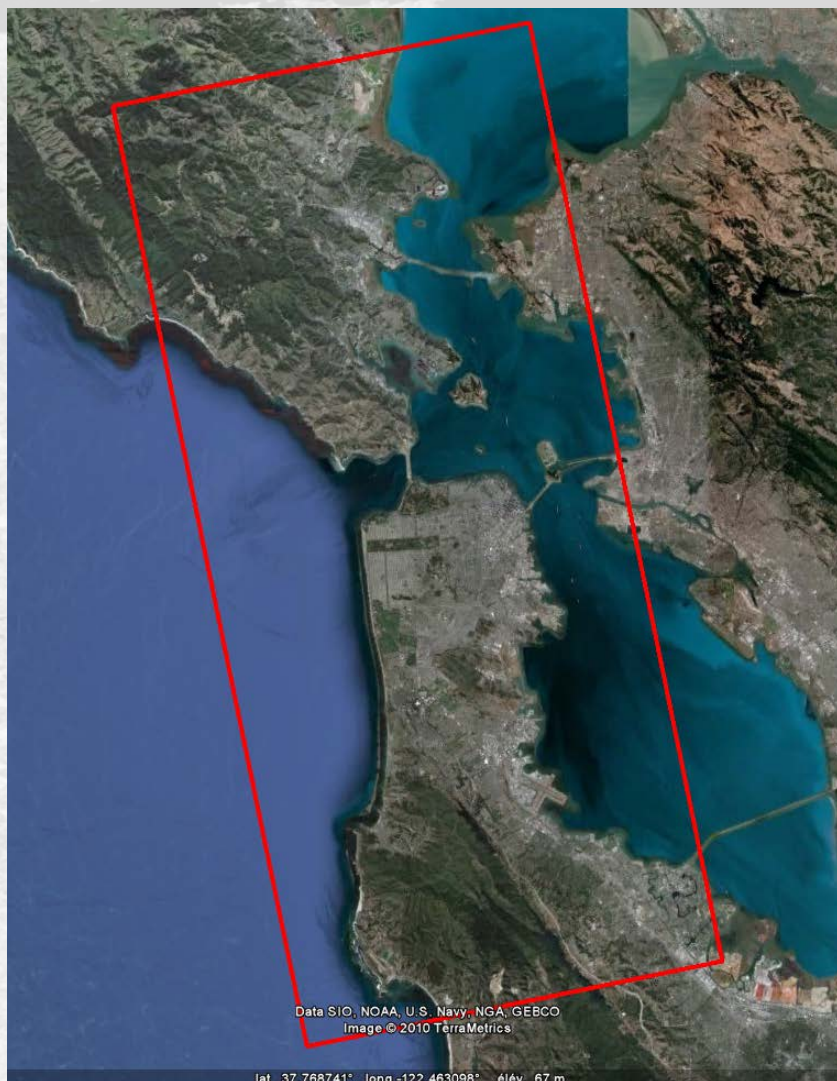


L-Band (Quad)



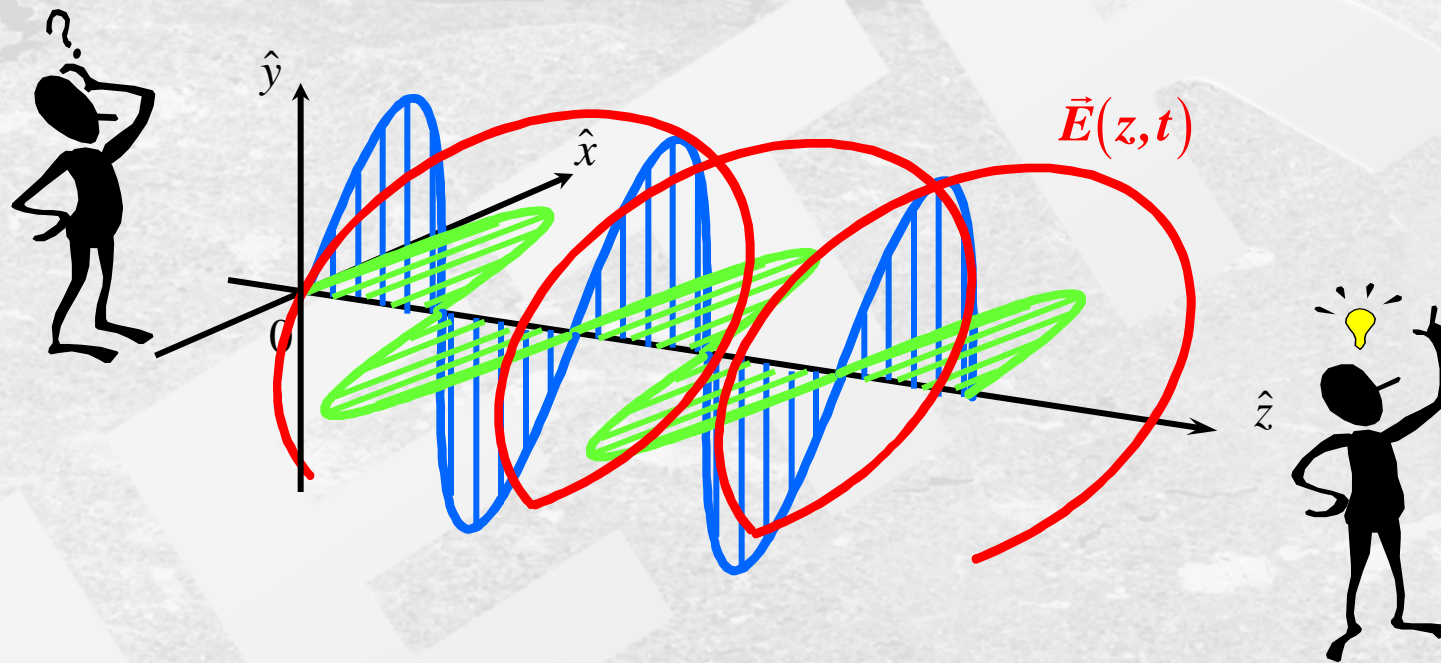
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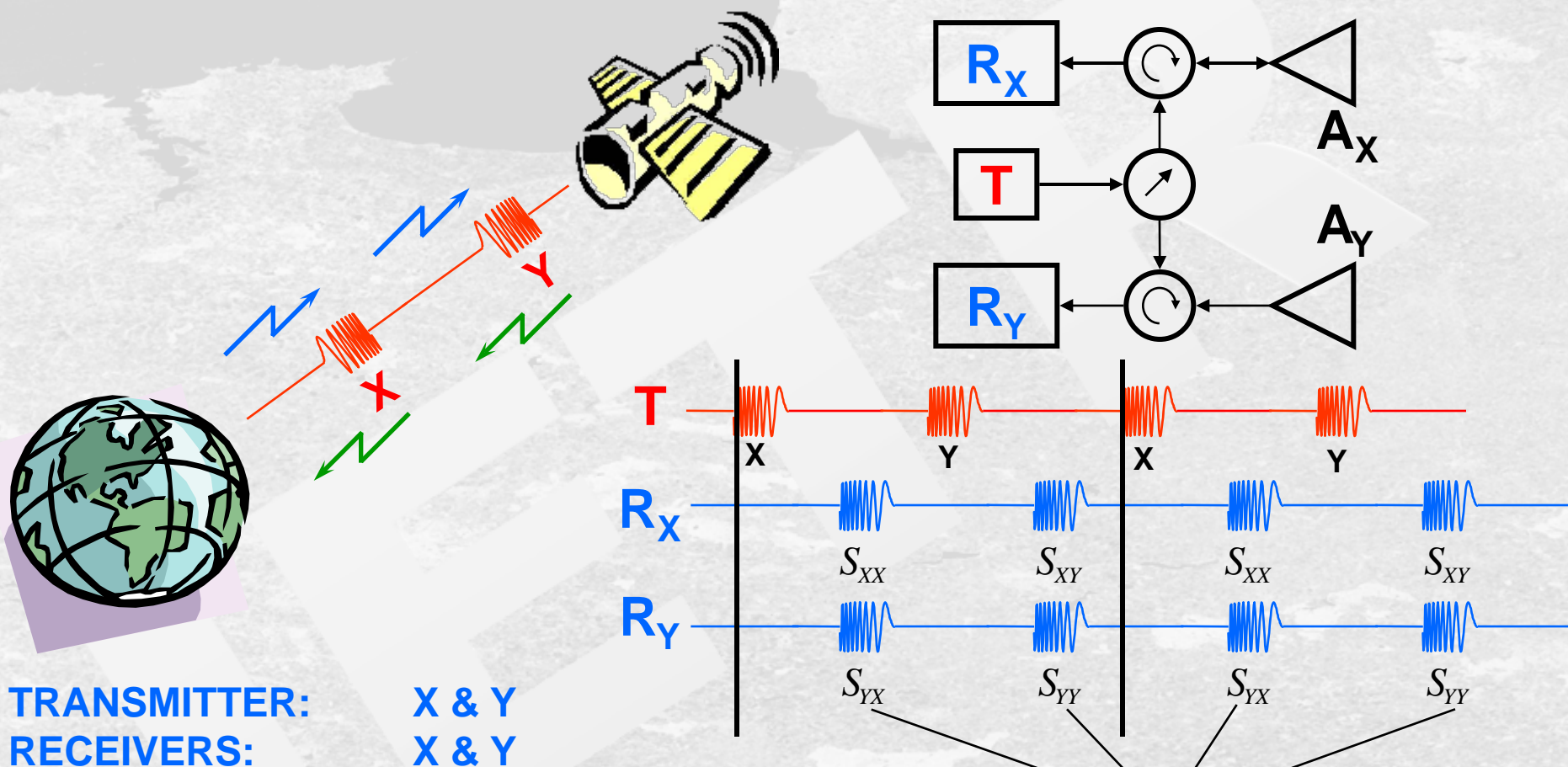


Courtesy of Dr Don Artwood (ASF)





SUMMARY



SINCLAIR MATRICES

$$[S] = \begin{bmatrix} S_{XX} & S_{XY} \\ S_{YX} & S_{YY} \end{bmatrix}$$

SCATTERING POLARIMETRY

Tx → Rx →

Tx → Rx ↑

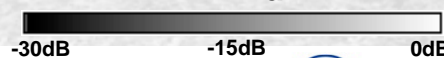
Tx ↑ Rx ↑



$|HH|_{dB}$

$|HV|_{dB}$

$|VV|_{dB}$



Sinclair Color Coding



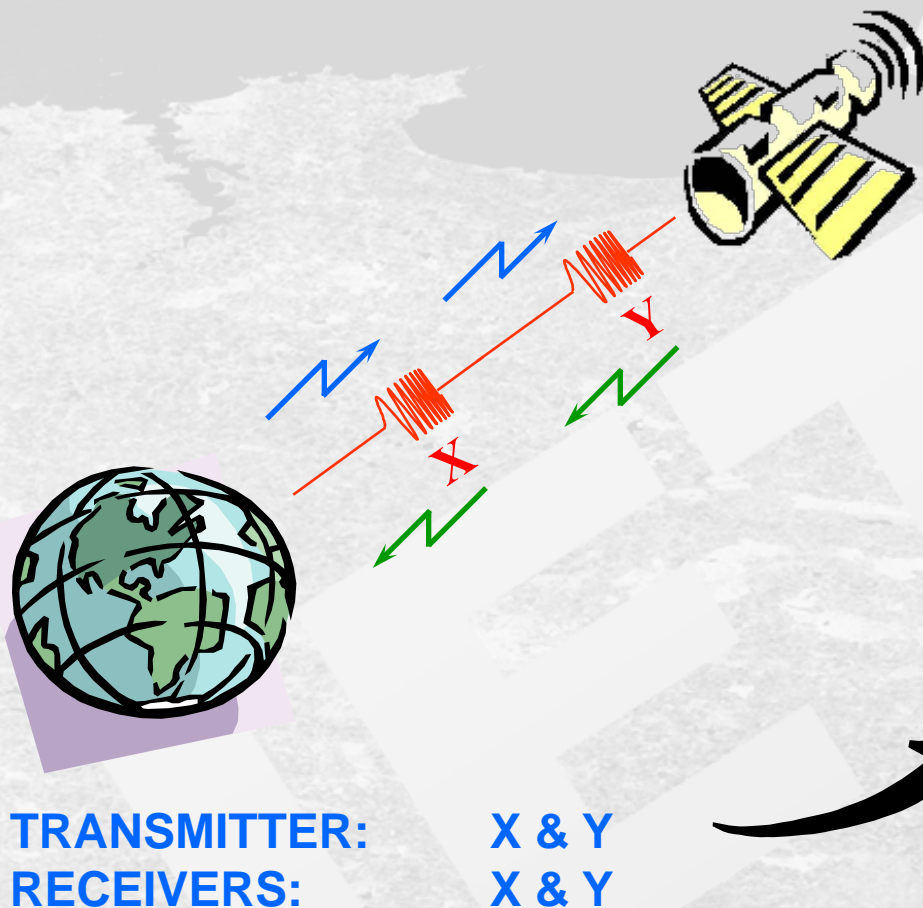
© Google Earth



|HH|

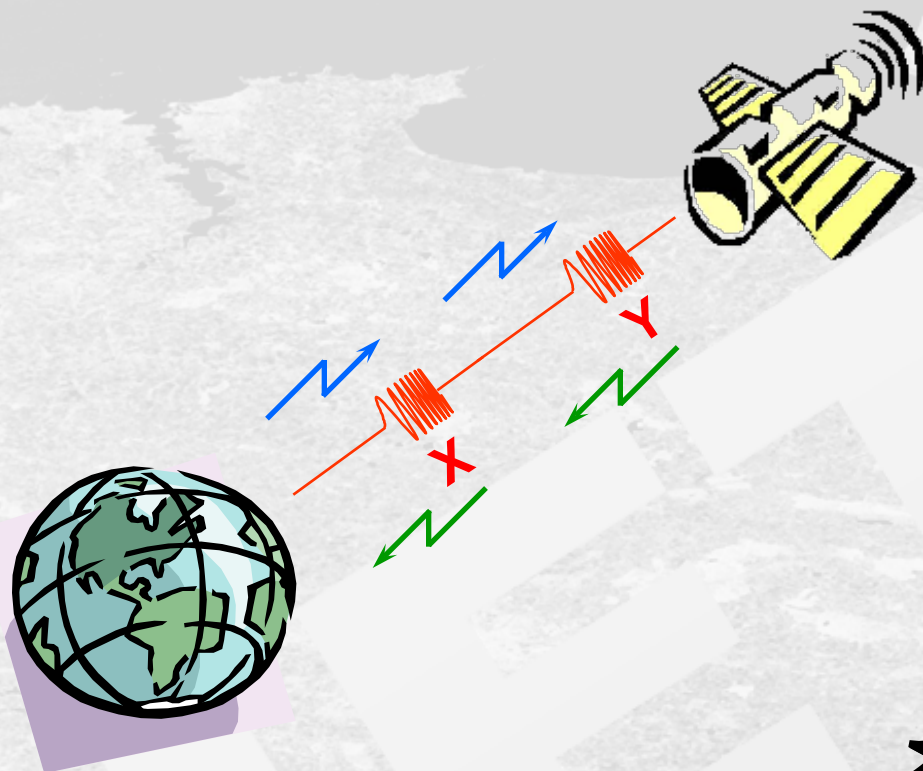
|HV|

|VV|



THE DIFFERENT TARGET POLARIMETRIC DESCRIPTORS

- [S]** SINCLAIR Matrix
- \underline{k} , $\underline{\Omega}$** Target Vectors
- [K]** KENNAUGH Matrix
- [T]** Coherency Matrix
- [C]** Covariance Matrix



TRANSMITTER:
RECEIVERS:

X & Y
X & Y

THE DIFFERENT TARGET POLARIMETRIC DESCRIPTORS

- [S] SINCLAIR Matrix
- [K] KENNAUGH Matrix
- $\underline{k}, \underline{\Omega}$ Target Vectors
- [T] **Coherency Matrix**
- [C] Covariance Matrix

STATISTICAL DESCRIPTION
PARTIAL SCATTERING POLARIMETRY

MONOSTATIC CASE

PAULI SCATTERING VECTOR \underline{k}

$$\underline{k} = \frac{1}{\sqrt{2}} \begin{bmatrix} S_{XX} + S_{YY} & S_{XX} - S_{YY} & 2S_{XY} \end{bmatrix}^T$$



COHERENCY MATRIX $[T]$

$$[T] = \underline{k} \cdot \underline{k}^{*T} = \begin{bmatrix} 2A_0 & C - jD & H + jG \\ C + jD & B_0 + B & E + jF \\ H - jG & E - jF & B_0 - B \end{bmatrix}$$

HERMITIAN POSITIVE SEMI-DEFINITE MATRIX - RANK 1

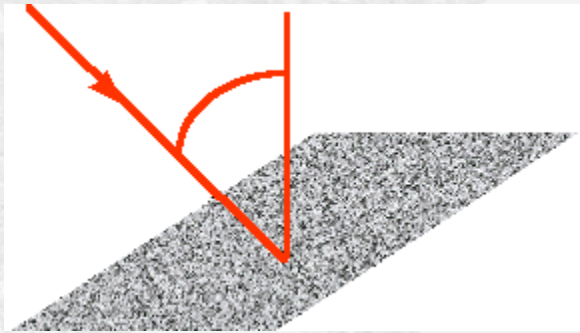
HUYNEN TARGET GENERATORS

$$T_{11} = 2A_0 = |S_{XX} + S_{YY}|^2 \quad T_{22} = B_0 + B = |S_{XX} - S_{YY}|^2$$

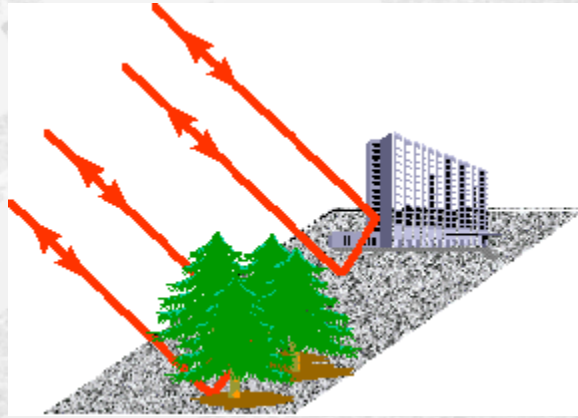
$$T_{33} = B_0 - B = 2|S_{XY}|^2$$

PHYSICAL INTERPRETATION

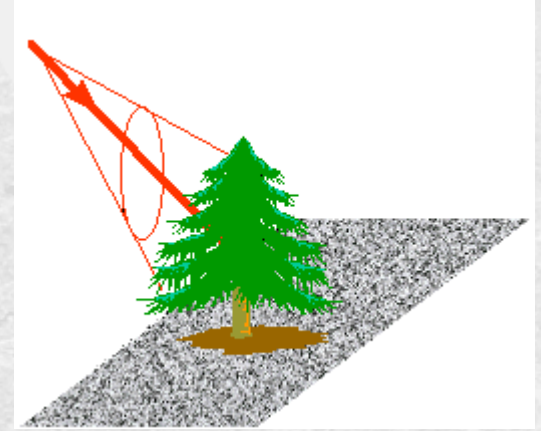
SINGLE BOUNCE SCATTERING (ROUGH SURFACE)



DOUBLE BOUNCE SCATTERING



VOLUME SCATTERING



$$T_{11} = 2A_0 = |S_{XX} + S_{YY}|^2$$

$$T_{33} = B_0 - B = 2|S_{XY}|^2$$

$$T_{22} = B_0 + B = |S_{XX} - S_{YY}|^2$$



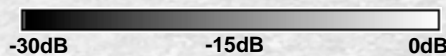
$|HH+VV|_{dB}$



$|HV|_{dB}$



$|HH-VV|_{dB}$



(H,V) POLARISATION BASIS



© Google Earth



|HH+VV|

|HV|

|HH-VV|

SINCLAIR MATRIX

$$[S] = \begin{bmatrix} S_{XX} & S_{XY} \\ S_{YX} & S_{YY} \end{bmatrix}$$



SCATTERING VECTOR \underline{k}

$$\underline{k} = \frac{1}{\sqrt{2}} \begin{bmatrix} S_{XX} + S_{YY} & S_{XX} - S_{YY} & 2S_{XY} \end{bmatrix}^T$$

COHERENCY MATRIX $[T]$

$$[T] = \underline{k} \cdot \underline{k}^{*T}$$

SINCLAIR MATRIX

$$[S_{(B,B_{\perp})}] = [U_{3(A,A_{\perp}) \rightarrow (B,B_{\perp})}]^T [S_{(A,A_{\perp})}] [U_{3(A,A_{\perp}) \rightarrow (B,B_{\perp})}]$$

CON-SIMILARITY TRANSFORMATION

$$[U_{3(A,A_{\perp}) \rightarrow (B,B_{\perp})}]$$

U(3) SPECIAL UNITARY ELLIPTICAL
BASIS TRANSFORMATION MATRIX



COHERENCY MATRIX

$$[T_{(B,B_{\perp})}] = [U_{3(A,A_{\perp}) \rightarrow (B,B_{\perp})}] [T_{(A,A_{\perp})}] [U_{3(A,A_{\perp}) \rightarrow (B,B_{\perp})}]^{-1}$$

SIMILARITY TRANSFORMATION

SPECIAL UNITARY SU(2) GROUP

$$[U_2] = \begin{bmatrix} \cos(\phi) & -\sin(\phi) \\ \sin(\phi) & \cos(\phi) \end{bmatrix} \begin{bmatrix} \cos(\tau) & j \sin(\tau) \\ j \sin(\tau) & \cos(\tau) \end{bmatrix} \begin{bmatrix} e^{-j\alpha} & 0 \\ 0 & e^{j\alpha} \end{bmatrix}$$

$$\begin{matrix} [U_2(\phi)] & [U_2(\tau)] & [U_2(\alpha)] \end{matrix}$$



SPECIAL UNITARY SU(3) GROUP

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos(2\phi) & \sin(2\phi) \\ 0 & -\sin(2\phi) & \cos(2\phi) \end{bmatrix} \begin{bmatrix} \cos(2\tau) & 0 & j \sin(2\tau) \\ 0 & 1 & 0 \\ j \sin(2\tau) & 0 & \cos(2\tau) \end{bmatrix} \begin{bmatrix} \cos(2\alpha) & -j \sin(2\alpha) & 0 \\ -j \sin(2\alpha) & \cos(2\alpha) & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{matrix} [U_3(2\phi)] & [U_3(2\tau)] & [U_3(2\alpha)] \end{matrix}$$

(H,V) POLARISATION BASIS



© Google Earth



|HH+VV|

|HV|

|HH-VV|

(+45°,-45°) POLARISATION BASIS



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|AA+BB| **|AB|** **|AA-BB|**

With: A=Linear +45° B=Linear -45°

(LC,RC) POLARISATION BASIS



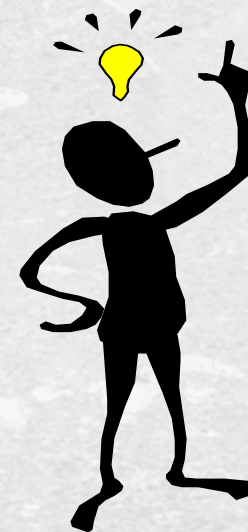
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$|LL+RR|$

$|LR|$

$|LL-RR|$



POLARIMETRIC GOLDEN NUMBER

POLARIMETRIC TARGET DIMENSION



$$[S] = \begin{bmatrix} S_{XX} & S_{XY} \\ S_{YX} & S_{YY} \end{bmatrix}$$

5 DEGREES OF FREEDOM

$$|S_{XX}|, |S_{XY}|, |S_{YY}|$$

$$\phi_{XY-XX}, \phi_{YY-XX}$$

COHERENCY MATRIX [T]

9 HUYNEN REAL PARAMETERS
(A0, B0, B, C, D, E, F, G, H)

TARGET MONOSTATIC
POLARIMETRIC « DIMENSION »

||
5

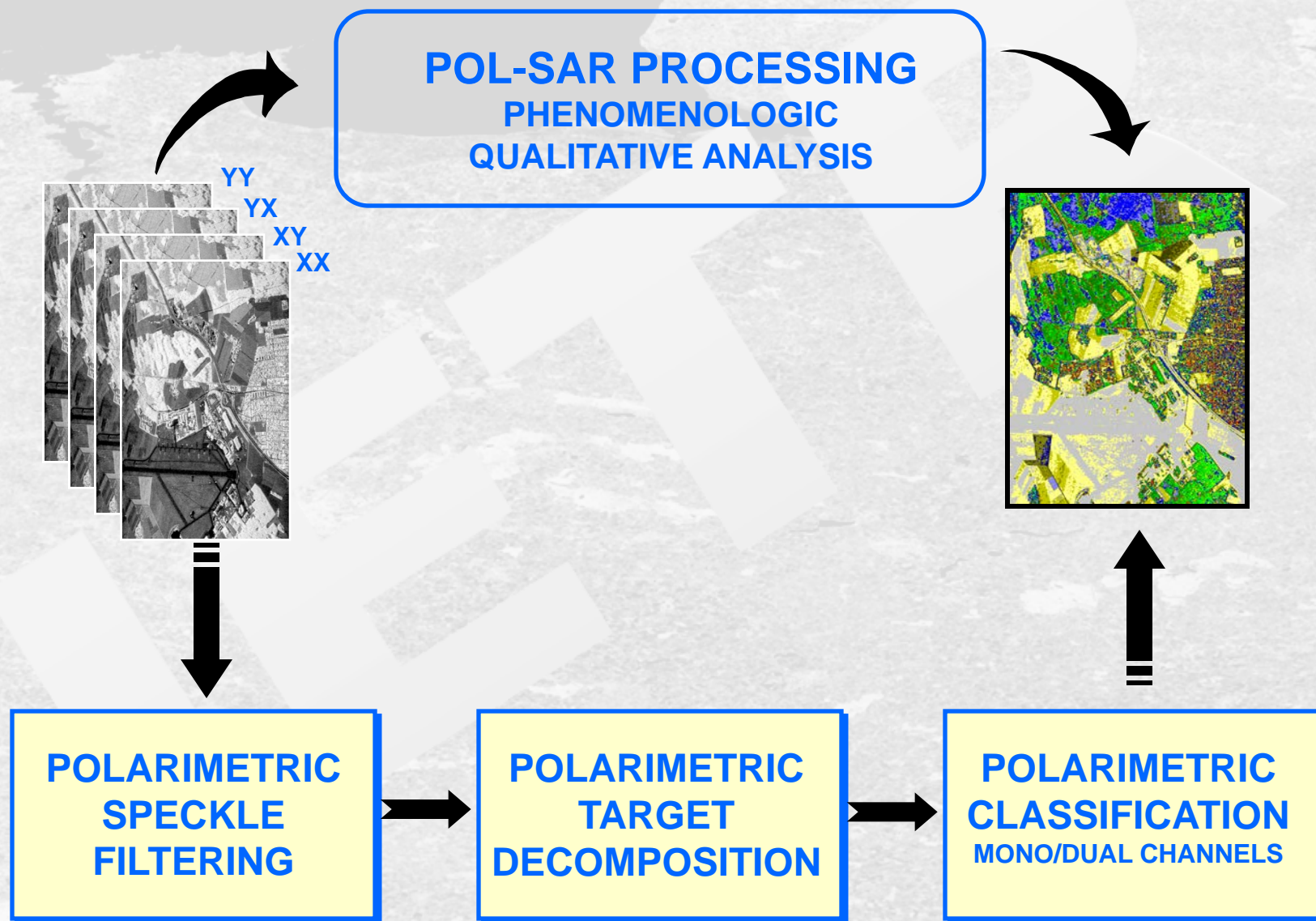
9 - 5 = 4 TARGET EQUATIONS

$$2A_0(B_0 + B) = C^2 + D^2$$

$$2A_0(B_0 - B) = G^2 + H^2$$

$$2A_0E = CH - DG$$

$$2A_0F = CG + DH$$



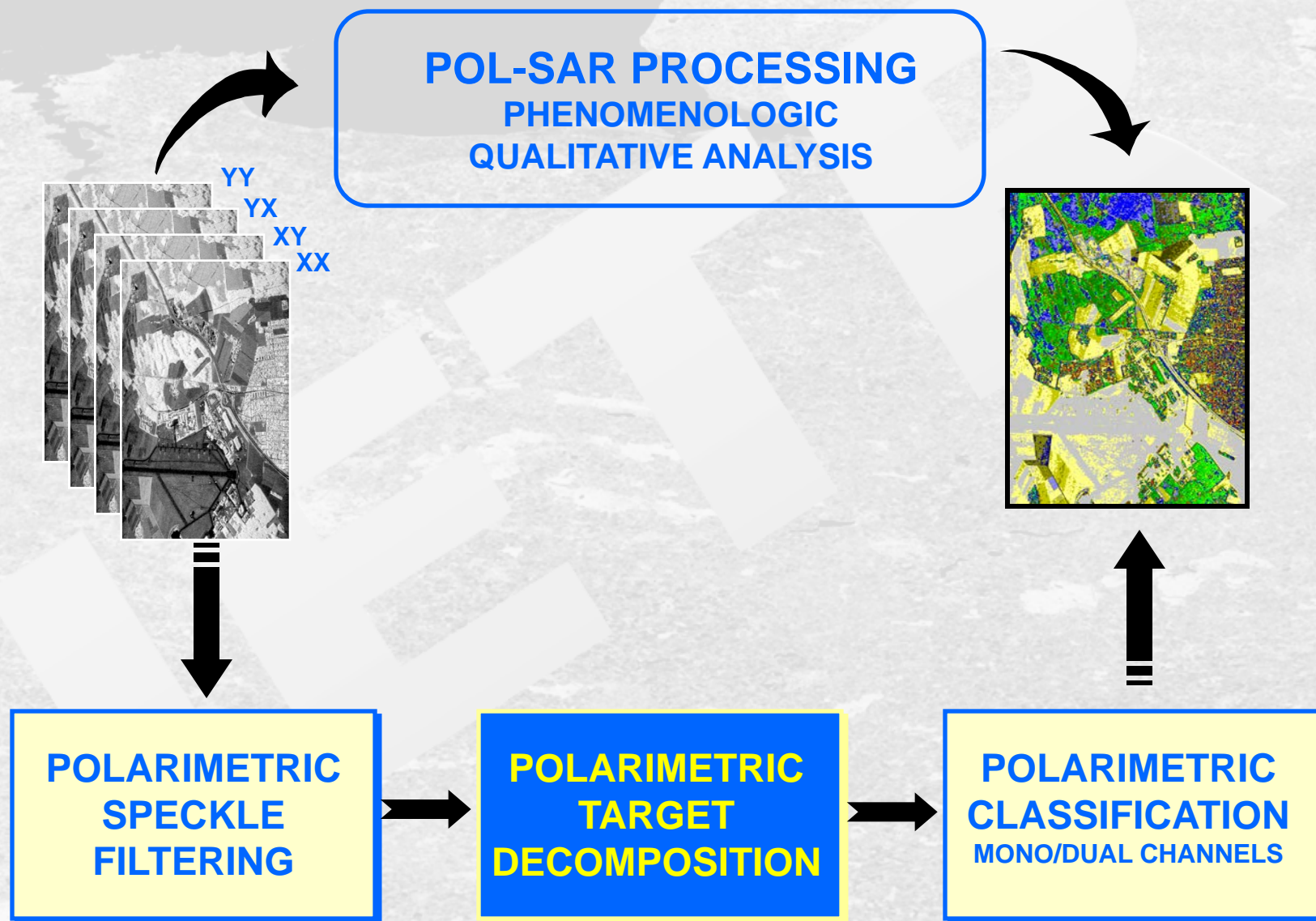
POLARIMETRIC SPECKLE FILTERING IS NOT AN EXACT SCIENCE SUBJECTIVE, IMAGE DEPENDENT

Quantitative Criteria (J.S. Lee - IGARSS 98)

- Speckle Reduction (E.N.L)
- Edge Sharpness Preservation
- Line and Point Target Contrast Preservation
- Retention of Mean Values in Homogeneous Regions
- Retention of Texture Information
- Retention of Polarimetric Information (co, cross-correlations)
- Computational Efficiency
- Implementation Complexity

$$[\hat{T}] = E([T]) - k[E([T]) - [T]]$$

THE POLARIMETRIC SPECKLE LEE FILTER
IS TODAY A GOOD COMPROMISE





$$[T] = \underline{k} \underline{k}^{*T}$$



AVERAGING DATA



SECOND ORDER STATISTICS

COHERENCY MATRICES

$$\langle [T] \rangle = \frac{1}{N} \sum_{i=1}^N \underline{k}_i \underline{k}_i^{*T}$$

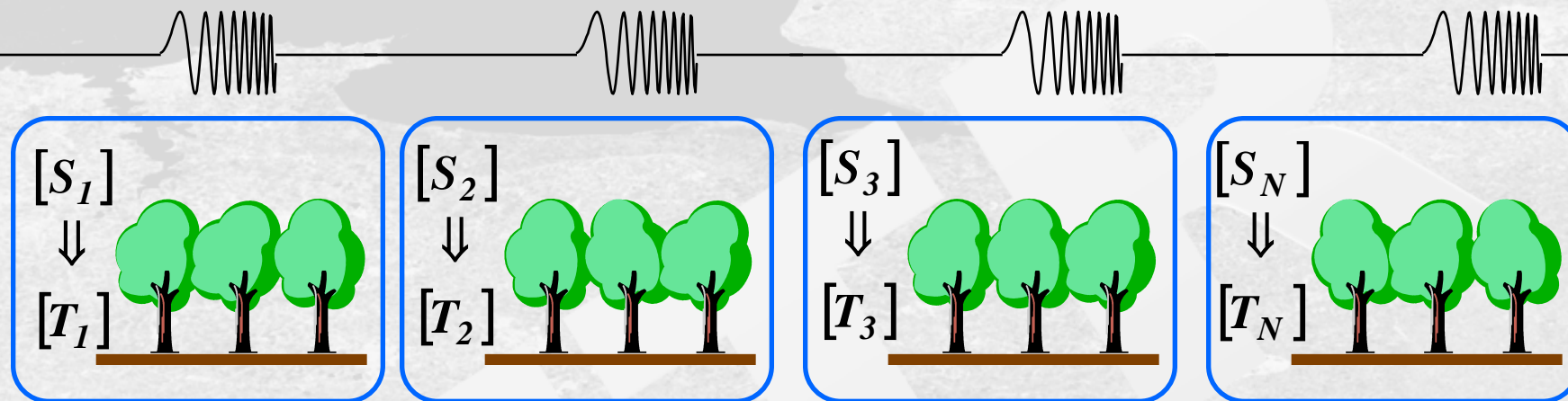


SMOOTHING AVERAGING



CONCEPT OF THE DISTRIBUTED TARGET

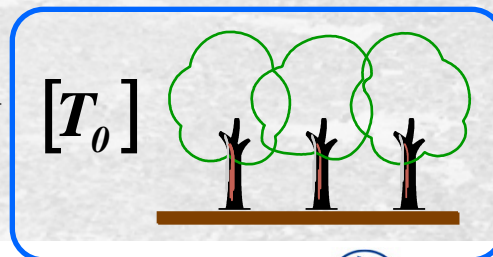
TARGET DECOMPOSITION



$$\langle [T] \rangle = \frac{1}{N} \sum_{i=1}^{i=N} [T_i]$$

**DISTRIBUTED
TARGET
or
AVERAGED
TARGET**

**DECOMPOSITION
THEOREM**



MEAN TARGET



[S]

[T]

[C]

COHERENT DECOMPOSITION

E. KROGAGER (1990)

W.L. CAMERON (1990)

[K]

TARGET DICHOTOMY

J.R. HUYNEN (1970)

R.M. BARNES (1988)

EIGENVECTORS BASED DECOMPOSITION

S.R. CLOUDE (1985)

W.A. HOLM (1988)

EIGENVECTORS / EIGENVALUES ANALYSIS & MODEL BASED DECOMPOSITION

J.J. VAN ZYL (1992-2008), M. ARII (2010)
TSVM (R. TOUZI – 2007)

EIGENVECTORS / EIGENVALUES ANALYSIS ENTROPY / ANISOTROPY

S.R. CLOUDE - E. POTTIER (1996-1997)

AZIMUTHAL SYMMETRY

MODEL BASED DECOMPOSITION

A.J. FREEMAN – S.L. DURDEN (1992)
Y. YAMAGUSHI (2005 - 2012), AN (2010)

[S]

[T]

[C]

COHERENT DECOMPOSITION

E. KROGAGER (1990)

W.L. CAMERON (1990)

[K]

TARGET DICHOTOMY

J.R. HUYNEN (1970)

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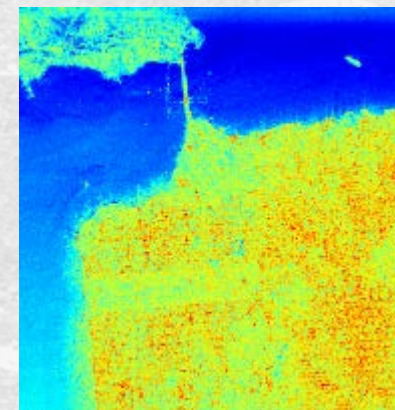
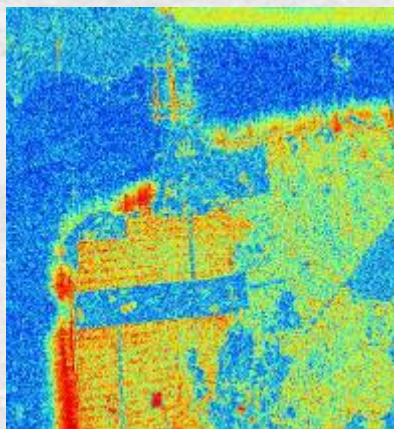
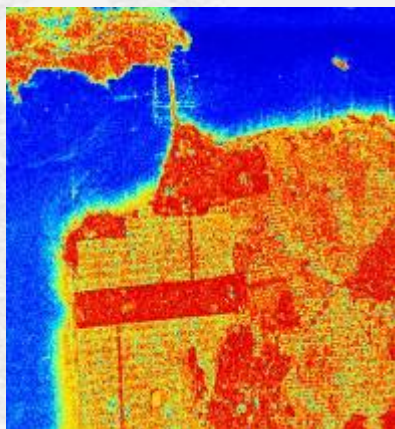
S.R. CLOUDE - E. POTTIER (1996-1997)

AZIMUTHAL SYMMETRY

MODEL BASED DECOMPOSITION

A.J. FREEMAN – S.L. DURDEN (1992)
Y. YAMAGUSHI (2005 - 2012), AN (2010)

THE $H/A/\alpha$ POLARIMETRIC TARGET DECOMPOSITION THEOREM



S.R. CLOUDE - E. POTTIER (1995 - 1996)

TARGET VECTOR $\underline{k} = \frac{1}{\sqrt{2}} \begin{bmatrix} S_{XX} + S_{YY} & S_{XX} - S_{YY} & 2S_{XY} \end{bmatrix}^T$

LOCAL ESTIMATE OF THE COHERENCY MATRIX $\langle [T] \rangle = \frac{1}{N} \sum_{i=1}^N \underline{k}_i \cdot \underline{k}_i^{*T} = \frac{1}{N} \sum_{i=1}^N [T_i]$


EIGENVECTORS / EIGENVALUES ANALYSIS

$$\langle [T] \rangle = [U_3][\Sigma][U_3]^{-1} = \begin{bmatrix} \underline{u}_1 & \underline{u}_2 & \underline{u}_3 \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} \begin{bmatrix} \underline{u}_1 & \underline{u}_2 & \underline{u}_3 \end{bmatrix}^{*T}$$

ORTHOGONAL EIGENVECTORS

REAL EIGENVALUES

$$\lambda_1 > \lambda_2 > \lambda_3$$



$$P_i = \frac{\lambda_i}{\sum_{k=1}^3 \lambda_k}$$

$$\langle [T] \rangle = [U_3][\Sigma][U_3]^{-1} = \begin{bmatrix} \underline{u}_1 & \underline{u}_2 & \underline{u}_3 \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} \begin{bmatrix} \underline{u}_1 & \underline{u}_2 & \underline{u}_3 \end{bmatrix}^{*T}$$

ORTHOGONAL
EIGENVECTORS

REAL EIGENVALUES

$$\lambda_1 > \lambda_2 > \lambda_3$$



PARAMETERISATION OF THE SU(3) UNITARY MATRIX

$$[U_3] = \begin{bmatrix} \cos \alpha_1 e^{j\phi_1} & & \\ \sin \alpha_1 \cos \beta_1 e^{j\phi_1} e^{j\delta_1} & \cos \alpha_2 e^{j\phi_2} & \\ \sin \alpha_1 \sin \beta_1 e^{j\phi_1} e^{j\gamma_1} & \sin \alpha_2 \cos \beta_2 e^{j\phi_2} e^{j\delta_2} & \cos \alpha_3 e^{j\phi_3} \\ & \sin \alpha_2 \sin \beta_2 e^{j\phi_2} e^{j\gamma_2} & \sin \alpha_3 \cos \beta_3 e^{j\phi_3} e^{j\delta_3} \\ & & \sin \alpha_3 \sin \beta_3 e^{j\phi_3} e^{j\gamma_3} \end{bmatrix}$$

TARGET 1

TARGET 2

TARGET 3

PROBABILITIES

$$P_i = \frac{\lambda_i}{\sum_{k=1}^3 \lambda_k}$$



AVERAGED PARAMETERS

$$\begin{aligned} \underline{\alpha} &= P_1 \alpha_1 + P_2 \alpha_2 + P_3 \alpha_3 & \underline{\beta} &= P_1 \beta_1 + P_2 \beta_2 + P_3 \beta_3 \\ \underline{\gamma} &= P_1 \gamma_1 + P_2 \gamma_2 + P_3 \gamma_3 & \underline{\delta} &= P_1 \delta_1 + P_2 \delta_2 + P_3 \delta_3 \end{aligned}$$

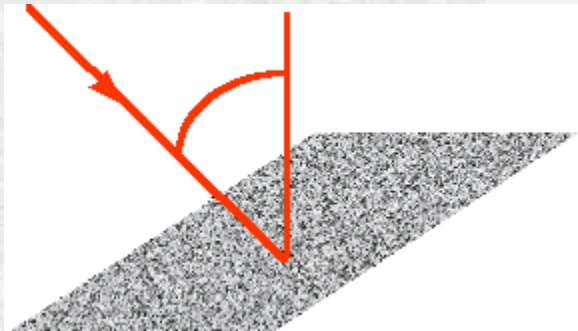


UNITARY TARGET VECTOR (\underline{u}_0) OF THE MEAN DOMINANT MECHANISM

$$\underline{u}_0 = \left[\cos(\underline{\alpha}) \quad \sin(\underline{\alpha}) \cos(\underline{\beta}) e^{j\underline{\delta}} \quad \sin(\underline{\alpha}) \sin(\underline{\beta}) e^{j\underline{\gamma}} \right]^T$$

α PHYSICAL INTERPRETATION

SINGLE BOUNCE SCATTERING (ROUGH SURFACE)

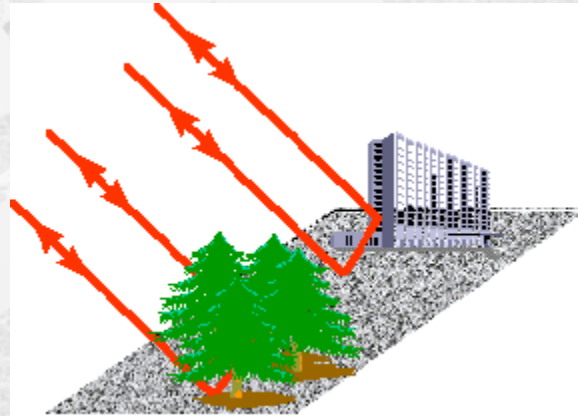


$$a \mapsto b \Rightarrow v \mapsto 0$$

$$\Downarrow$$

$$\underline{\alpha} \mapsto 0$$

DOUBLE BOUNCE SCATTERING

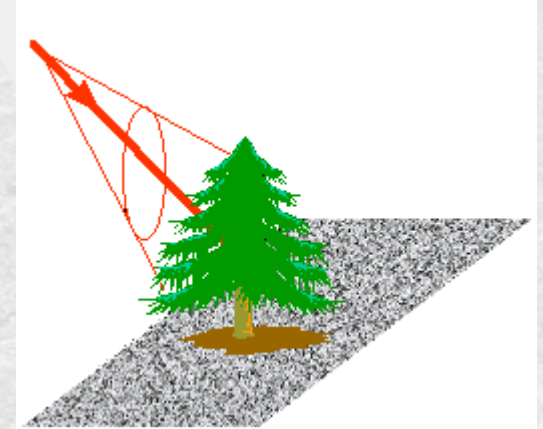


$$a \mapsto -b \Rightarrow \varepsilon \mapsto 0$$

$$\Downarrow$$

$$\underline{\alpha} \mapsto \frac{\pi}{2}$$

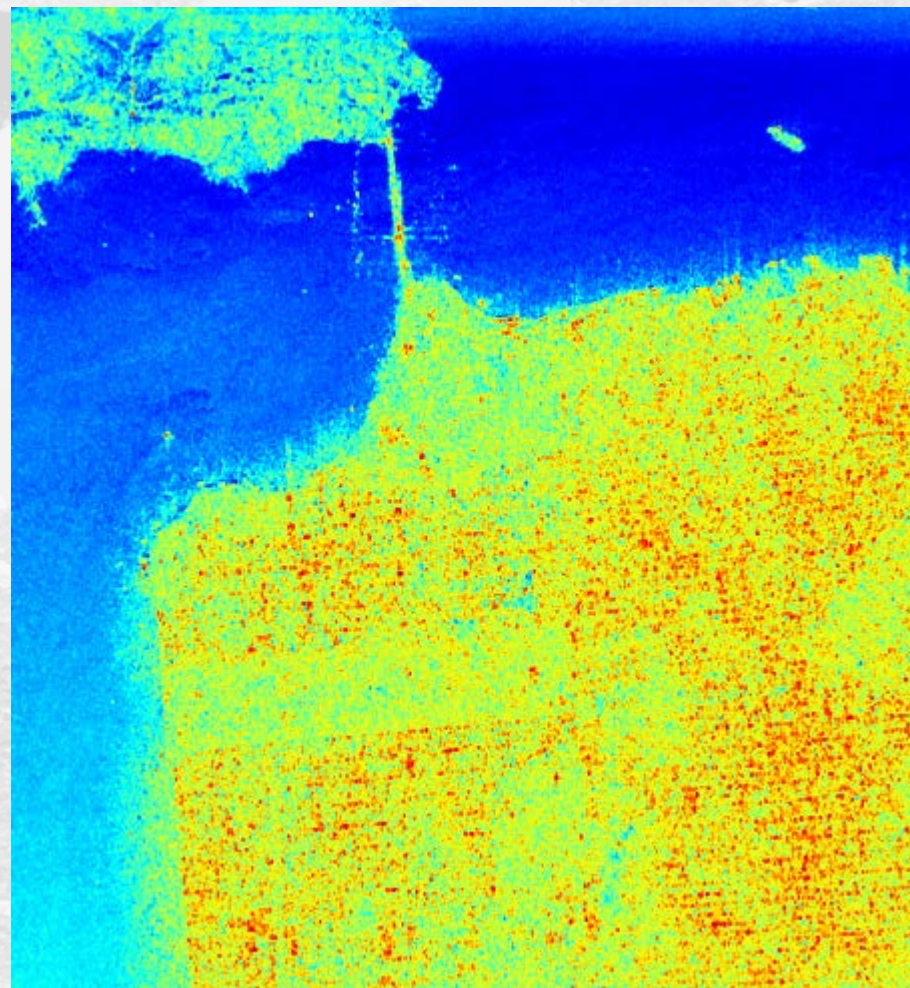
VOLUME SCATTERING



$$a \gg b \Rightarrow \varepsilon \approx v$$

$$\Downarrow$$

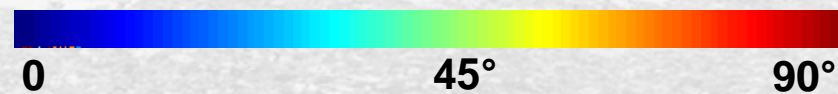
$$\underline{\alpha} \mapsto \frac{\pi}{4}$$



$2A_0$

$B_0 + B$

$B_0 - B$



EIGENVALUES $\lambda_1 \lambda_2 \lambda_3$: ROLL INVARIANT
PROBABILITIES $P_1 P_2 P_3$: ROLL INVARIANT



ENTROPY

(DEGREE OF RANDOMNESS
STATISTICAL DISORDER)

$$H = - \sum_{i=1}^3 P_i \log_3(P_i)$$



PURE TARGET

$$\lambda_1 = \text{SPAN} \quad \lambda_2 = 0 \quad \lambda_3 = 0$$

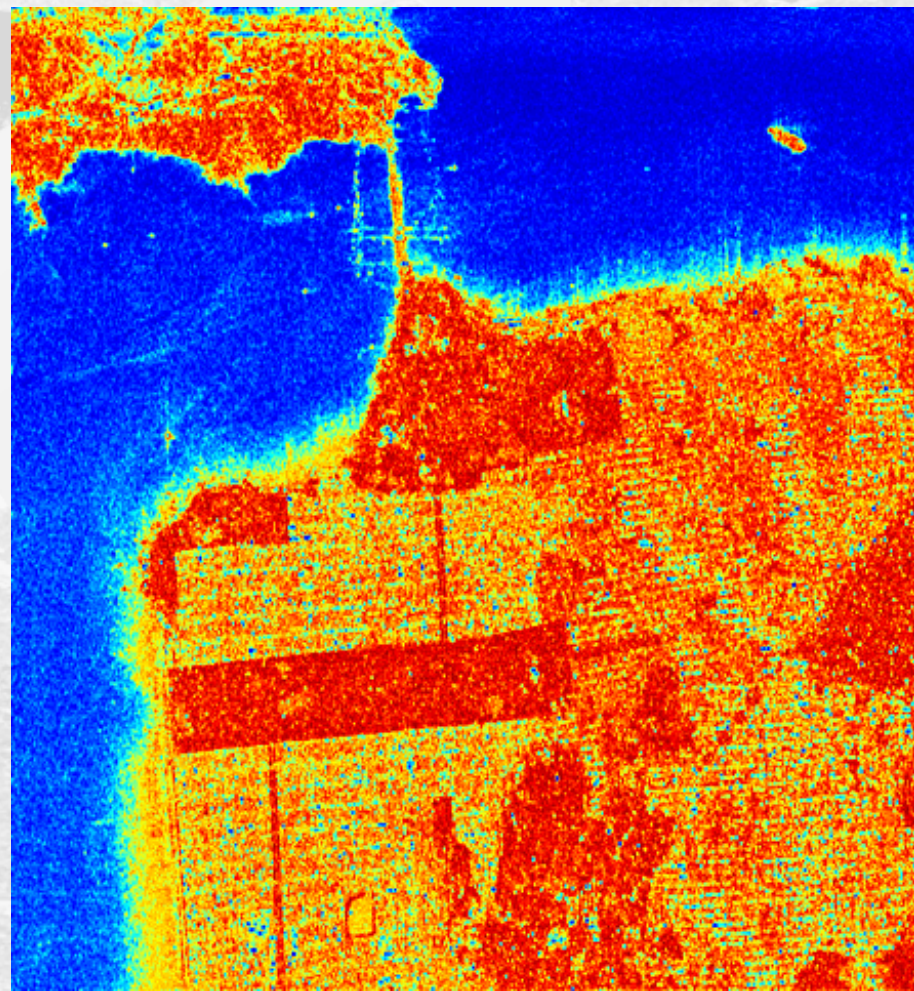
$$H = 0$$



DISTRIBUTED TARGET

$$\lambda_1 = \lambda_2 = \lambda_3 = \text{SPAN} / 3$$

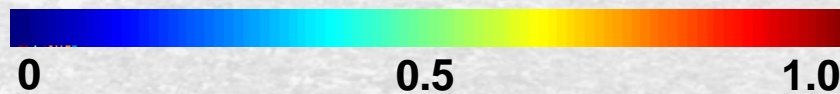
$$H = 1$$



$2A_0$

$B_0 + B$

$B_0 - B$



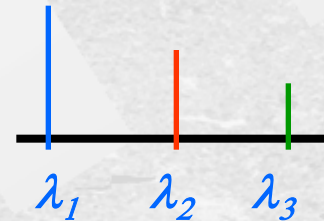
ENTROPY (H)

DIFFICULT MECHANISM DISCRIMINATION WHEN : $H > 0.7$



ANISOTROPY
(EIGENVALUES SPECTRUM)

$$A = \frac{\lambda_2 - \lambda_3}{\lambda_2 + \lambda_3}$$



COMPLEMENTARY TO ENTROPY



DISCRIMINATION WHEN $H > 0.7$



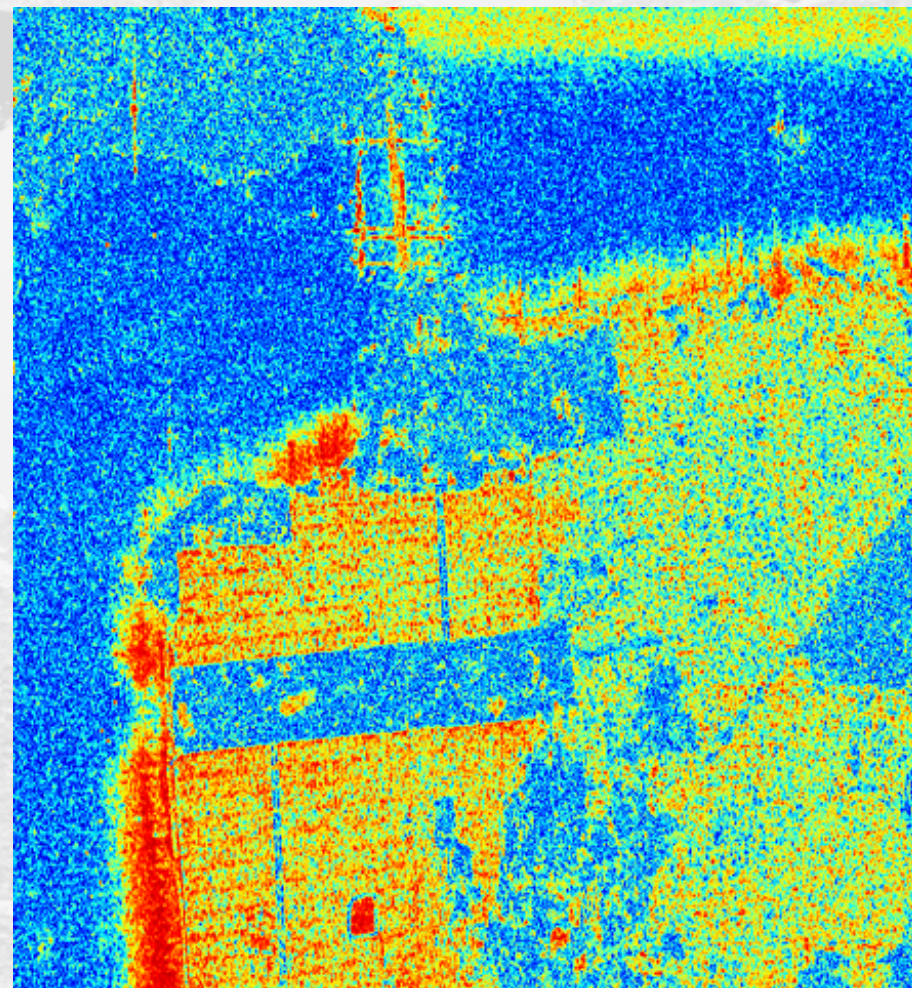
ROLL INVARIANT



$2A_0$

$B_0 + B$

$B_0 - B$

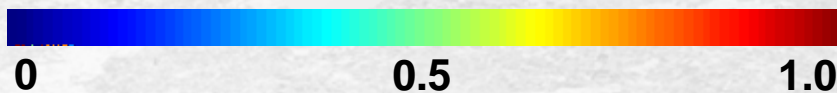
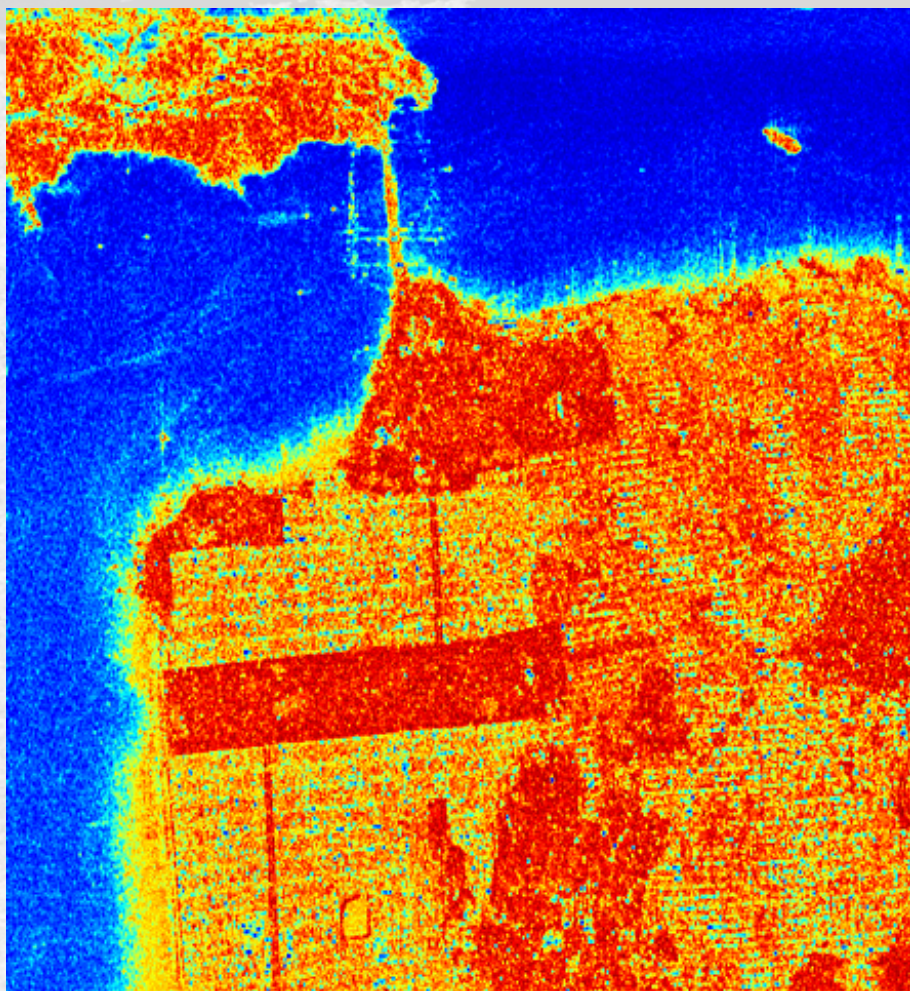


0

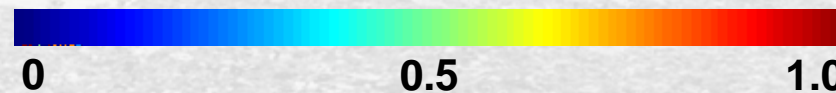
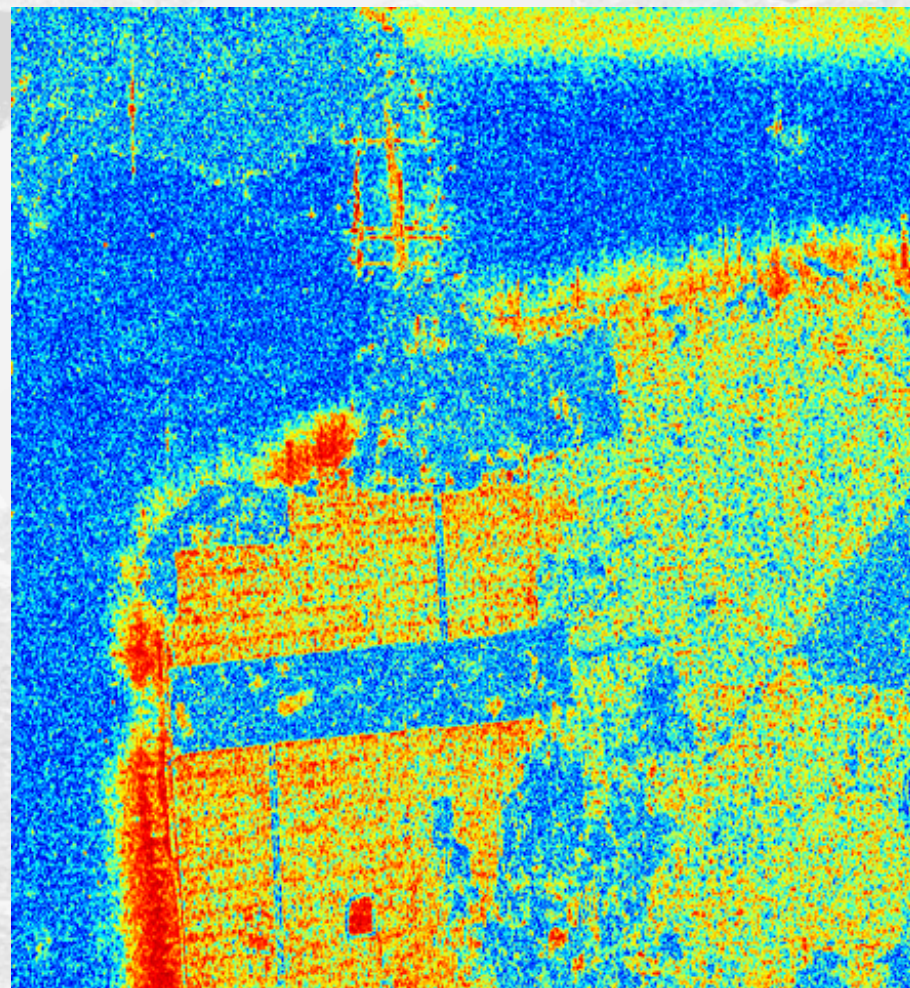
0.5

1.0

ANISOTROPY (A)

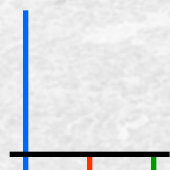


ENTROPY (H)

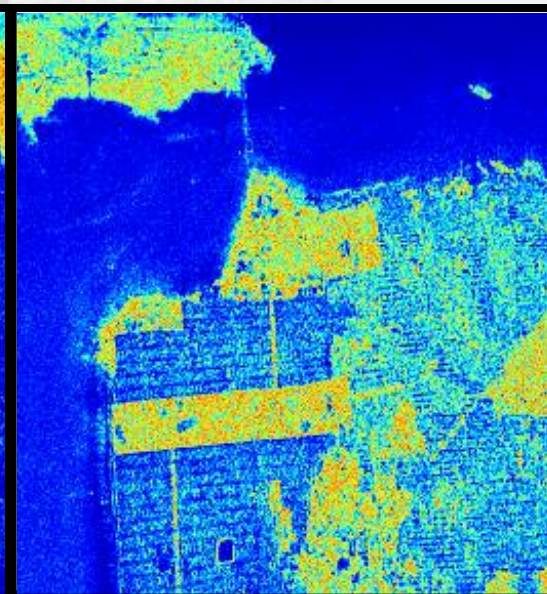
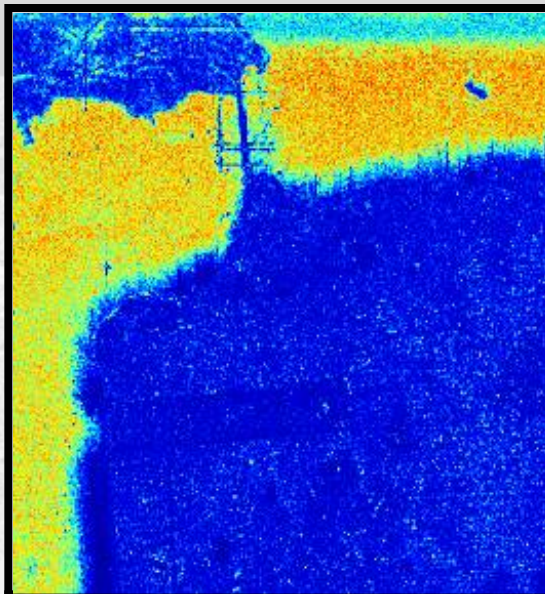


ANISOTROPY (A)

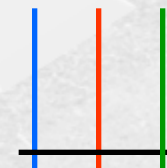
$(1-H)(1-A)$



1 MECHANISM

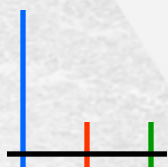


H(1-A)

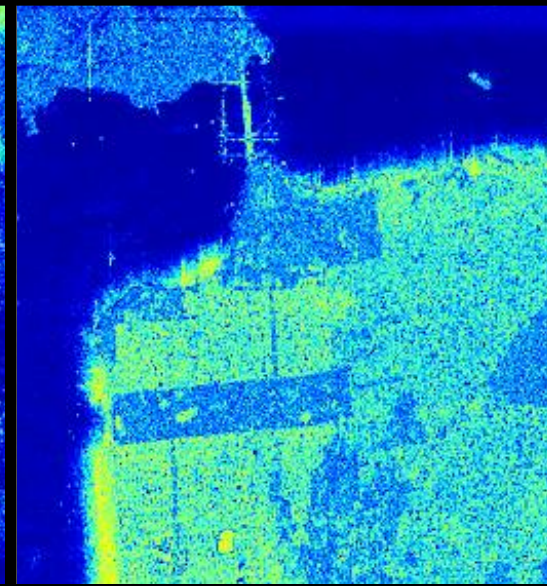
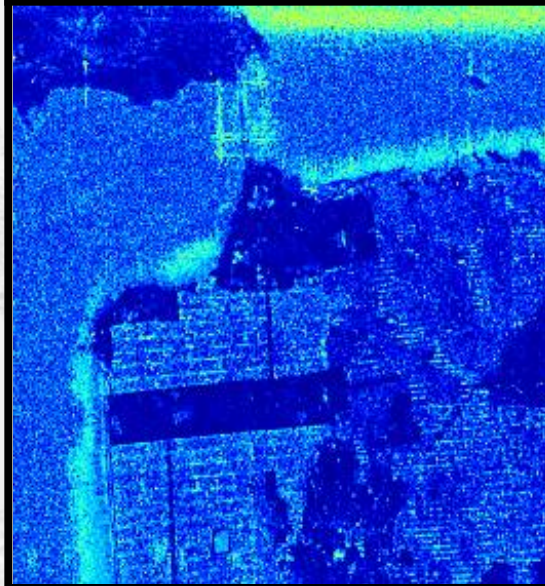


3 MECHANISMS

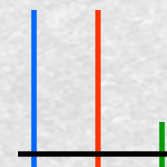
A(1-H)



2 MECHANISMS



HA



2 MECHANISMS



S. Allain

S.E.R.D and D.E.R.D PARAMETERS

(Single- and Double-bounce Eigenvalue Relative Difference)

$$SERD = \frac{\lambda_S - \lambda_{3_{NOS}}}{\lambda_S + \lambda_{3_{NOS}}}$$

$$DERD = \frac{\lambda_D - \lambda_{3_{NOS}}}{\lambda_D + \lambda_{3_{NOS}}}$$



T. Ainsworth

POLARIZATION FRACTION

$$PF = 1 - \frac{3\lambda_3}{Span} = 1 - \frac{3\lambda_3}{\lambda_1 + \lambda_2 + \lambda_3} \quad 0 \leq PF \leq 1$$

POLARIZATION ASYMMETRY

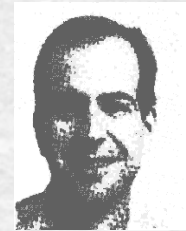
$$PA = \frac{(\lambda_1 - \lambda_3) - (\lambda_2 - \lambda_3)}{(\lambda_1 - \lambda_3) + (\lambda_2 - \lambda_3)} = \frac{\lambda_1 - \lambda_2}{Span - 3\lambda_3} \quad 0 \leq PA \leq 1$$



J. Van Zyl

RADAR VEGETATION INDEX

$$RVI = \frac{4\lambda_3}{\lambda_1 + \lambda_2 + \lambda_3} \quad 0 \leq RVI \leq \frac{4}{3}$$



S.L. Durden

PEDESTAL HEIGHT

$$PH = \frac{\min(\lambda_1, \lambda_2, \lambda_3)}{\max(\lambda_1, \lambda_2, \lambda_3)} = \frac{\lambda_3}{\lambda_1} \quad 0 \leq PH \leq 1$$



E. Luneburg

TARGET RANDOMNESS

$$p_R = \sqrt{\frac{3}{2}} \sqrt{\frac{\lambda_2^2 + \lambda_3^2}{\lambda_1^2 + \lambda_2^2 + \lambda_3^2}} \quad 0 \leq p_R \leq 1$$

ALTERNATIVE ENTROPY PARAMETERS DERIVATION

Normalized Coherency Matrix

$$\mathbf{N}_3 = \langle \underline{\mathbf{k}}^{T*} \cdot \underline{\mathbf{k}} \rangle^{-1} \langle \underline{\mathbf{k}} \cdot \underline{\mathbf{k}}^{T*} \rangle = \frac{\mathbf{T}_3}{\text{Tr}(\mathbf{T}_3)}$$

$$H \approx 2.52 + 0.78 \log_3(|\mathbf{N}_3 + 0.16\mathbf{I}_{D3}|)$$

ENTROPY

SHANNON POLARIMETRIC ENTROPY (2006)

$$SE = \log(\pi^3 e^3 |\mathbf{T}_3|) = SE_I + SE_P$$

$$SE_I = 3 \log\left(\frac{\pi e I_T}{3}\right) = 3 \log\left(\frac{\pi e \text{Tr}(\mathbf{T}_3)}{3}\right)$$

INTENSITY

$$SE_P = \log(1 - p_T^2) = \log\left(27 \frac{|\mathbf{T}_3|}{\text{Tr}(\mathbf{T}_3)^3}\right)$$

DEGREE OF POLARIZATION



J. Praks



E. Colin



J. Morio



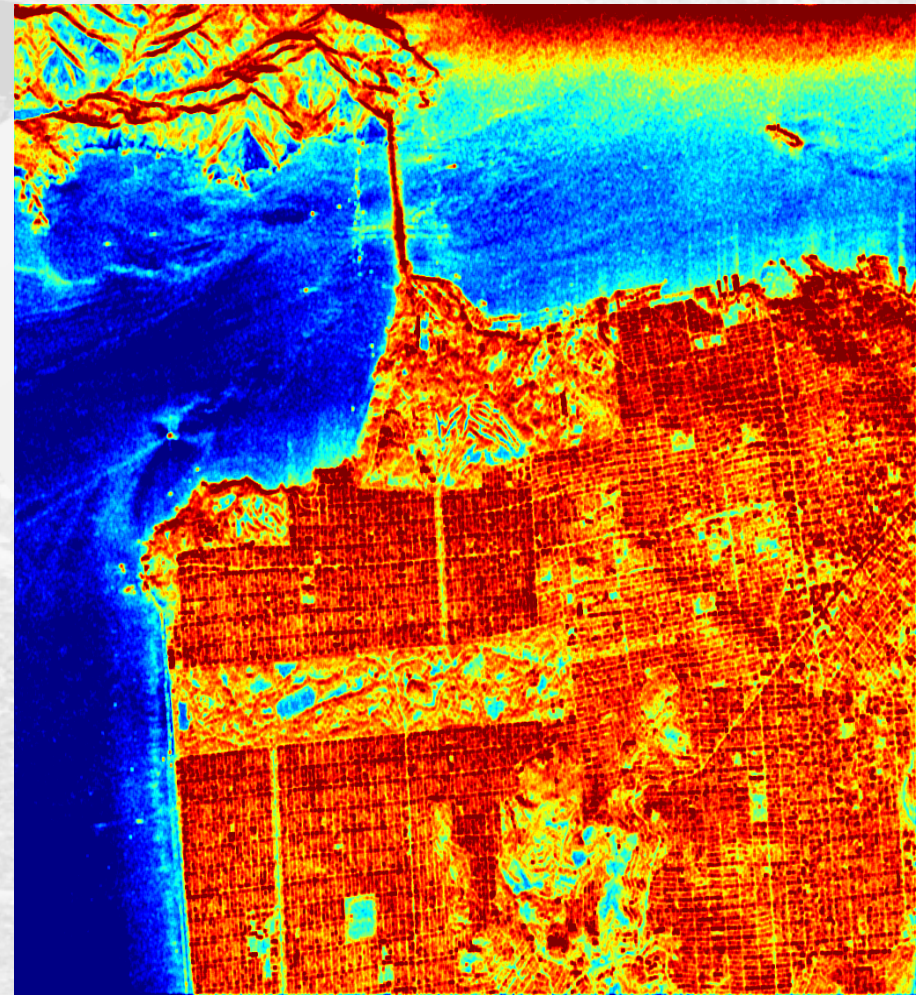
P. Refregier



$2A_0$

$B_0 + B$

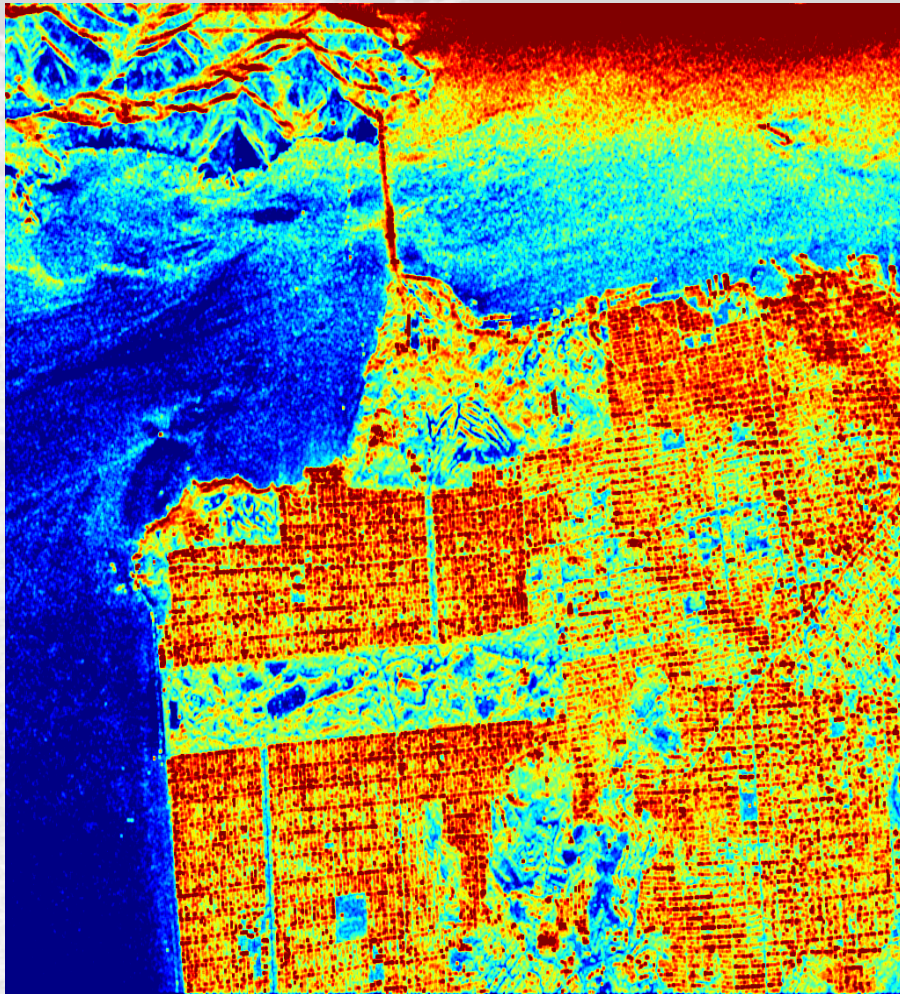
$B_0 - B$



-13.0

1.0

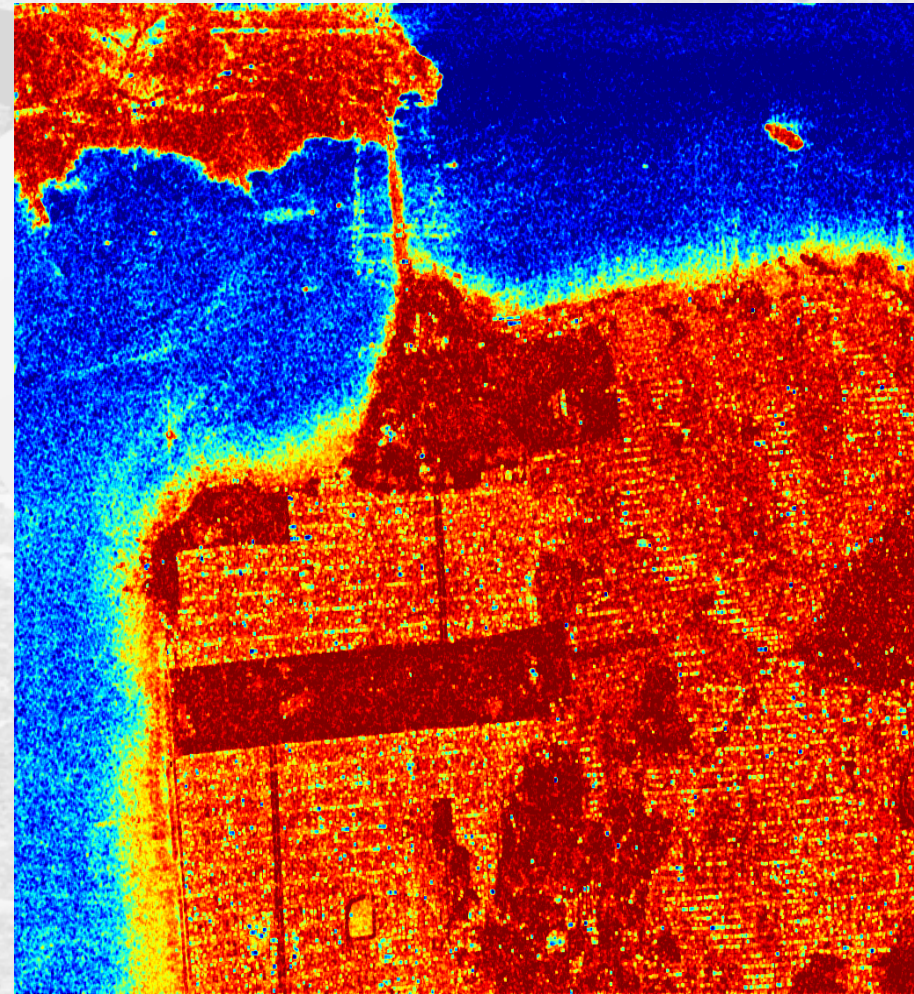
SHANNON ENTROPY (SE-norm)



-9.0

3.0

SHANNON ENTROPY (SE-I)



-6.0

0.0

SHANNON ENTROPY (SE-P)

[S]

[T]

[C]

COHERENT DECOMPOSITION

E. KROGAGER (1990)

W.L. CAMERON (1990)

[K]

TARGET DICHOTOMY

J.R. HUYNEN (1970)

R.M. BARNES (1988)

EIGENVECTORS BASED DECOMPOSITION

S.R. CLOUDE (1985)

W.A. HOLM (1988)

EIGENVECTORS / EIGENVALUES ANALYSIS & MODEL BASED DECOMPOSITION

J.J. VAN ZYL (1992-2008), M. ARII (2010)
TSVM (R. TOUZI – 2007)

EIGENVECTORS / EIGENVALUES ANALYSIS ENTROPY / ANISOTROPY

S.R. CLOUDE - E. POTTIER (1996-1997)

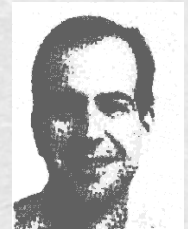
AZIMUTHAL SYMMETRY

MODEL BASED DECOMPOSITION

A.J. FREEMAN – S.L. DURDEN (1992)
Y. YAMAGUSHI (2005 - 2012), AN (2010)

MODEL BASED DECOMPOSITIONS

➔ **A. FREEMAN – S. DURDEN**
(1992)



➔ **Y. YAMAGUCHI – S. SINGH**
(2005 - 2018)



➔ **And others ...**
(2015 - 2017)



TARGET DECOMPOSITION FOR TARGETS WITH REFLECTION SYMMETRY

MODEL BASED DECOMPOSITION

A. FREEMAN – S. DURDEN (1992)



*A. Freeman and S.L. Durden, "A Three-Component Scattering Model for Polarimetric SAR Data"
IEEE TGRS, vol. 36, no. 3, May 1998*

3 COMPONENTS SCATTERING MECHANISM MODEL

$$\langle [T] \rangle = [T_S] + [T_D] + [T_V]$$



**SINGLE
SCATTERING**

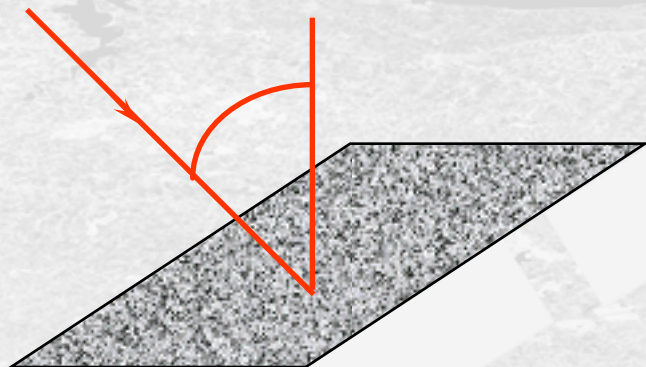


**DOUBLE
SCATTERING**



**VOLUME
SCATTERING**

SINGLE SCATTERING (ROUGH SURFACE)



MECHANISM

$$[S_s] = \begin{bmatrix} R_H & 0 \\ 0 & R_V \end{bmatrix} \Rightarrow \underline{k}_s = \begin{bmatrix} R_H + R_V \\ R_H - R_V \\ 0 \end{bmatrix}$$

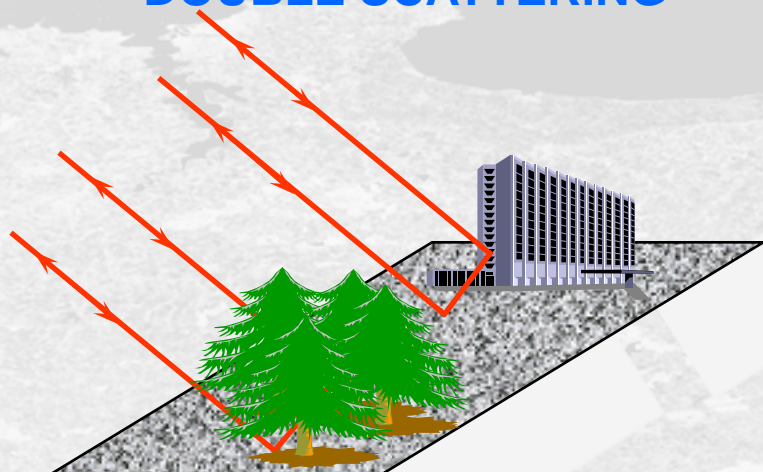
COHERENCY MATRIX

$$[T_s] = f_s \begin{bmatrix} |\beta+1|^2 & (\beta+1)(\beta-1)^* & 0 \\ (\beta+1)^*(\beta-1) & |\beta-1|^2 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$f_s = |R_V|^2$$

$$\beta = \frac{R_H}{R_V}$$

DOUBLE SCATTERING



MECHANISM

$$[S_D] = \begin{bmatrix} R_{GH} R_{TH} & 0 \\ 0 & -R_{GV} R_{TV} \end{bmatrix}$$

$$\Rightarrow \underline{k}_D = \begin{bmatrix} R_{GH} R_{TH} - R_{GV} R_{TV} \\ R_{GH} R_{TH} + R_{GV} R_{TV} \\ 0 \end{bmatrix}$$

COHERENCY MATRIX

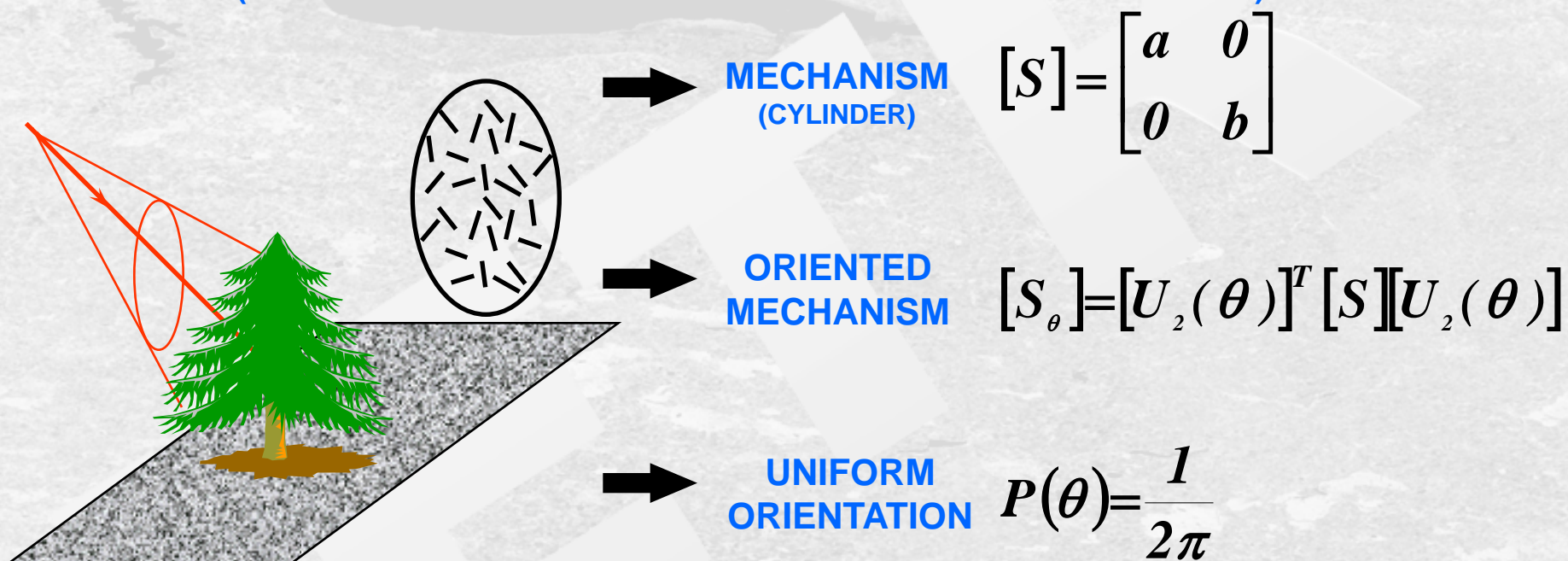
$$[T_D] = f_D \begin{bmatrix} |\alpha-1|^2 & (\alpha-1)(\alpha+1)^* & 0 \\ (\alpha-1)^*(\alpha+1) & |\alpha+1|^2 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$f_D = |R_{GV} R_{TV}|^2$$

$$\alpha = \frac{R_{GH} R_{TH}}{R_{GV} R_{TV}}$$

VOLUME SCATTERING

(RANDOMLY ORIENTED VERY THIN CYLINDER-LIKE SCATTERERS)



SECOND-ORDER STATISTICS

$$[T_v] = \langle [T_\theta] \rangle = \int_0^{2\pi} [T_v] P(\theta) d\theta$$

COVARIANCE MATRIX

(THIN CYLINDERS)

$$[T_v] = \frac{f_v}{3} \begin{bmatrix} 4 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

$a \mapsto 1 \quad b \mapsto 0$

3 COMPONENTS SCATTERING MECHANISM MODEL

$$\langle [T] \rangle = [T_S] + [T_D] + [T_V]$$



**SINGLE
SCATTERING**



**DOUBLE
SCATTERING**



**VOLUME
SCATTERING**

$$T_{11} = f_S |\beta + 1|^2 + f_D |\alpha - 1|^2 + \frac{4f_V}{3}$$

$$T_{12} = f_S (\beta + 1)(\beta - 1)^* + f_D (\alpha - 1)(\alpha + 1)^*$$

$$T_{22} = f_S |\beta - 1|^2 + f_D |\alpha + 1|^2 + \frac{2f_V}{3}$$

$$T_{33} = \frac{2f_V}{3}$$



5 UNKNOWN REAL COEFFICIENTS



4 OBSERVED EQUATIONS

$$\text{if } \Re\left(\langle S_{XX} S_{YY}^* \rangle - \frac{f_V}{3}\right) \geq 0 \Rightarrow \alpha = +1$$

$$\text{if } \Re\left(\langle S_{XX} S_{YY}^* \rangle - \frac{f_V}{3}\right) \leq 0 \Rightarrow \beta = +1$$



$$\{f_S, |\beta|, f_D, |\alpha|, f_V\}$$

$$\text{span} = \langle T_{11} \rangle + \langle T_{22} \rangle + \langle T_{33} \rangle = f_S (1 + \beta^2) + f_D (1 + |\alpha|^2) + \frac{2}{3} f_V$$



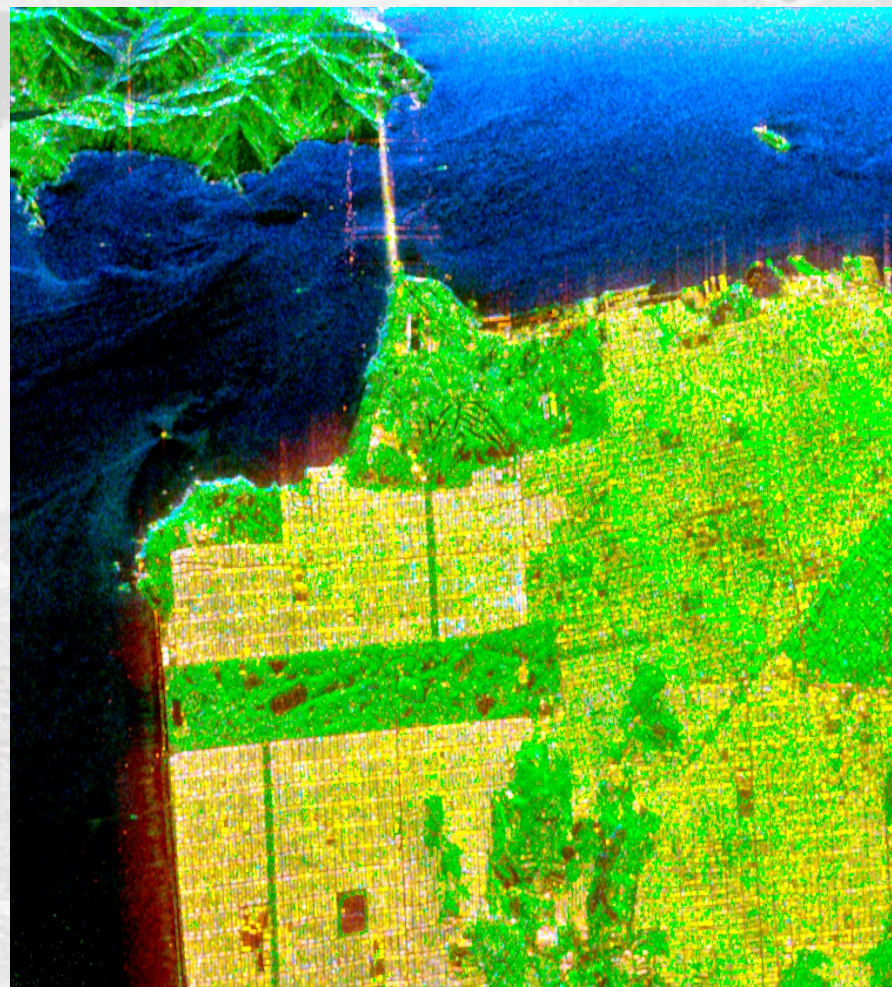
**SINGLE BOUNCE
SCATTERING
(ODD)**



**DOUBLE DOUBLE
SCATTERING
(DBL)**



**VOLUME
SCATTERING
(VOL)**



$$2A_0$$

$$B_0 + B$$

$$B_0 - B$$

$$ODD = f_s (1 + \beta^2)$$

$$VOL = \frac{2f_v}{3}$$

$$DBL = f_D (1 + \alpha^2)$$

TARGET DECOMPOSITION FOR TARGETS WITHOUT REFLECTION SYMMETRY

MODEL BASED - 4 COMPONENTS DECOMPOSITION

Y. YAMAGUCHI et al. (2005 - 2013)



MEDIUM WITHOUT ANY REFLECTION SYMMETRY

4 COMPONENTS SCATTERING MECHANISM MODEL

$$\langle [T] \rangle = [T_S] + [T_D] + [T_V] + [T_H]$$



**SINGLE
SCATTERING**



**DOUBLE
SCATTERING**



**VOLUME
SCATTERING**



**HELIX
SCATTERING**

$$[S]_{\pm Helix} = \frac{1}{2} \begin{bmatrix} 1 & \pm j \\ \pm j & -1 \end{bmatrix}$$

$$\langle [T] \rangle_{Helix} = \frac{1}{2} \left\langle \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & \pm j \\ 0 & \mp j & 1 \end{bmatrix} \right\rangle$$

**Non reflection
Symmetric cases**

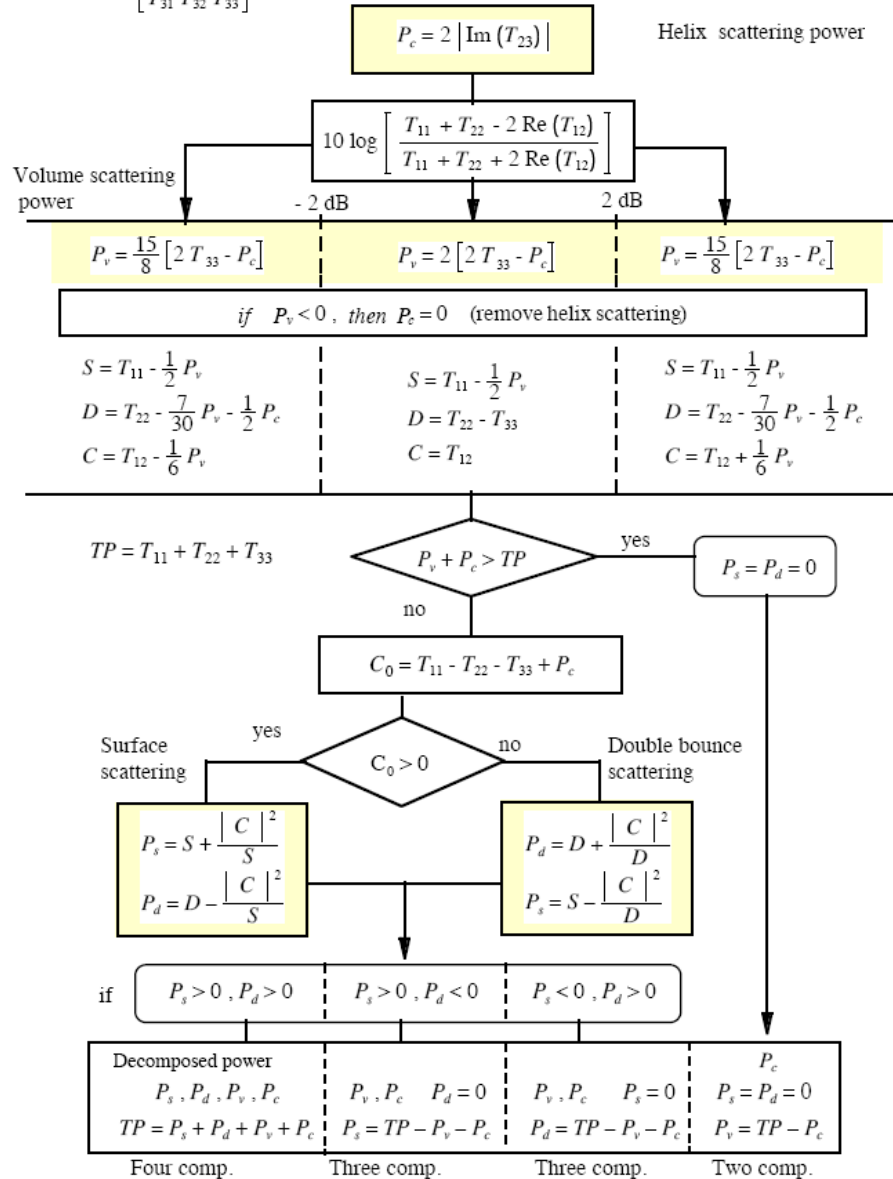
Yamaguchi Y., Moriyama T., Ishido M. and Yamada H., "Four-Component Scattering Model for Polarimetric SAR Image Decomposition", IEEE Trans. Geos. Remote Sens., vol. 43, no. 8, August 2005.

Yamaguchi Y., Yajima Y. and Yamada H., "A Four-Component Decomposition of POLSAR Images Based on the Coherency Matrix", IEEE Geos. Rem. Sens. Letters, vol. 3, no. 3, July 2006.

MODEL BASED DECOMPOSITION

Y40

$$\langle [T] \rangle = \begin{bmatrix} T_{11} & T_{12} & T_{13} \\ T_{21} & T_{22} & T_{23} \\ T_{31} & T_{32} & T_{33} \end{bmatrix} = \frac{1}{n} \sum k_p k_p^\dagger$$





$$2A_0$$

$$B_0 + B$$

$$B_0 - B$$

$$ODD = f_s (1 + \beta^2)$$

$$VOL = \frac{2f_v}{3}$$

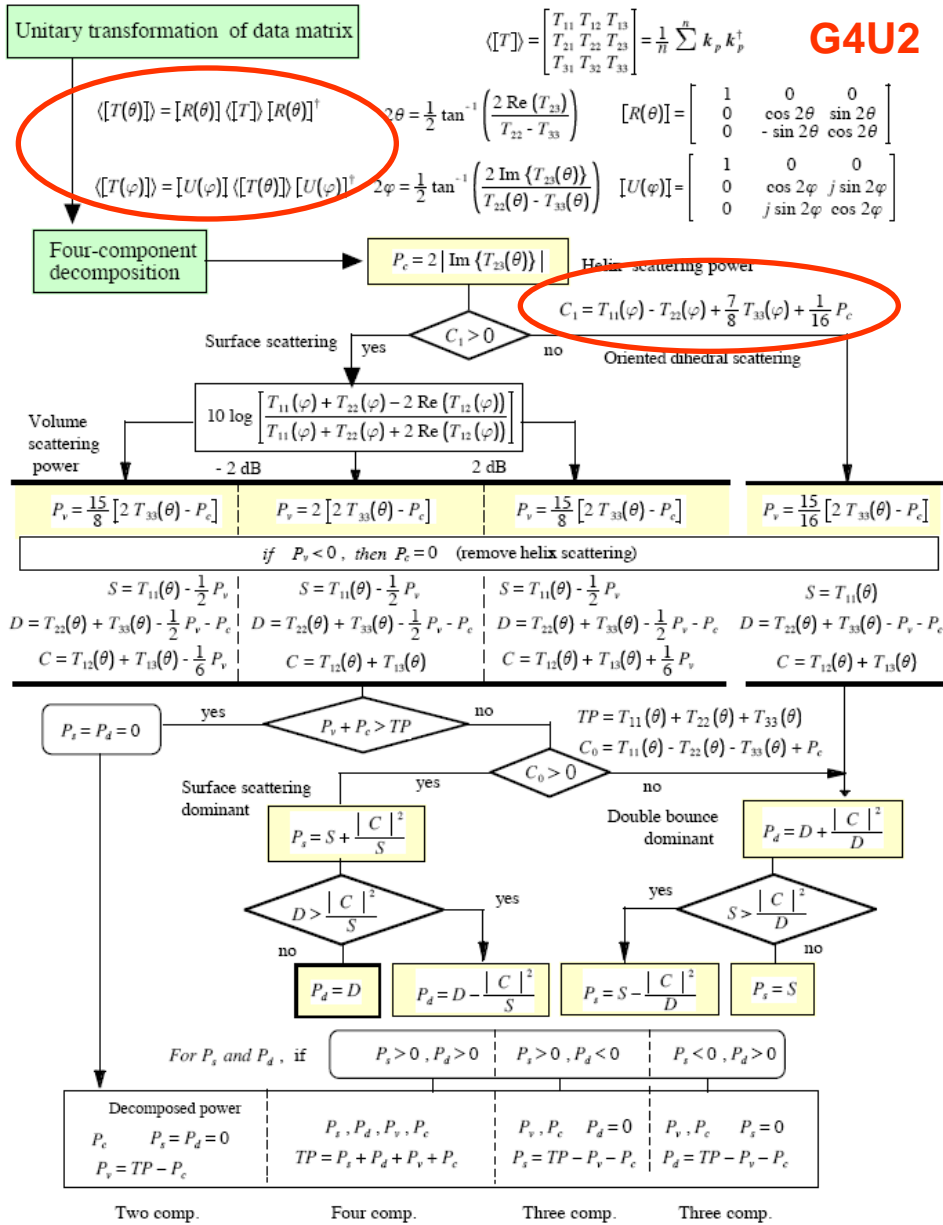
$$DBL = f_D (1 + \alpha^2)$$

Y. Yamaguchi, A. Sato, W.M. Boerner, R. Sato, H. Yamada, “*4-component scattering power decomposition with rotation of coherency matrix*”, IEEE TGRS vol. 49, no. 6, **June 2011**.

A. Sato, Y. Yamaguchi, G. Singh, and S.-E. Park, “*4-component scattering power decomposition with extended volume scattering model*”, IEEE GRS Letters, vol. 9, no. 2, pp. 166–170, **March 2012**.

G. Singh, Y. Yamaguchi, S.E. Park, Y. Cui, H. Kobayashi, « *Hybrid Freeman/Eigenvalue Decomposition Method With Extended Volume Scattering Model* » IEEE GRS Letters, vol. 10, no. 1, **January 2013**.

G. Singh, Y. Yamaguchi, S.E. Park, « *General Four-Component Scattering Power Decomposition With Unitary Transformation of Coherency Matrix* » IEEE TGRS vol. 51, no. 5, **May 2013**.





$2A_0$

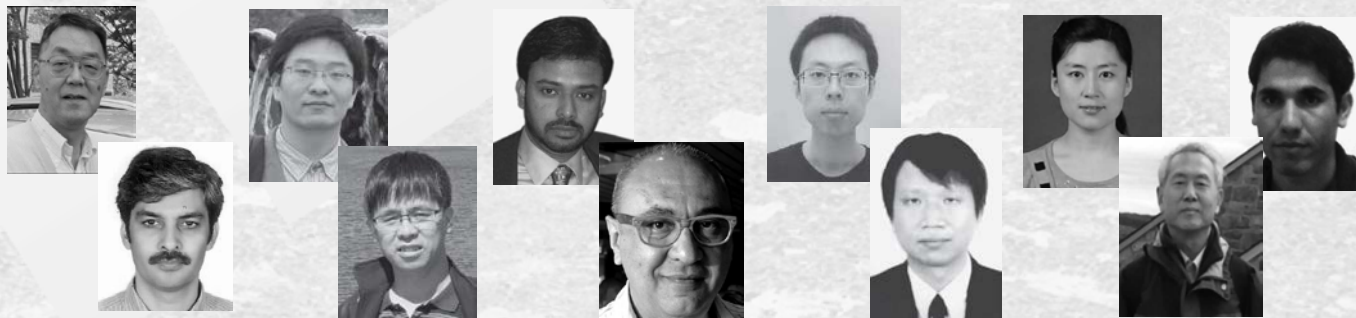
$B_0 + B$

$B_0 - B$

ODD DBL VOL

TARGET DECOMPOSITION FOR TARGETS WITHOUT REFLECTION SYMMETRY

MODEL BASED - 4 / 5 / 6 COMPONENTS DECOMPOSITION
(2015 - 2017)



A. BHATTACHARYA, A. FRERY, “*Modifying the Yamaguchi 4-component decomposition scattering powers using a stochastic distance*”, IEEE JSTARS, vol. 8, pp 3497-3506, **July 2015**.

F. XU, Y.Q. JIN, “*Deorientation theory of Polarimetric scattering targets and application to terrain surface classification*”, IEEE TGRS Vol 43, n° 10, **October 2015**.

B. ZOU, D. LU, L. ZHANG, W.M. Moon, « *Eigen-decomposition-based Four Component Decomposition for PoSAR Data*”. IEEE JSTARS, vol. 9, pp 1286-1296, **March 2016**.

H. AGHABABAEI, M. Reza SAHEBI, “*Incoherent Target Scattering Decomposition of Polarimetric SAR Data Based on Vector Model Roll-Invariant Parameters*”. IEEE TGRS, vol. 54, no 8, **August 2016**.

G. SINGH, Y. YAMAGUCHI, “*Model-based Six-Component Scattering Matrix Power Decomposition*”, IEEE TGRS Vol 56, n° 10, **October 2018**.



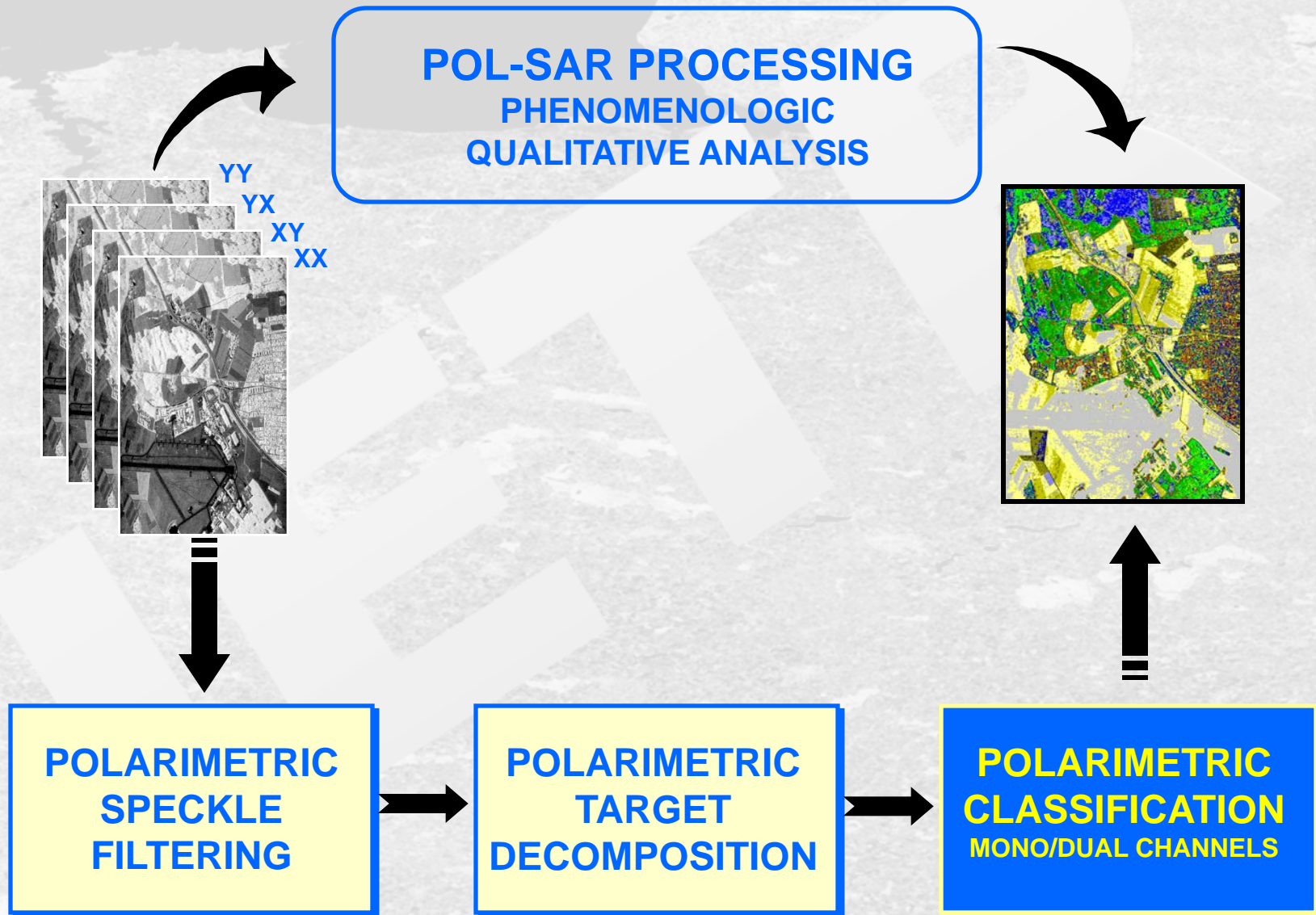
$2A_0$

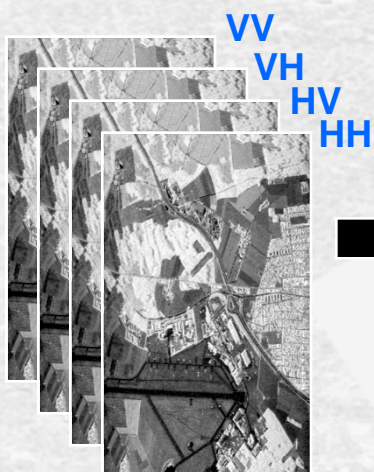
$B_0 + B$

$B_0 - B$

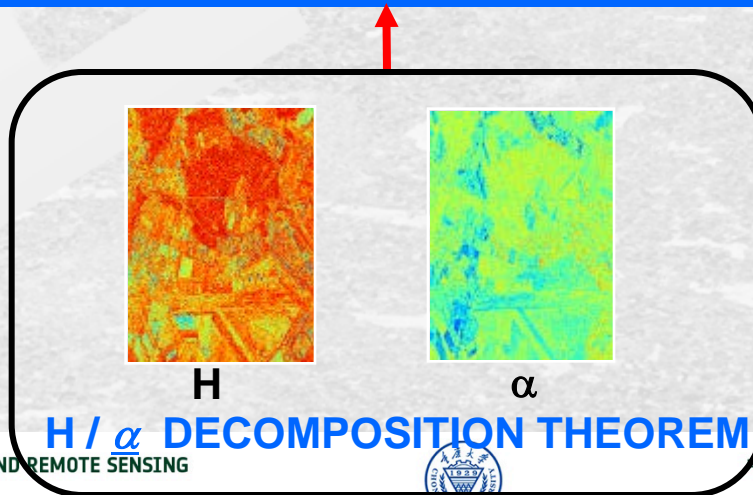
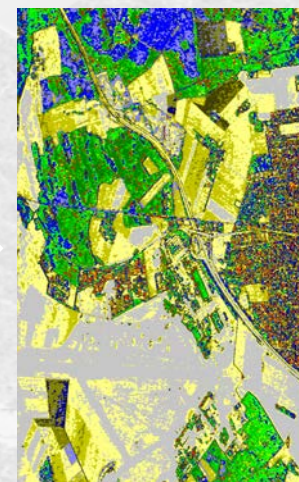
ODD DBL VOL

Singh decomposition – 6 components





**UNSUPERVISED
POLAR
CLASSIFICATION**
S.R. CLOUDE, E.POTTIER (1996)



ENTROPY

$$H = -\sum_{i=1}^3 P_i \log_3(P_i)$$

α PARAMETER

$$\alpha = P_1\alpha_1 + P_2\alpha_2 + P_3\alpha_3$$

ANISOTROPY

$$A = \frac{\lambda_2 - \lambda_3}{\lambda_2 + \lambda_3}$$

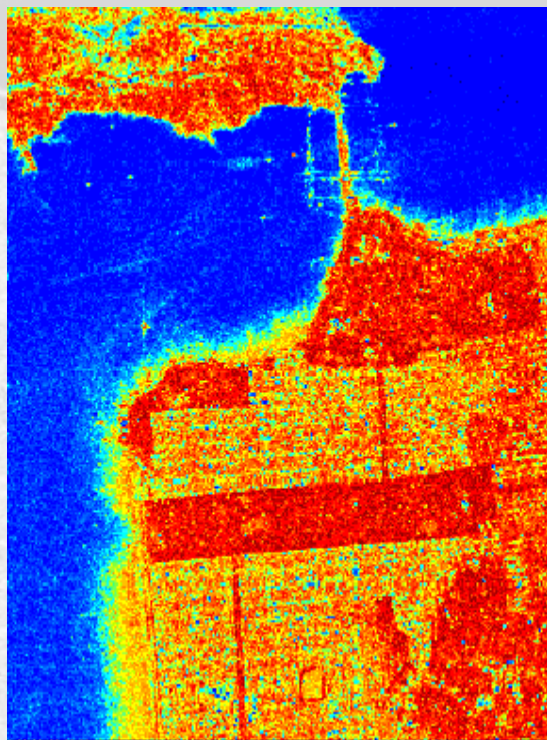
3 ROLL INVARIANT PARAMETERS

$$\underline{I} = \begin{bmatrix} \alpha \\ HA \\ H(1-A) \\ (1-H)A \\ (1-H)(1-A) \end{bmatrix}$$

PHYSICAL SCATTERING MECHANISM

TYPE OF SCATTERING PROCESS

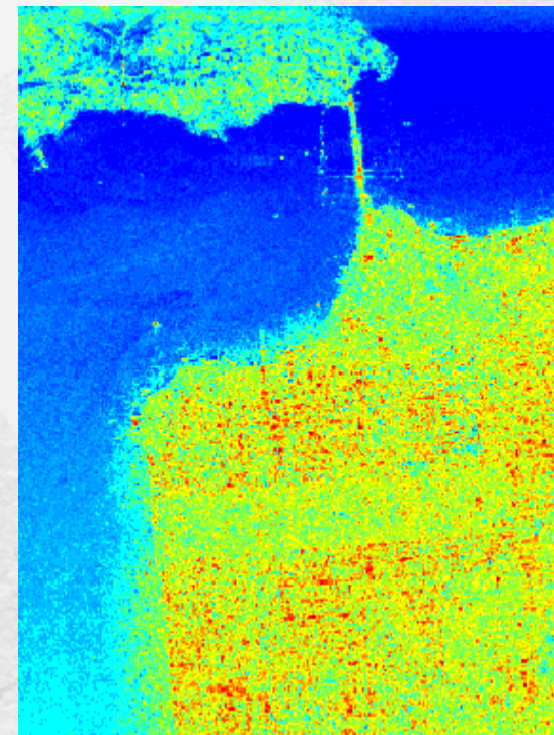
SEGMENTATION / CLASSIFICATION



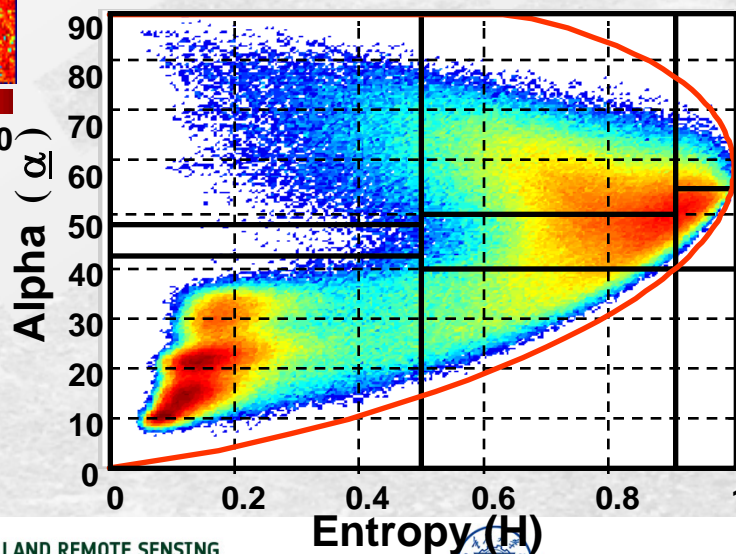
0 0.5 1.0
H



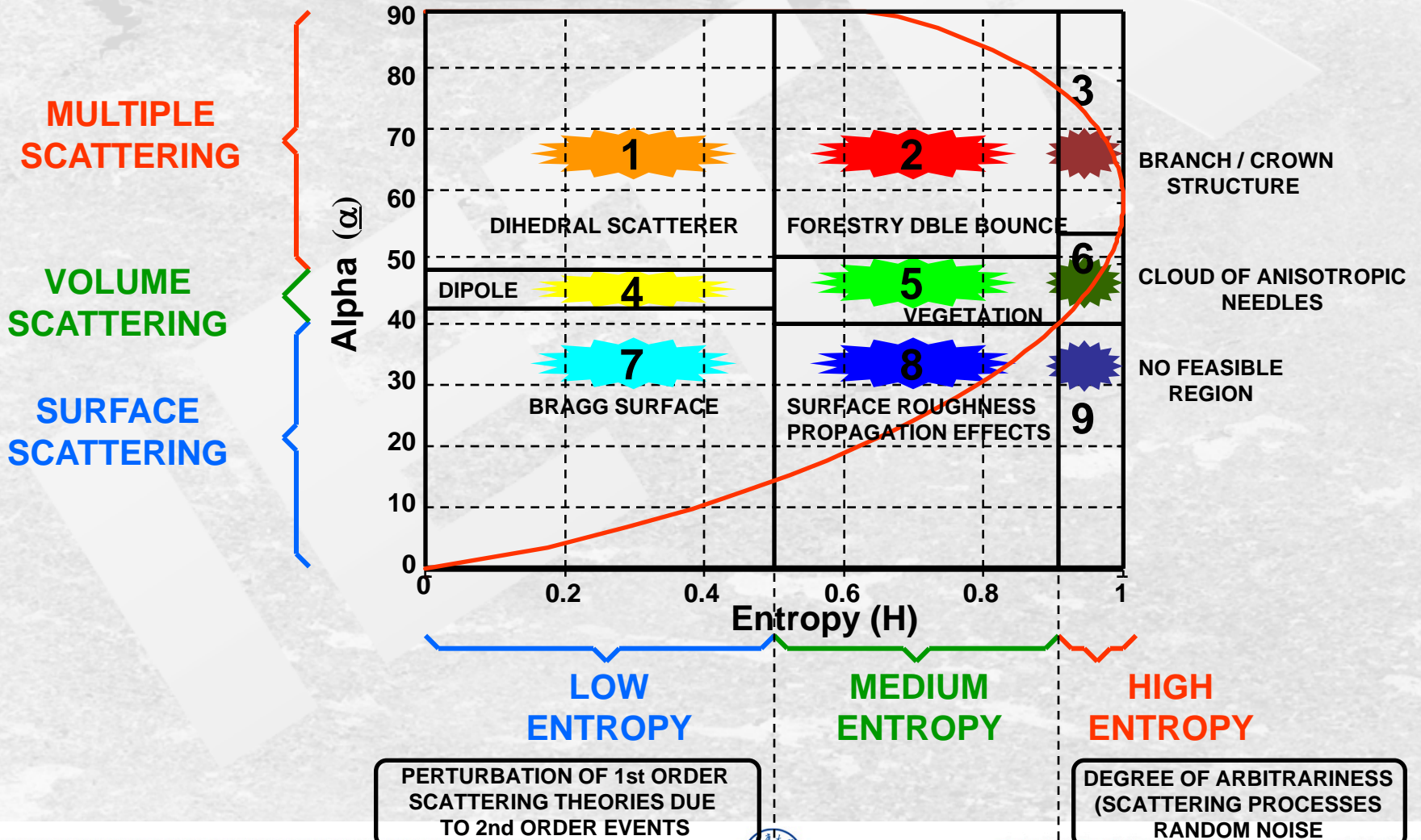
POLSAR DATA DISTRIBUTION IN THE H / α PLANE



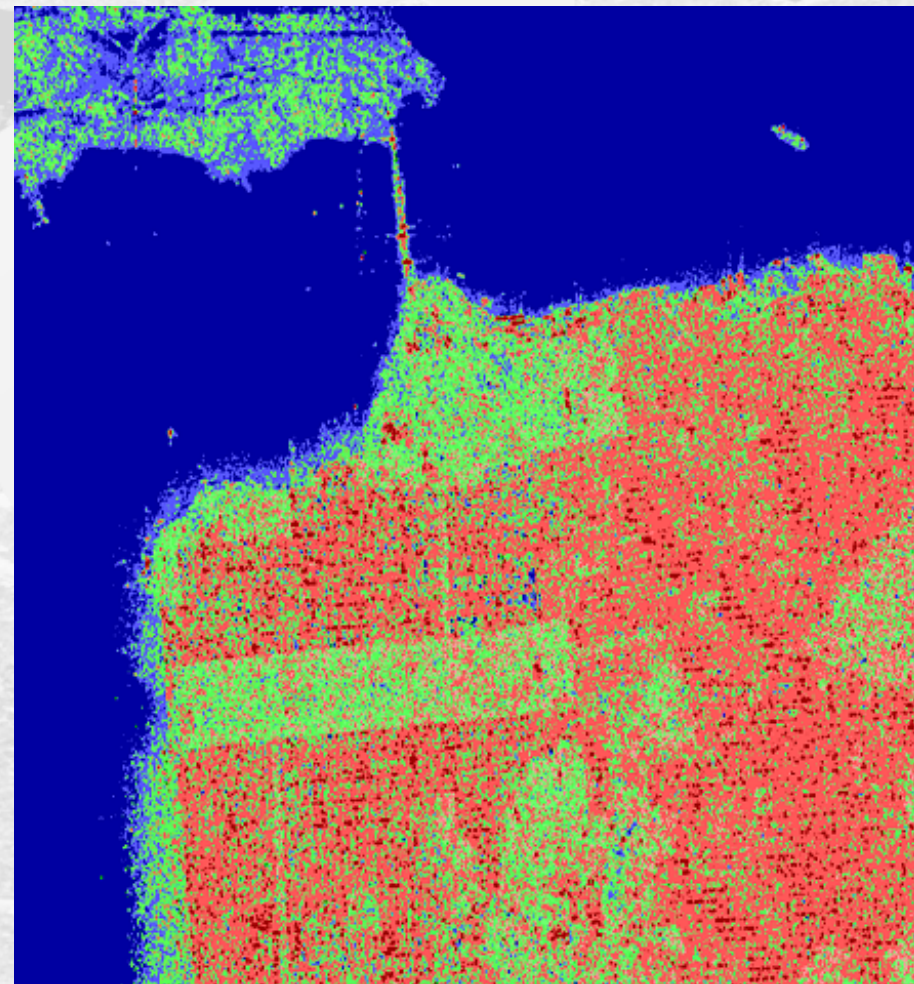
0 45° 90°
 α



SEGMENTATION OF THE H / α SPACE



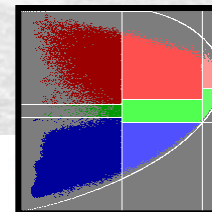
H - α classification



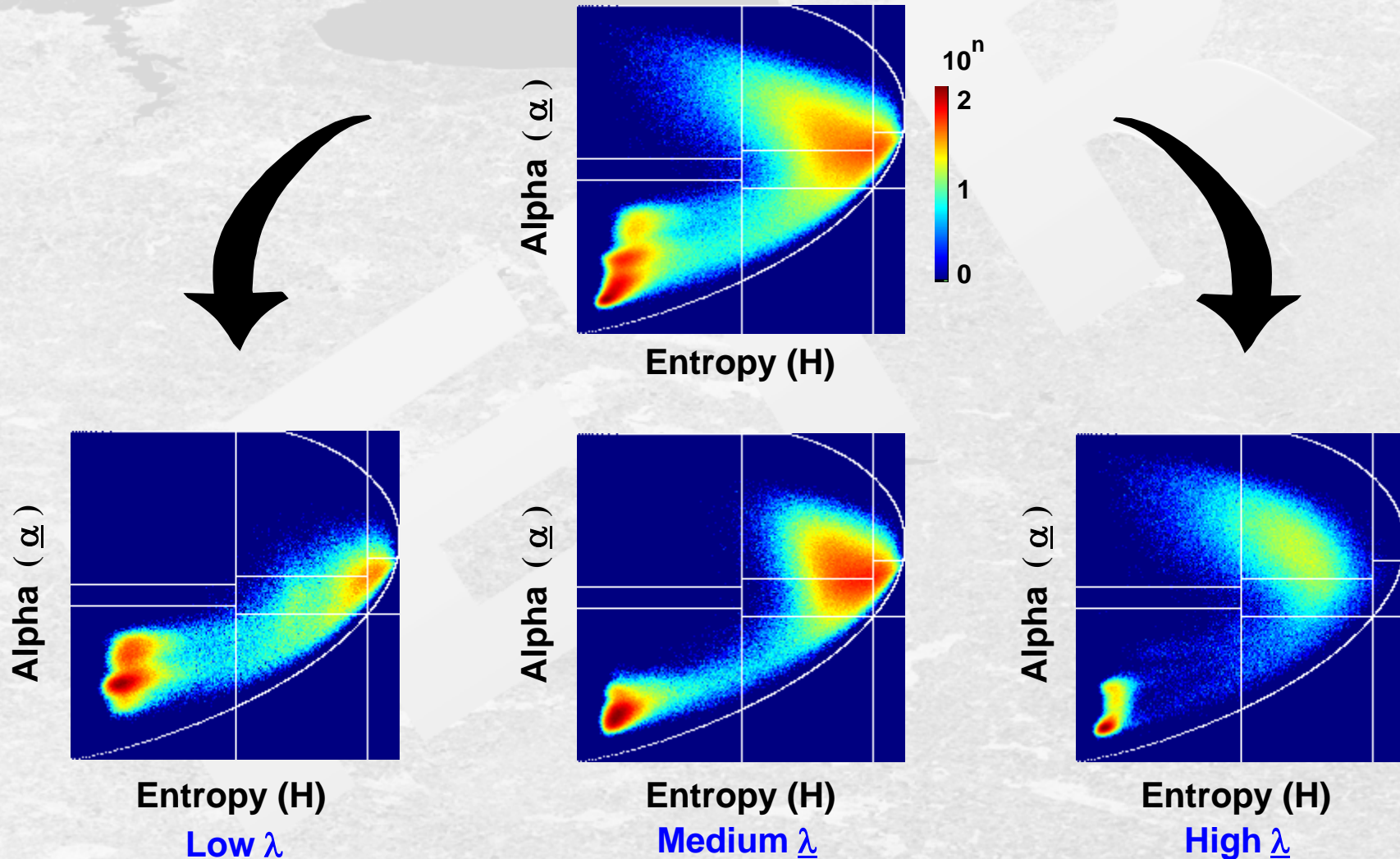
$2A_0$

$B_0 + B$

$B_0 - B$

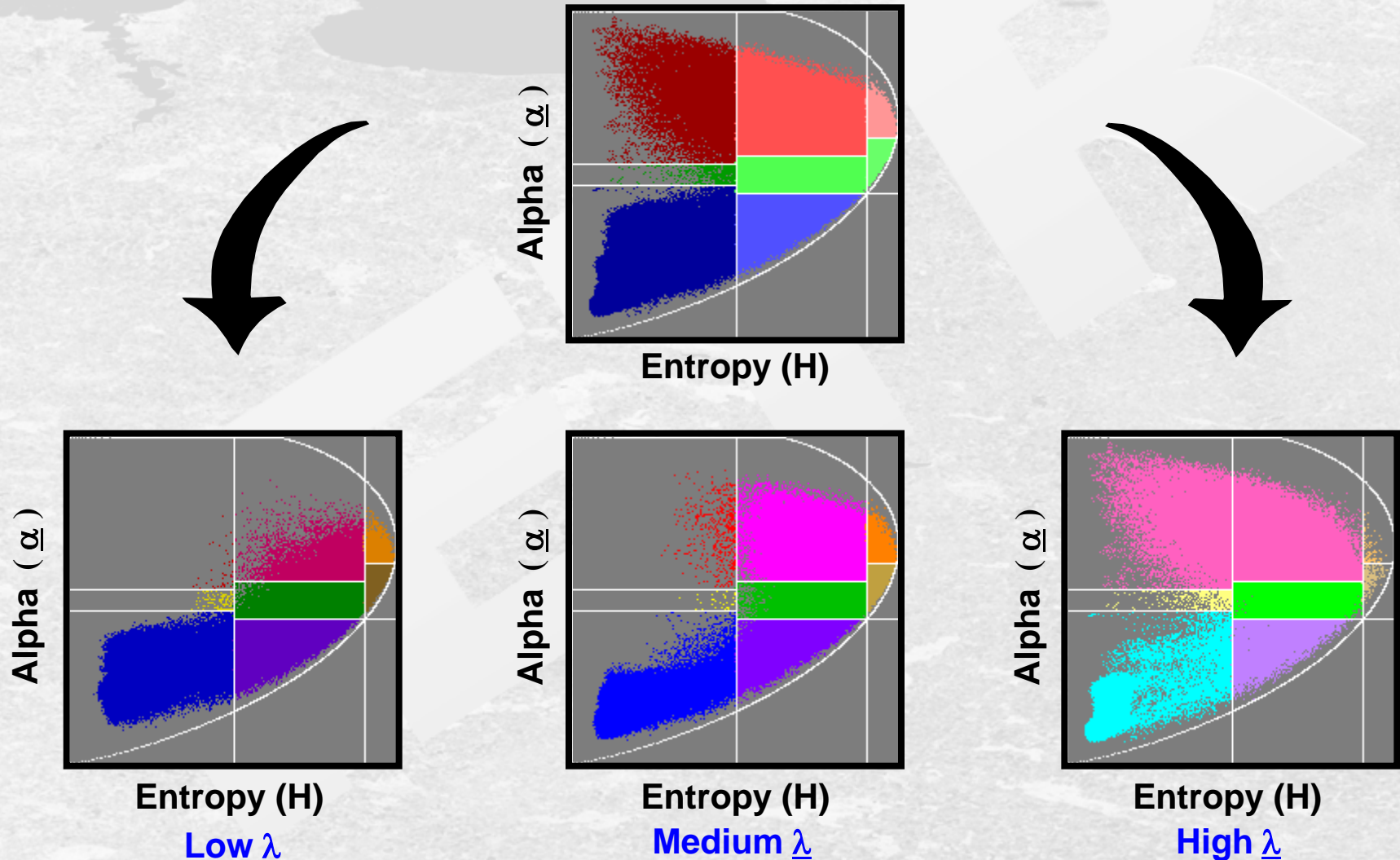


POLSAR DATA DISTRIBUTION IN THE H / α PLANE



Cao Fang, Hong Wen A New Classification Method Based on Cloude-Pottier Eigenvalue / Eigenvector Decomposition, IGARSS 05, Seoul, Korea

POLSAR DATA DISTRIBUTION IN THE H / α PLANE



Cao Fang, Hong Wen A New Classification Method Based on Cloude-Pottier Eigenvalue / Eigenvector Decomposition, IGARSS 05, Seoul, Korea

H - α (λ) classification



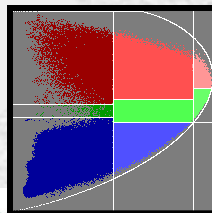
$2A_0$

$B_0 + B$

$B_0 - B$



H- α classification



H / α Classification Space
Sub-divided into 9 basic zones



Location of the boundaries
is arbitrary and generically

Degree of arbitrariness on the
setting of these boundaries



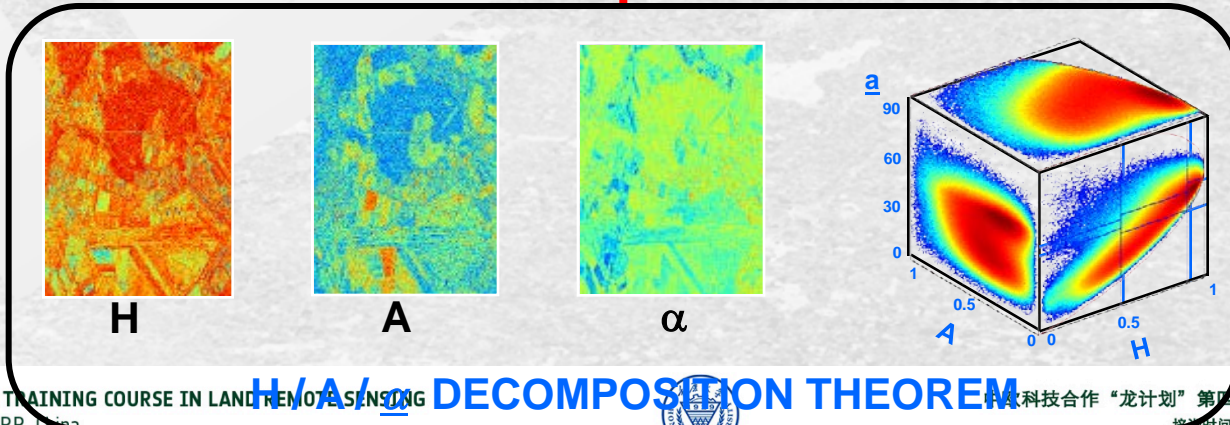
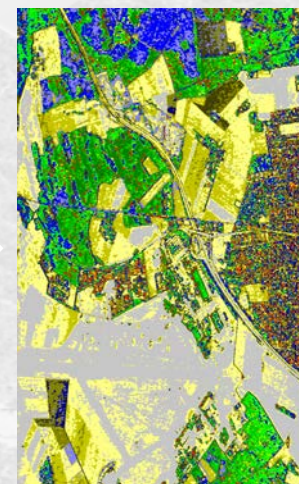
Segmentation is offered merely
to illustrate the unsupervised
classification strategy and to
emphasize the geometrical
segmentation of physical scattering
processes

WISHART PDF $P(\langle [T] \rangle / [T_m]) = \frac{L^p \langle [T] \rangle^{L-p} e^{-LTr([T_m]^{-1} \langle [T] \rangle)}}{\pi^{\frac{p(p-1)}{2}} \Gamma(L) \dots \Gamma(L-p+1) [T_m]^L}$



UNSUPERVISED POLARSAR CLASSIFICATION

E.POTTIER, J.S LEE (2000)



PoISAR TERRAIN and LAND-USE CLASSIFICATION

J.S. Lee, M.R. Grunes, E. Pottier, L. Ferro-Famil, “Unsupervised terrain classification preserving scattering characteristics,” *IEEE Transactions on Geoscience and Remote Sensing*, vol. 42, no.4, pp. 722-731, April, 2004.

J.S. Lee, M. R. Grunes and E. Pottier, “Quantitative Comparison of Classification Capability: Fully polarimetric versus Dual- and Single polarization SAR,” *IEEE TGRS*, November 2002

E. Pottier and J.S. Lee, “Application of the « $H / A / \alpha$ » polarimetric decomposition theorem for unsupervised classification of fully polarimetric SAR data based on the Wishart distribution” *Proceedings of EUSAR2000*

J.S. Lee, M.R. Grunes, T.L. Ainsworth, L. Du, D.L. Schuler, and S.R. Cloude, “ Unsupervised Classification of Polarimetric SAR Imagery Based on Target Decomposition and Wishart Distribution,” *IEEE Transactions on Geoscience and Remote Sensing*, vol. 37, no. 5, 2249-2258, September 1999.

J.S. Lee, M. R. Grunes and R. Kwok,” Classification of Polarimetric SAR Images Based on the Complex Wishart Distribution,” *Int. J. Remote Sensing*, vol.32, No. 5, Sept. 1994.

J.S. Lee, E. Pottier, *Polarimetric Radar Imaging: From Basics to Applications*, Taylor & Francis/CRC, 2009

Target Vector

$$\underline{X} = \begin{bmatrix} S_{HH} & \sqrt{2}S_{HV} & S_{VV} \end{bmatrix}^T$$

$$P(\underline{X}) = \frac{1}{\pi^3 |[C]|} e^{-\underline{X}^{*T} [C]^{-1} \underline{X}}$$

$$\underline{k} = \frac{1}{\sqrt{2}} \begin{bmatrix} S_{HH} + S_{VV} & S_{HH} - S_{VV} & 2S_{HV} \end{bmatrix}^T$$

$$P(\underline{k}) = \frac{1}{\pi^3 |[T]|} e^{-\underline{k}^{*T} [T]^{-1} \underline{k}}$$

Coherency Matrix

$$\langle [T] \rangle = \frac{1}{N} \sum_{i=1}^N \underline{k}_i \cdot \underline{k}_i^{*T} = \frac{1}{N} \sum_{i=1}^N [T_i]$$

$$P(\langle [T] \rangle / [T_m]) = \frac{L^{Lp} |\langle [T] \rangle|^{L-p} e^{-L \text{Tr}([T_m]^{-1} \langle [T] \rangle)}}{\pi^{\frac{p(p-1)}{2}} \Gamma(L) \dots \Gamma(L-p+1) [T_m]^L}$$

COMPLEX WISHART DISTRIBUTION

L: Number of Look p: Polarimetric Dimension

$$P(\langle [T] \rangle / [T_m]) = \frac{L^{Lp} \|\langle [T] \rangle\|^{L-p} e^{-LTr([T_m]^{-1} \langle [T] \rangle)}}{\pi^{\frac{p(p-1)}{2}} \Gamma(L) \dots \Gamma(L-p+1) [T_m]^L}$$



BAYES MAXIMUM LIKELIHOOD CLASSIFICATION PROCEDURE

$$\langle [T] \rangle \in [T_m] \quad \text{if} \quad d_m(\langle [T] \rangle) < d_j(\langle [T] \rangle) \quad \forall j \neq m$$

with

$$d_m(\langle [T] \rangle) = LTr([T_m]^{-1} \langle [T] \rangle) + L \ln([T_m]) - \ln(P([T_m])) + K$$

$[T_m]$: Cluster Center of the class m

ROBUSTENESS OF WISHART CLASSIFIER

$$d_m(\langle [T] \rangle) = L \text{Tr}([T_m]^{-1} \langle [T] \rangle) + L \ln([T_m]) - \ln(P([T_m])) + K$$

INDEPENDENT OF # OF LOOKS

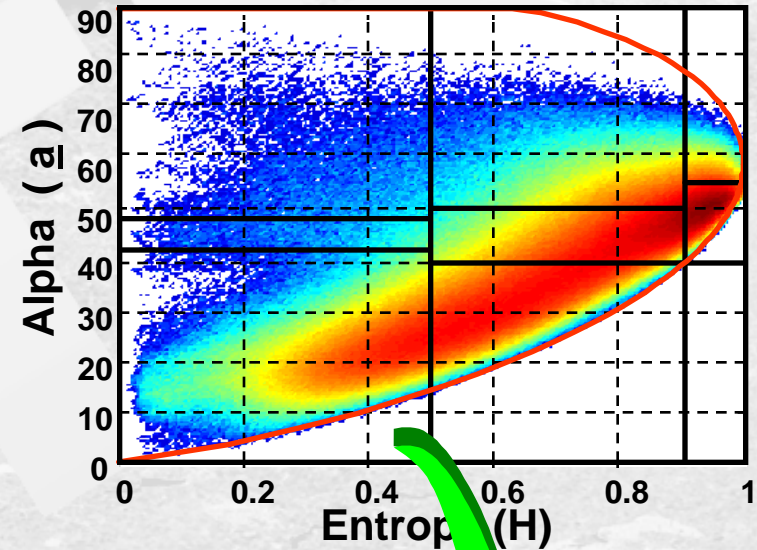
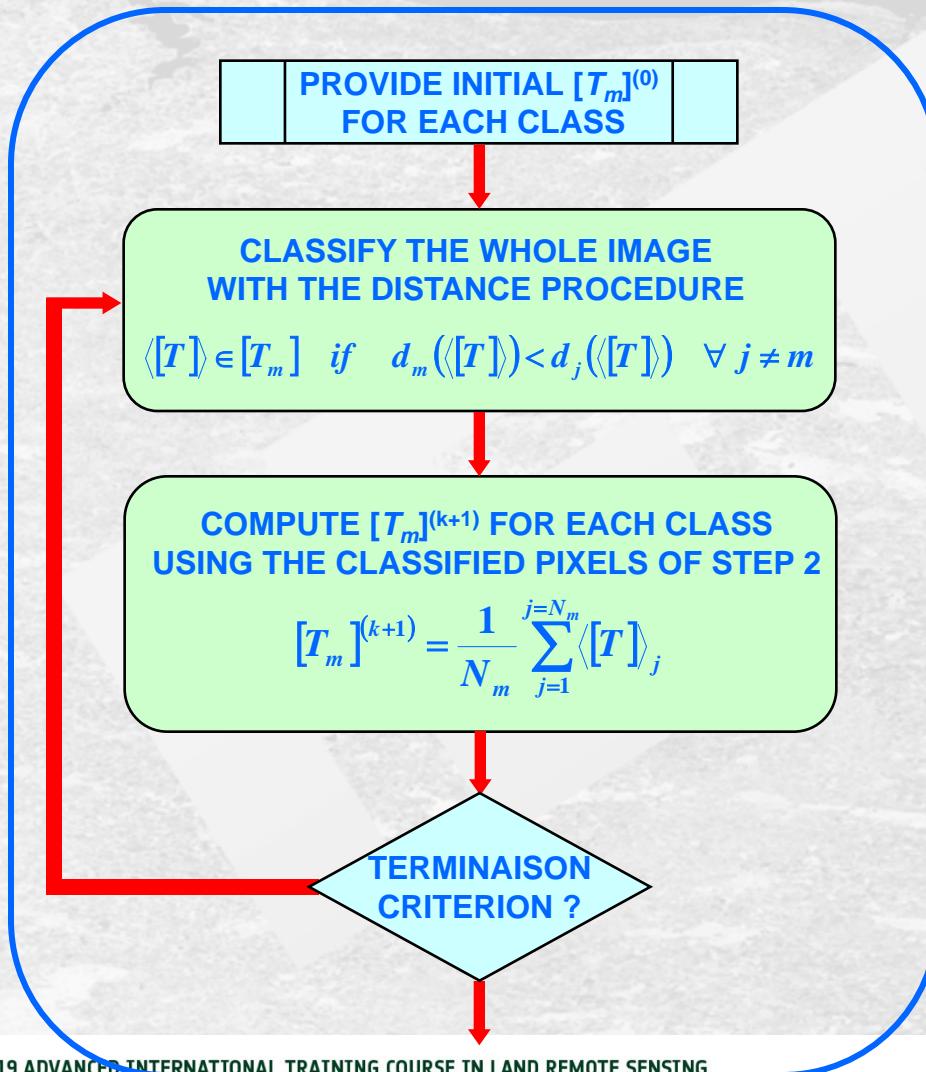
INDEPENDENT OF POLARIZATION BASIS

[T] or [C] IDENTICAL CLASSIFICATION RESULTS

For Dual-Pol ($p=2$), PolSAR ($p=3$), Pol-InSAR ($p=6$)

J.S. Lee, E. Pottier, *Polarimetric Radar Imaging: From Basics to Applications*, Taylor & Francis/CRC, 2009

k - mean CLASSIFICATION PROCEDURE



$$[T_m]^{(0)} = \frac{1}{N_m} \sum_{k=1}^{k=N_m} \langle [T] \rangle_k$$

Cluster Center of the class m
(Lee 1998)

SAN FRANCISCO BAY JPL - AIRSAR L-band 1988



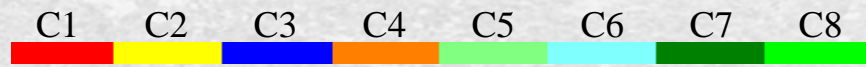
4th ITERATION



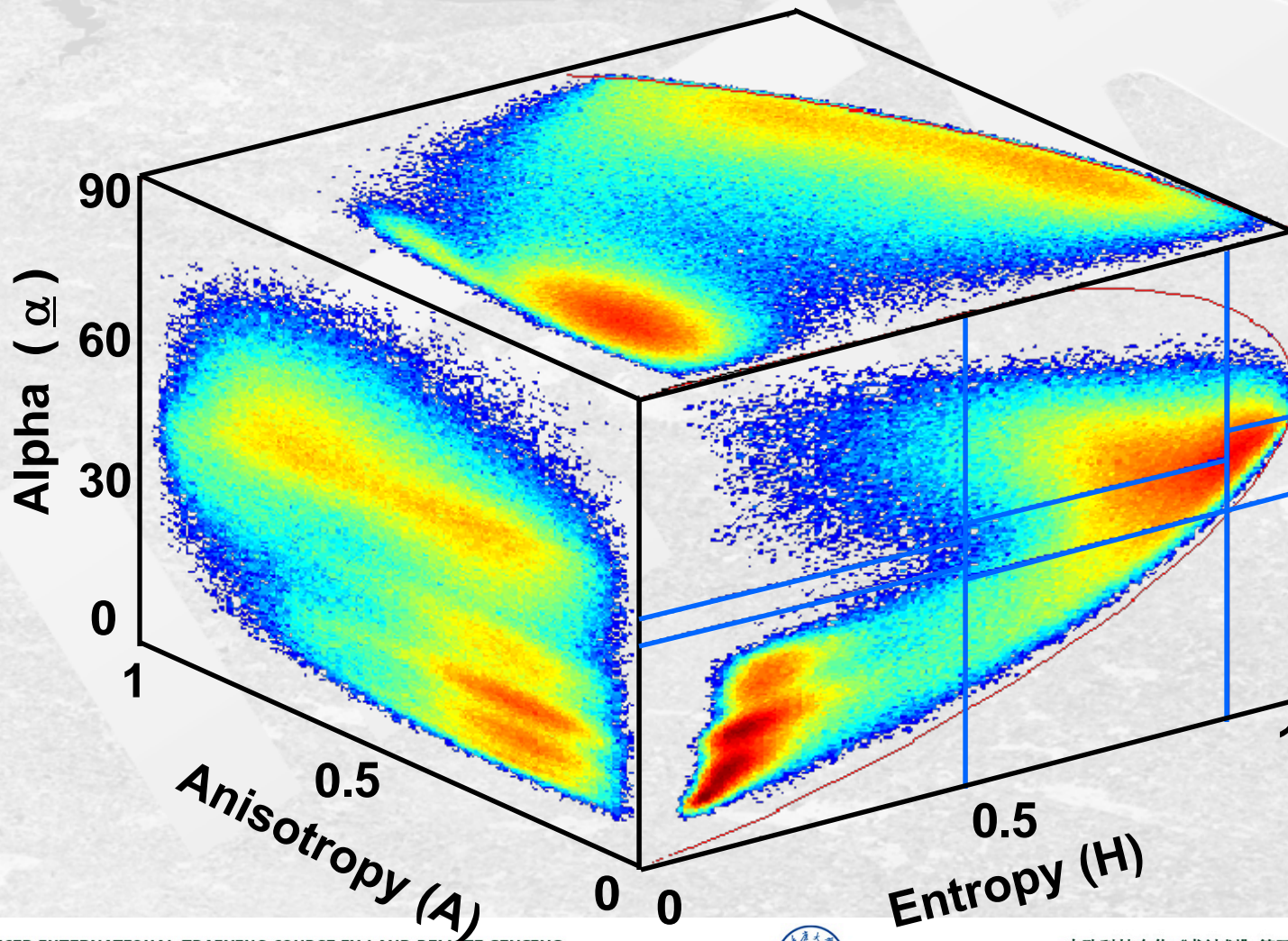
$2A_0$

$B_0 + B$

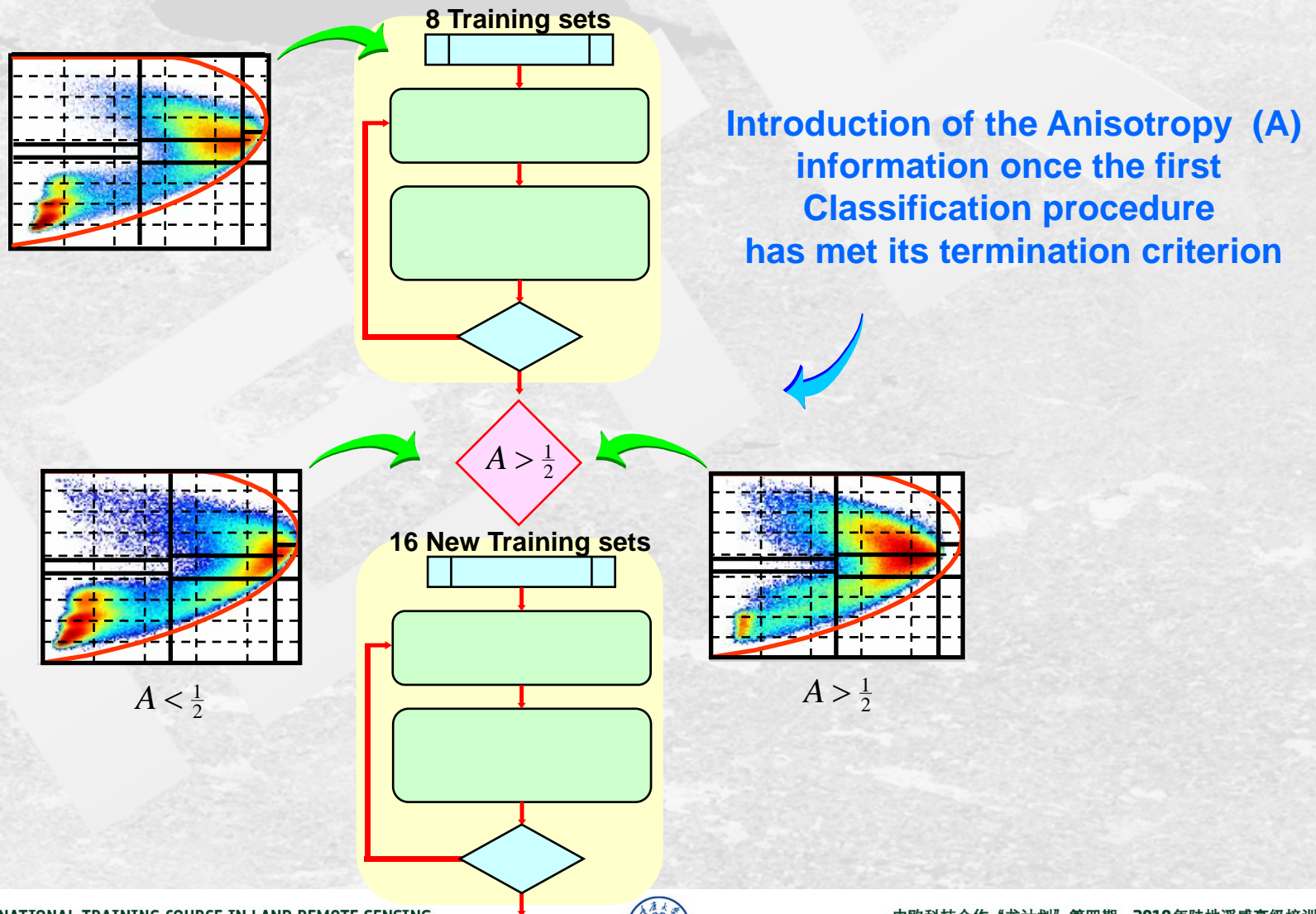
$B_0 - B$



POLSAR DATA DISTRIBUTION IN THE H / A / α SPACE

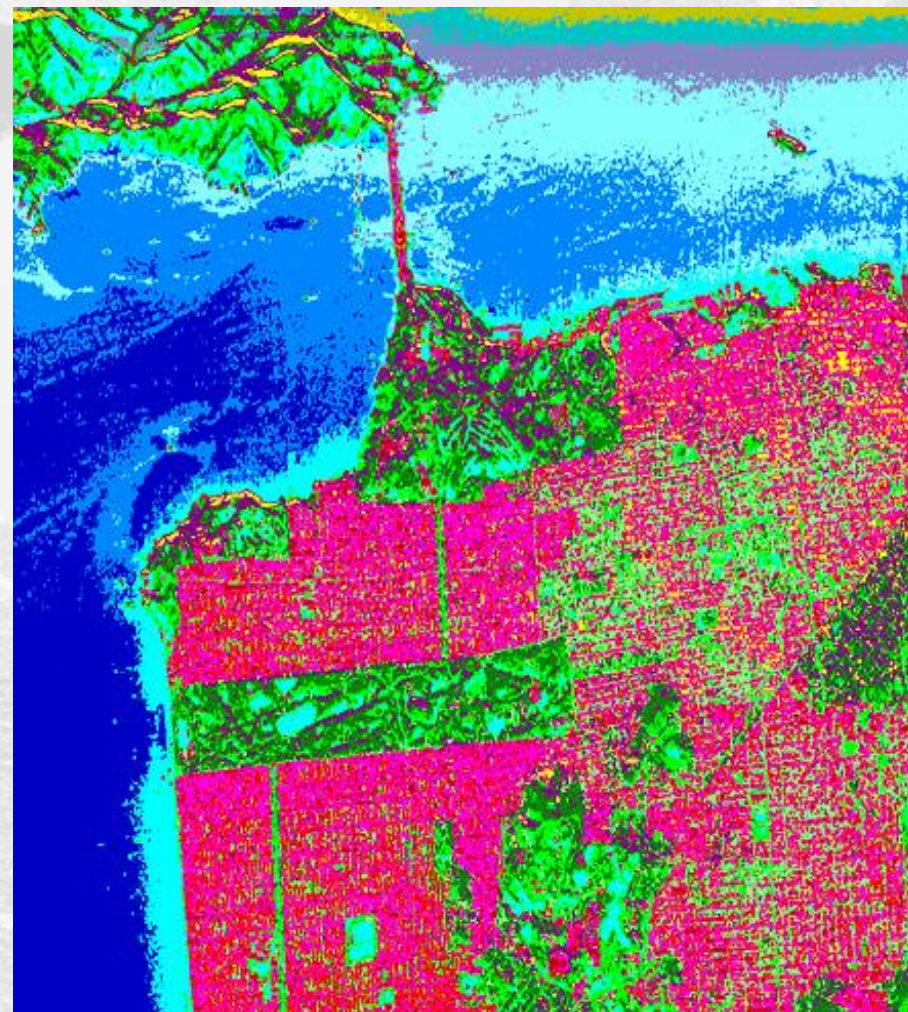


2 Successive k - mean Classification procedures



SAN FRANCISCO BAY JPL - AIRSAR L-band 1988

4th ITERATION



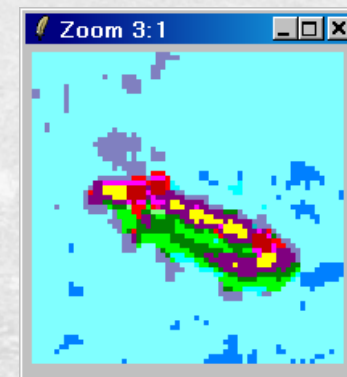
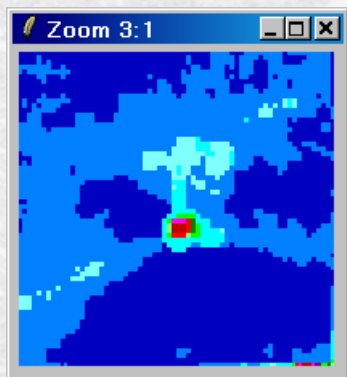
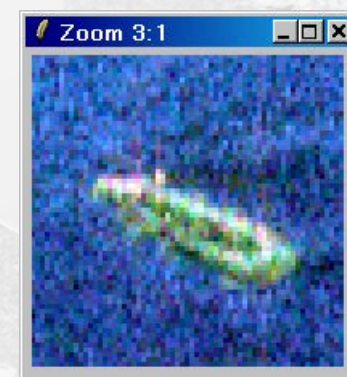
$2A_0$

$B_0 + B$

$B_0 - B$



SAN FRANCISCO BAY JPL - AIRSAR L-band 1988

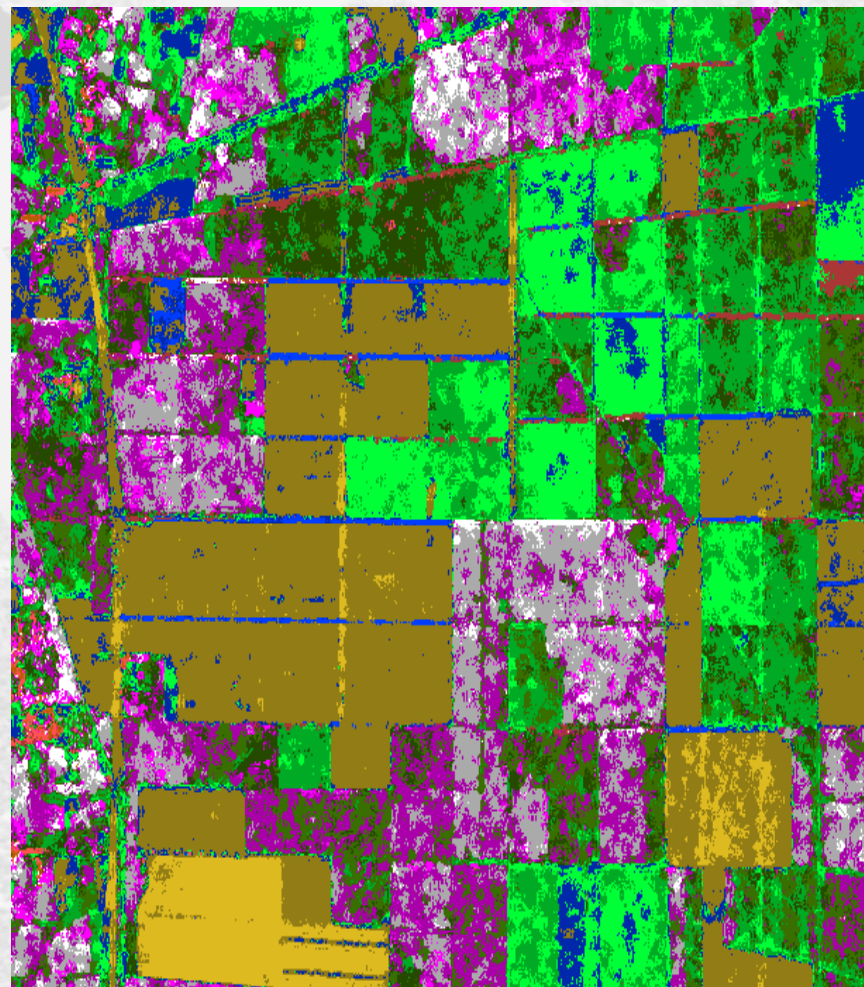


$$2A_0$$

$$B_0 + B$$

$$B_0 - B$$

NEZER FOREST JPL - AIRSAR L-band



$2A_0$

$B_0 + B$

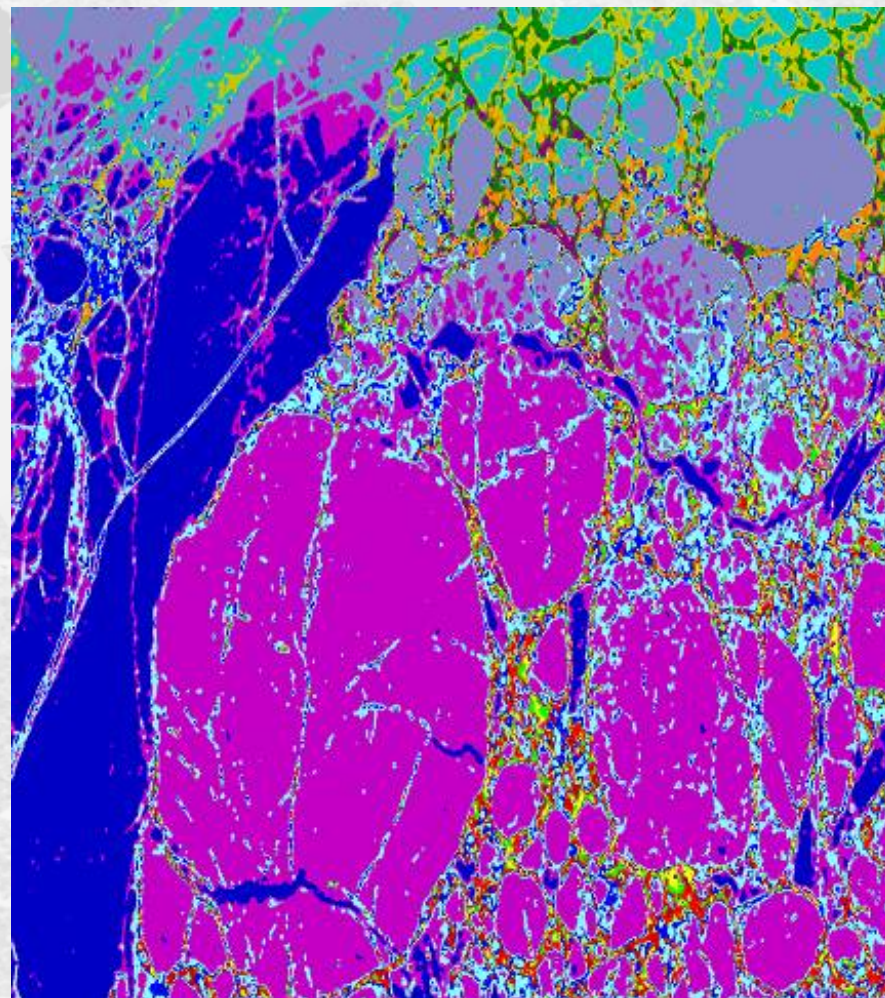
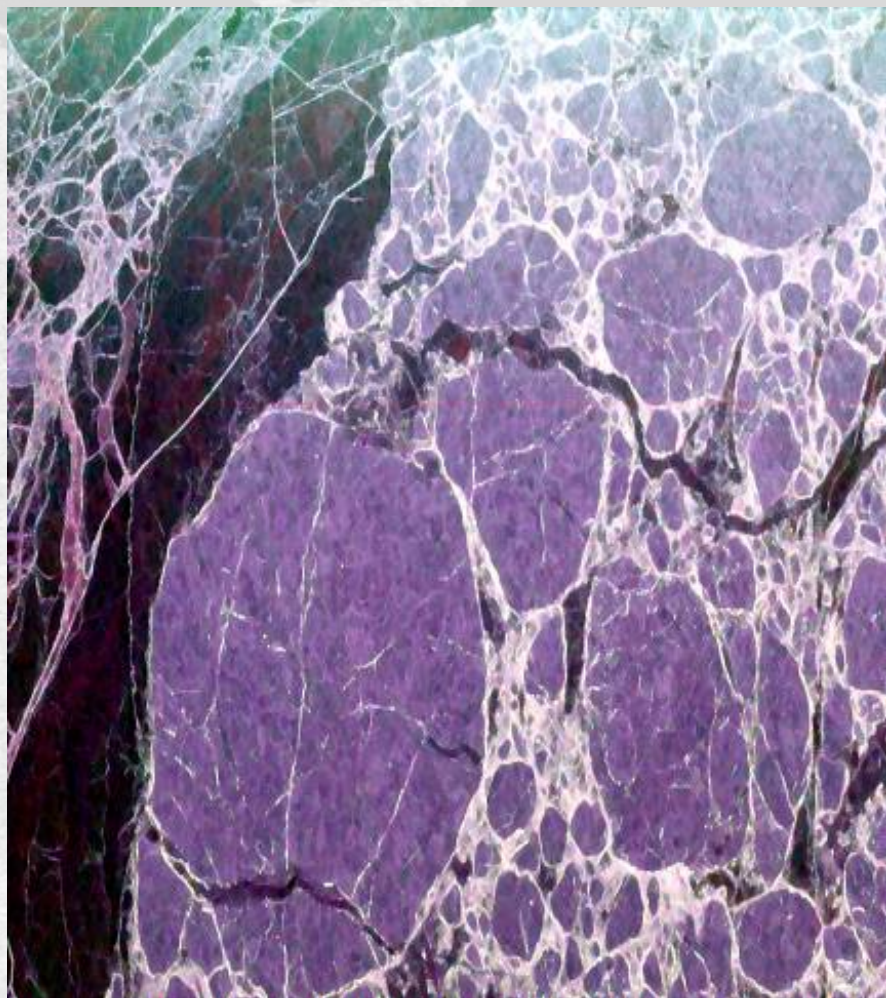
$B_0 - B$

C1 C2 C3 C4 C5 C6 C7 C8



C10 C11 C12 C13 C14 C15 C16

ICE AREA JPL - AIRSAR L-band



$2A_0$

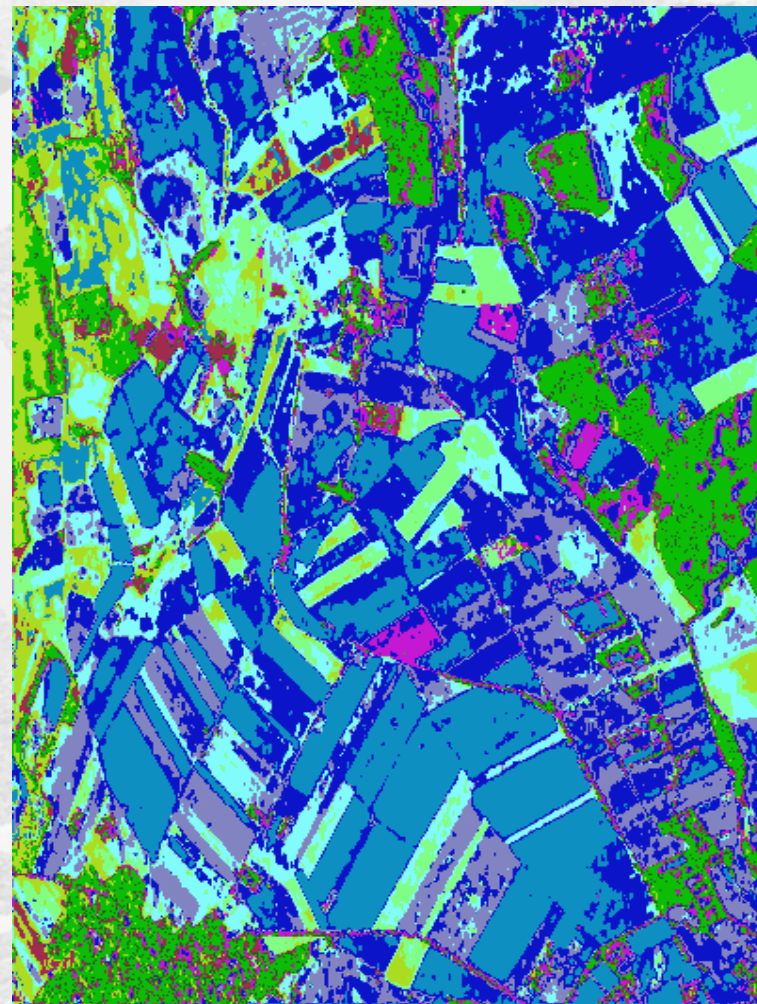
$B_0 + B$

$B_0 - B$



ALLING - ESAR L-band

H / A / α and WISHART CLASSIFIER

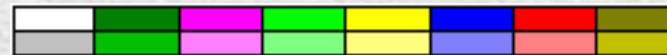


$2A_0$

$B_0 + B$

$B_0 - B$

C1 C2 C3 C4 C5 C6 C7 C8

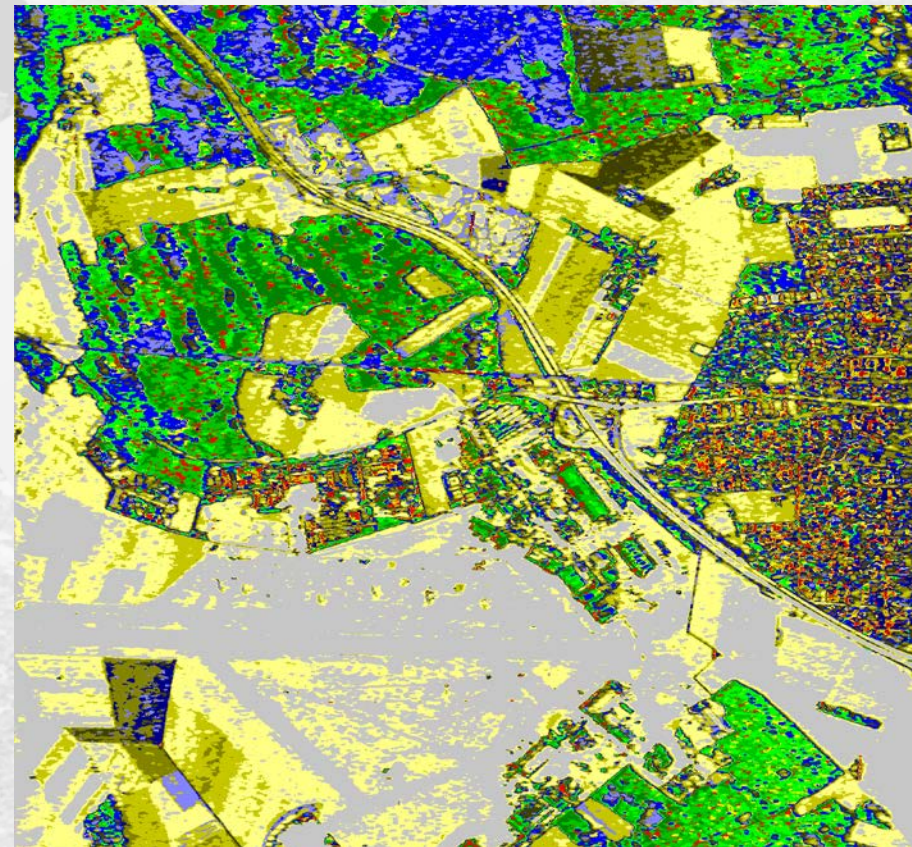


C9 C10 C11 C12 C13 C14 C15 C16

OBERPFAFFENHOFEN - ESAR L-band



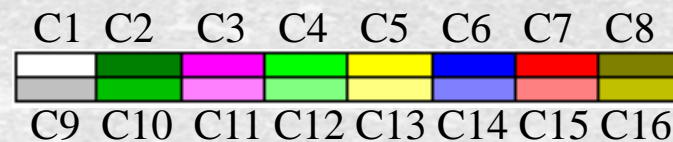
H / A / α and WISHART CLASSIFIER



$2A_0$

$B_0 + B$

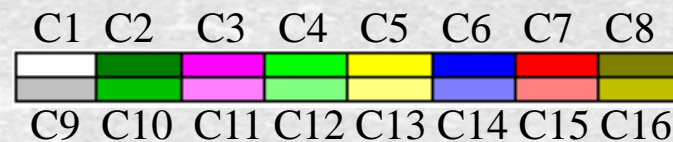
$B_0 - B$



OBERPFAFFENHOFEN - ESAR L-band



H / A / α and WISHART CLASSIFIER

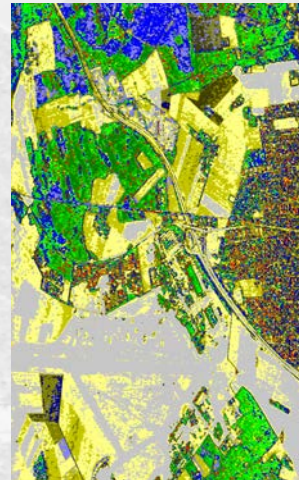


WISHART PDF
$$P(\langle [T] \rangle / [T_m]) = \frac{L^L p \langle [T] \rangle^{L-p} e^{-LTr([T_m]^{-1} \langle [T] \rangle)}}{\pi^{\frac{p(p-1)}{2}} \Gamma(L) \dots \Gamma(L-p+1) [T_m]^L}$$



UNSUPERVISED POLARSAR CLASSIFICATION

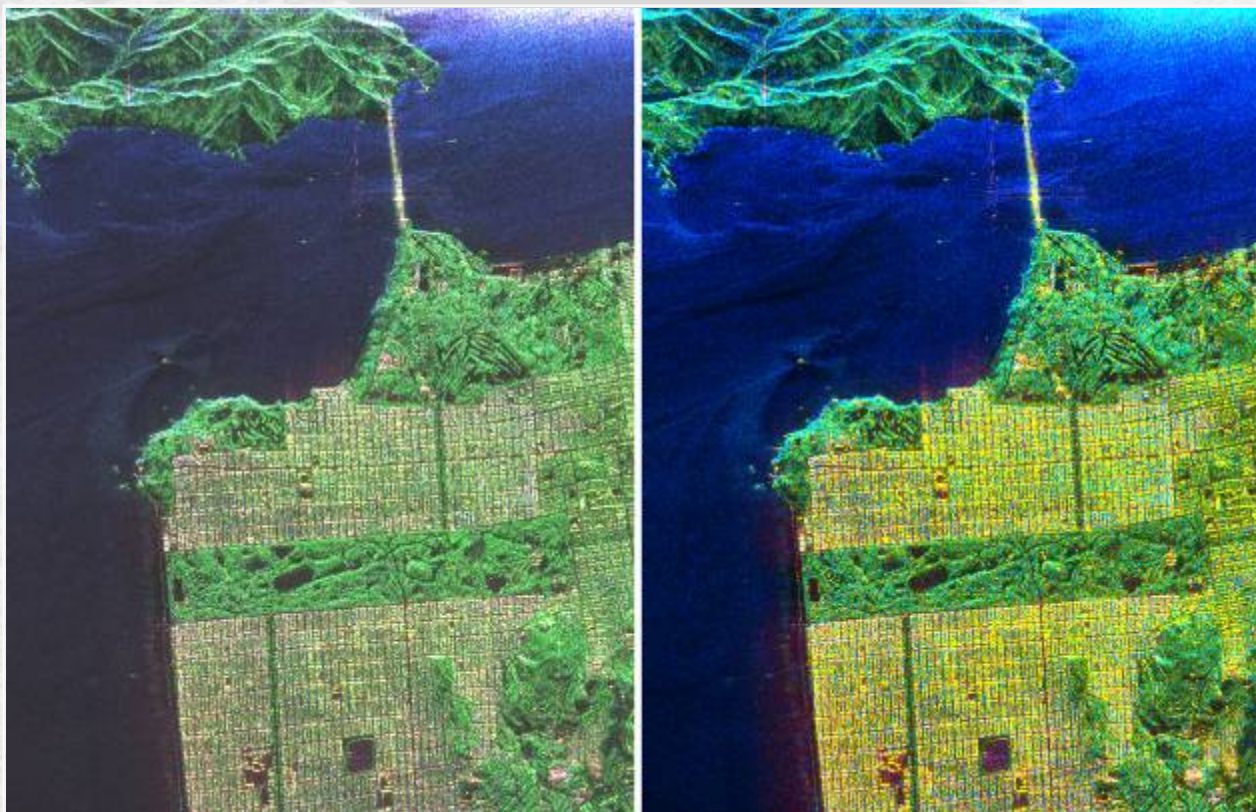
J.S LEE et al. (2002)



Unsupervised Classification Preserving Scattering Mechanisms

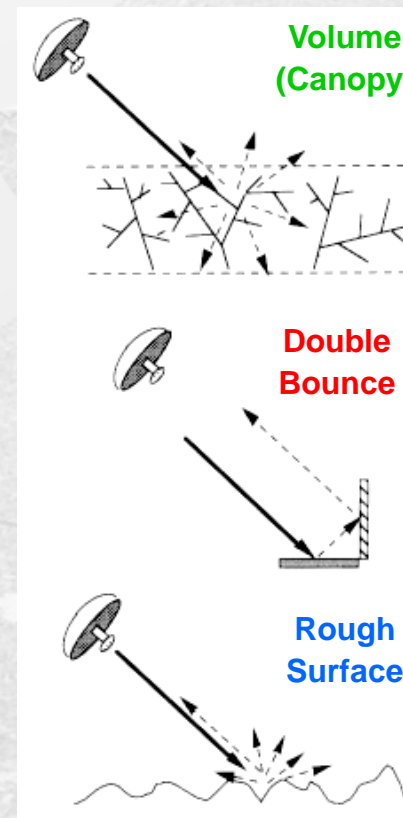
J.S. Lee, M.R. Grunes, E. Pottier and L. Ferro-Famil, "Segmentation of polarimetric SAR images that preserves scattering mechanisms"
Proceedings of EUSAR2002

Courtesy of Dr J.S Lee

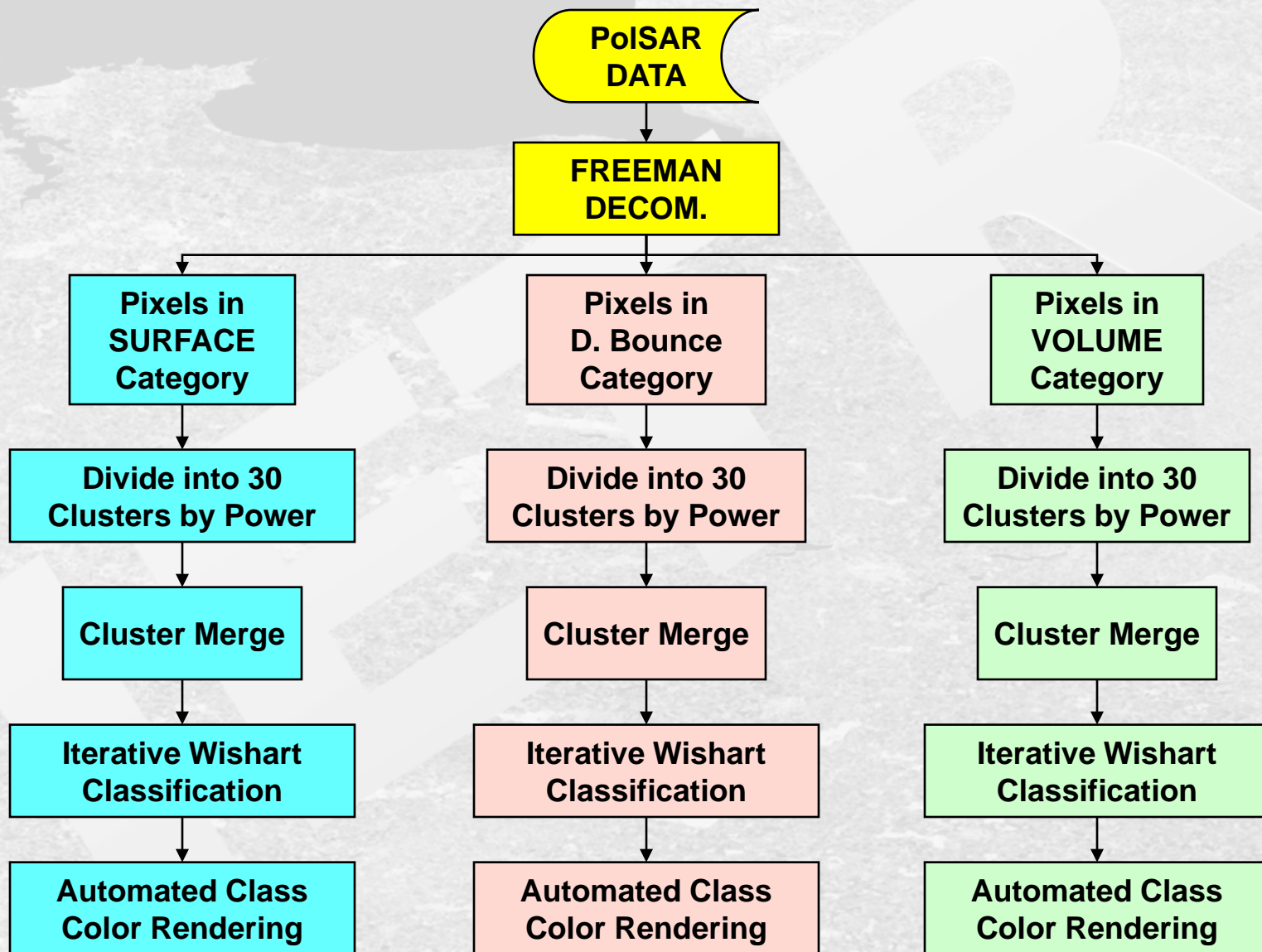


$|HH-VV|$, $|HV|$, $|HH+VV|$

Freeman and Durden



A. Freeman and S.L. Durden, "A Three-Component Scattering Model for Polarimetric SAR Data" IEEE TGRS, vol. 36, no. 3, May 1998



Cluster Merging $D_{ij} = \frac{1}{2} \{ \ln(|V_i|) + \ln(|V_j|) + \text{Tr}(V_i^{-1}V_j + V_j^{-1}V_i) \}$

Wishart Iteration – After Class Merge

Classification Maps



First Iteration



Second Iteration



Third Iteration

Note: Stability insures good convergence

Courtesy of Dr J.S Lee



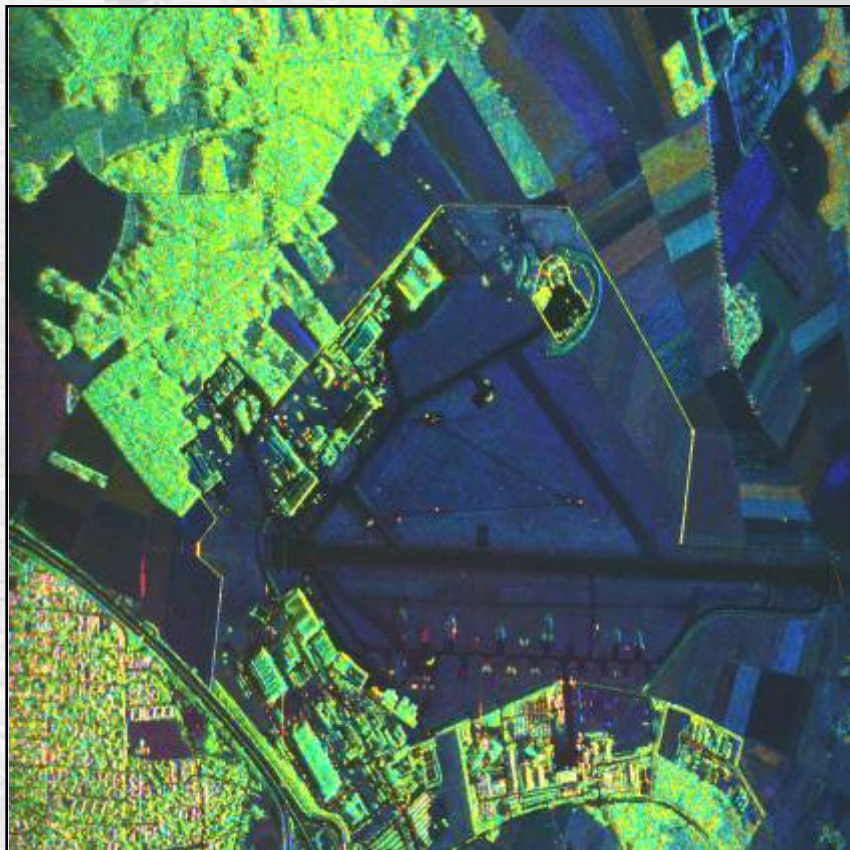
$|HH-VV|$, $|HV|$, $|HH+VV|$



4th Iteration (15 classes)



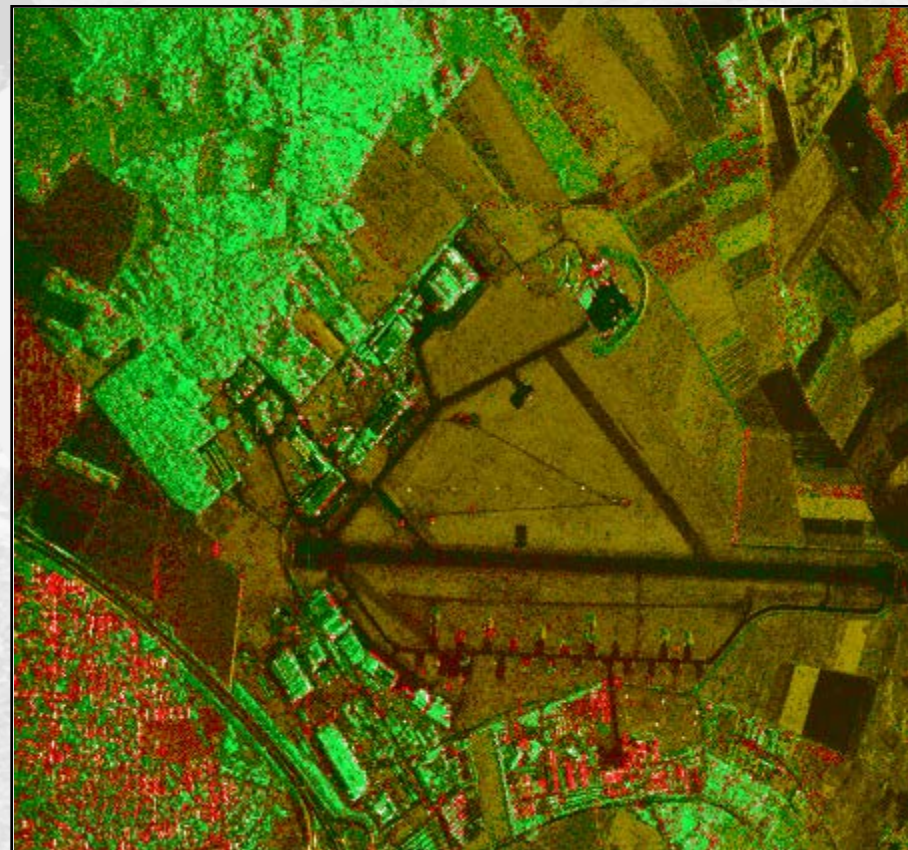
Courtesy of Dr J.S Lee



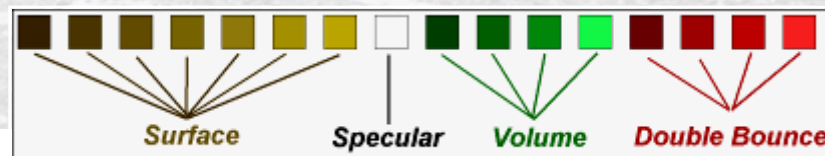
$2A_0$

$B_0 + B$

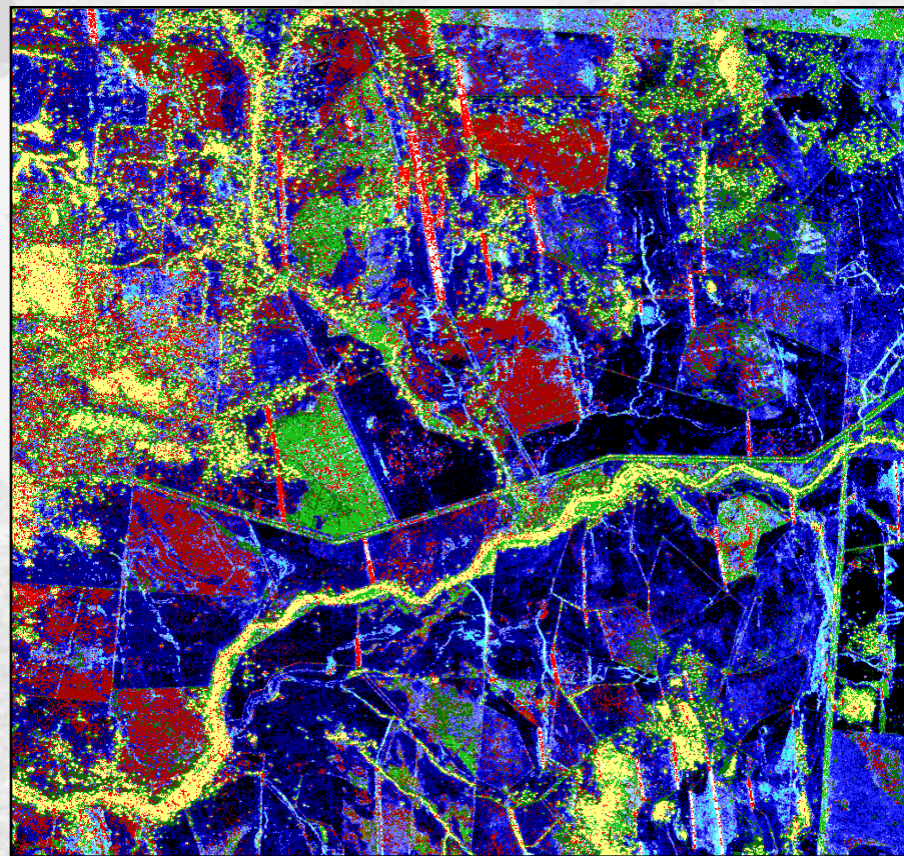
$B_0 - B$



4th Iteration (15 classes)



Courtesy of Dr J.S Lee



$2A_0$

$B_0 + B$

$B_0 - B$

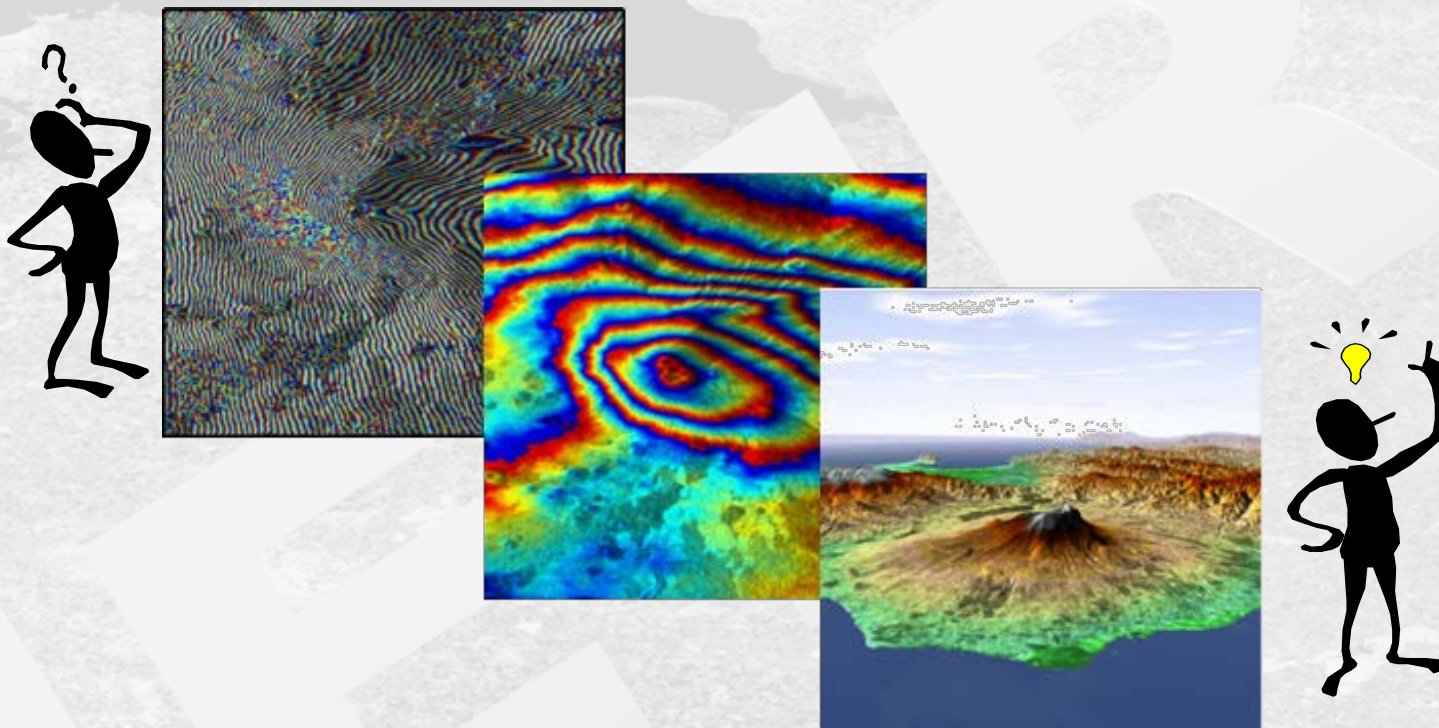
Australian Pasture

4th Iteration (15 classes)

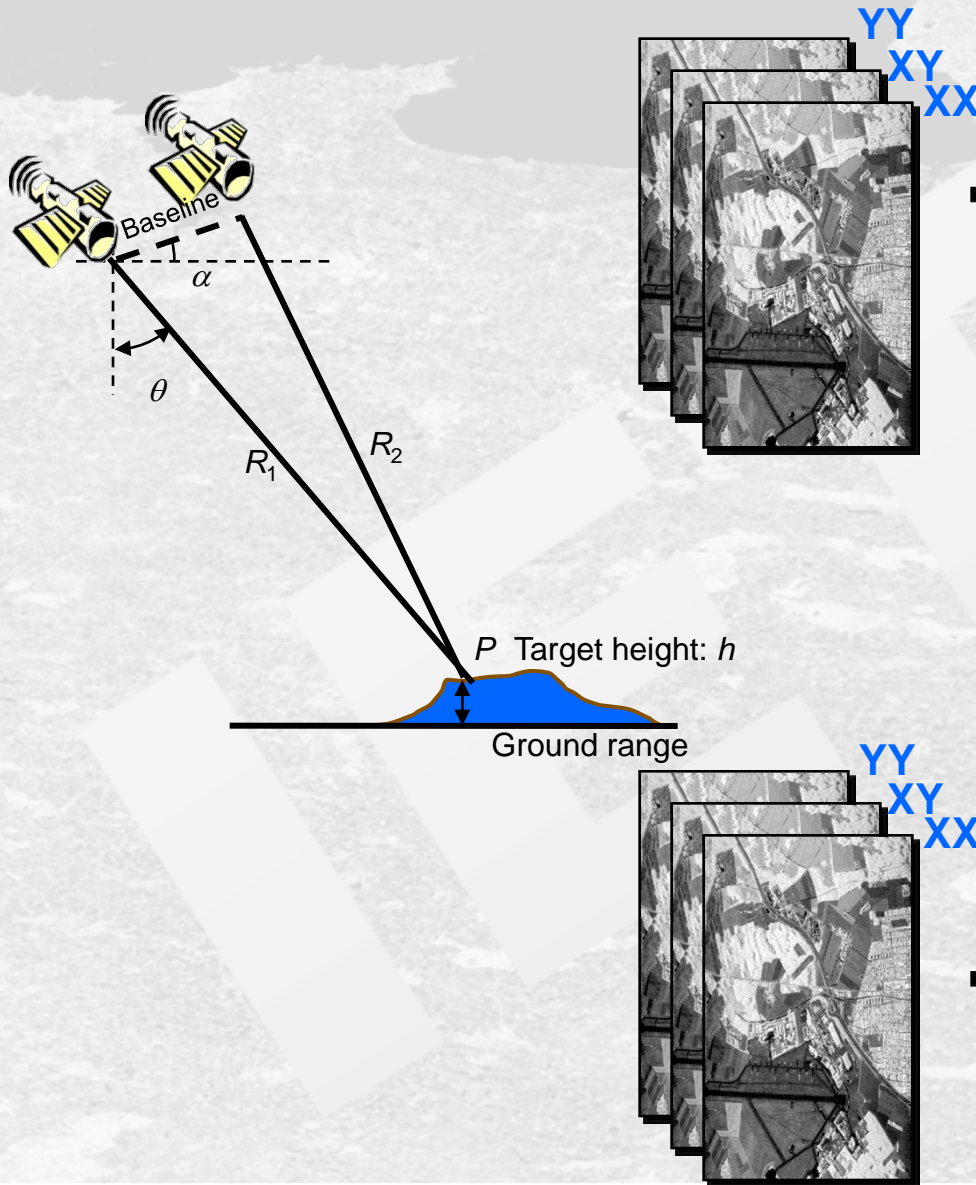


L-Band Volume Dominated





POLARIMETRIC INTERFEROMETRIC SAR (Pol-InSAR)



$$\underline{k}_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} S_{XX_1} + S_{YY_1} \\ S_{XX_1} - S_{YY_1} \\ 2S_{XY_1} \end{bmatrix}$$

$$\underline{k} = \begin{bmatrix} \underline{k}_1 \\ \underline{k}_2 \end{bmatrix}$$

POLARIMETRIC INTERFEROMETRIC TARGET VECTOR

$$\underline{k}_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} S_{XX_2} + S_{YY_2} \\ S_{XX_2} - S_{YY_2} \\ 2S_{XY_2} \end{bmatrix}$$

$$\underline{\underline{k}} = \begin{bmatrix} \underline{k}_1 \\ \underline{k}_2 \end{bmatrix}$$

**POLARIMETRIC
INTERFEROMETRIC
TARGET VECTOR**



$$\langle [T_6] \rangle = \langle \underline{\underline{k}} \cdot \underline{\underline{k}}^{T*} \rangle = \begin{bmatrix} \langle \underline{k}_1 \cdot \underline{k}_1^{T*} \rangle & \langle \underline{k}_1 \cdot \underline{k}_2^{T*} \rangle \\ \langle \underline{k}_2 \cdot \underline{k}_1^{T*} \rangle & \langle \underline{k}_2 \cdot \underline{k}_2^{T*} \rangle \end{bmatrix} = \begin{bmatrix} \langle [T_1] \rangle & \langle [\Omega_{12}] \rangle \\ \langle [\Omega_{12}]^{T*} \rangle & \langle [T_2] \rangle \end{bmatrix}$$

POLARIMETRIC INTERFEROMETRIC COHERENCY MATRIX (6x6)

$\langle [T_1] \rangle$ **HERMITIAN POLARIMETRIC COHERENCY MATRIX (3x3)**

$\langle [T_2] \rangle$ **HERMITIAN POLARIMETRIC COHERENCY MATRIX (3x3)**

$\langle [\Omega_{12}] \rangle$ **NON HERMITIAN POLARIMETRIC INTER-COHERENCY MATRIX (3x3)**

DUAL CHANNELS POLINSAR UNSUPERVISED SEGMENTATION

$$\langle [T_6] \rangle = \langle \underline{\underline{k}} \cdot \underline{\underline{k}}^{T*} \rangle = \begin{bmatrix} \langle \underline{k}_1 \cdot \underline{k}_1^{T*} \rangle & \langle \underline{k}_1 \cdot \underline{k}_2^{T*} \rangle \\ \langle \underline{k}_2 \cdot \underline{k}_1^{T*} \rangle & \langle \underline{k}_2 \cdot \underline{k}_2^{T*} \rangle \end{bmatrix} = \begin{bmatrix} \langle [T_1] \rangle & \langle [\Omega_{12}] \rangle \\ \langle [\Omega_{12}]^{T*} \rangle & \langle [T_2] \rangle \end{bmatrix}$$

POLARIMETRIC INTERFEROMETRIC COHERENCY MATRIX (6x6)



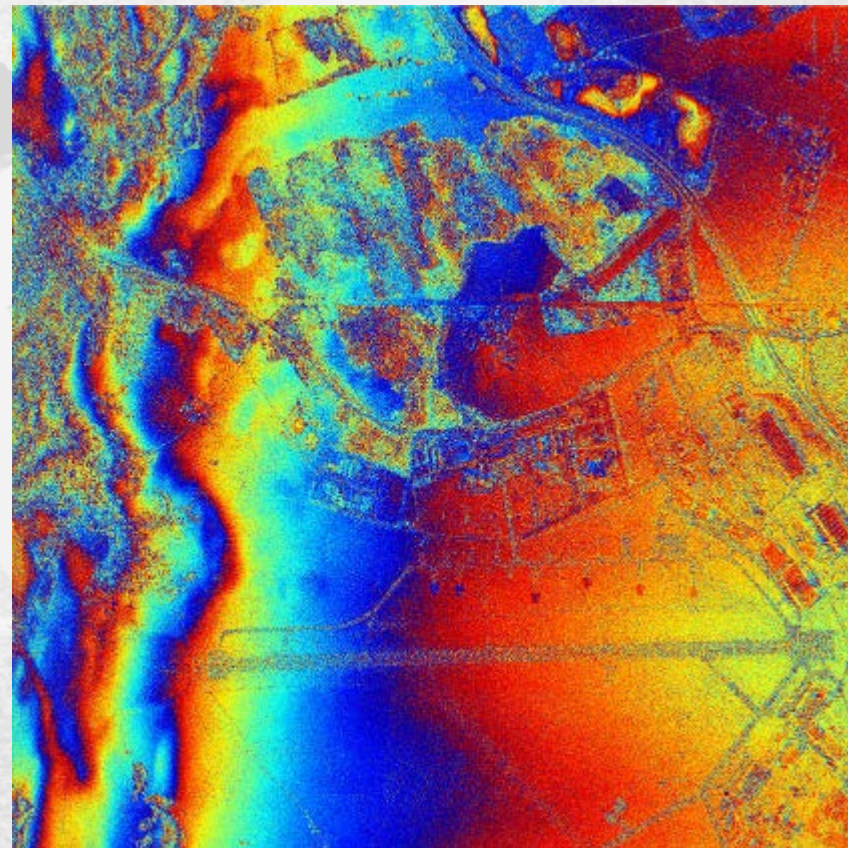
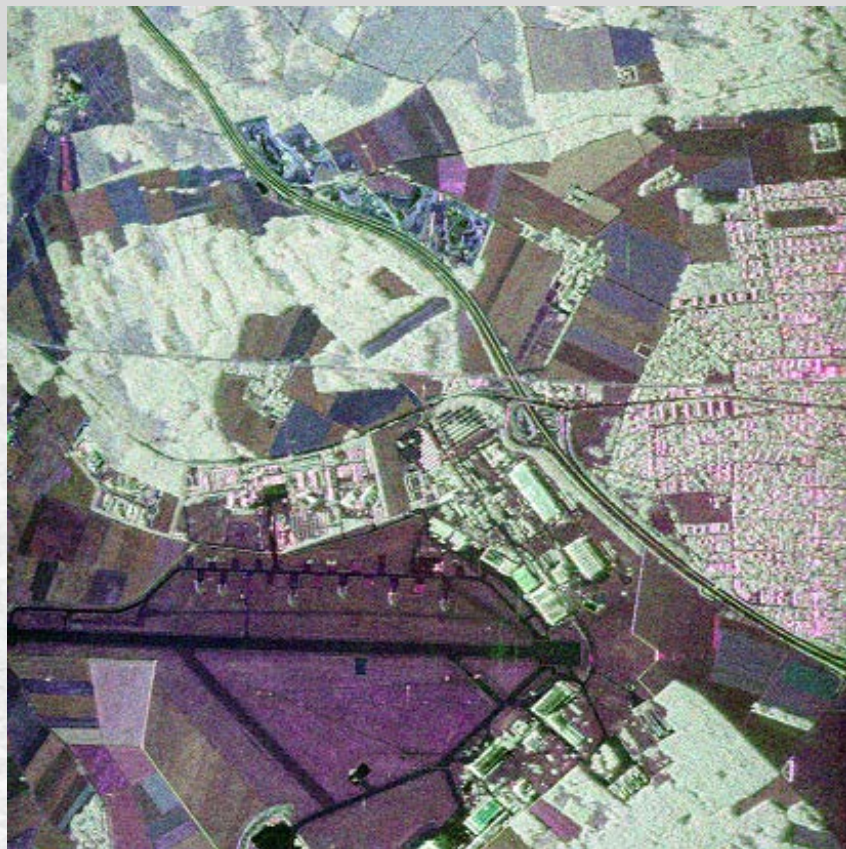
$\langle [T_6] \rangle$ **FOLLOWS A WISHART DISTRIBUTION**

$$P(\langle [T_6] \rangle / [\Sigma_m]) = \frac{|\langle [T_6] \rangle|^{L-p} \exp(-\text{tr}([\Sigma_m]^{-1} \langle [T_6] \rangle))}{K(L, p) [\Sigma_m]^L} = W_C(L, [\Sigma_m])$$

L: Number of Look
p: Polarimetric Dimension

With: $K(L, p) = \frac{\pi^{\frac{p(p-1)}{2}}}{L^{Lp}} \Gamma(L) \dots \Gamma(L - p + 1)$

$[\Sigma_m]$: Cluster Center of the class m

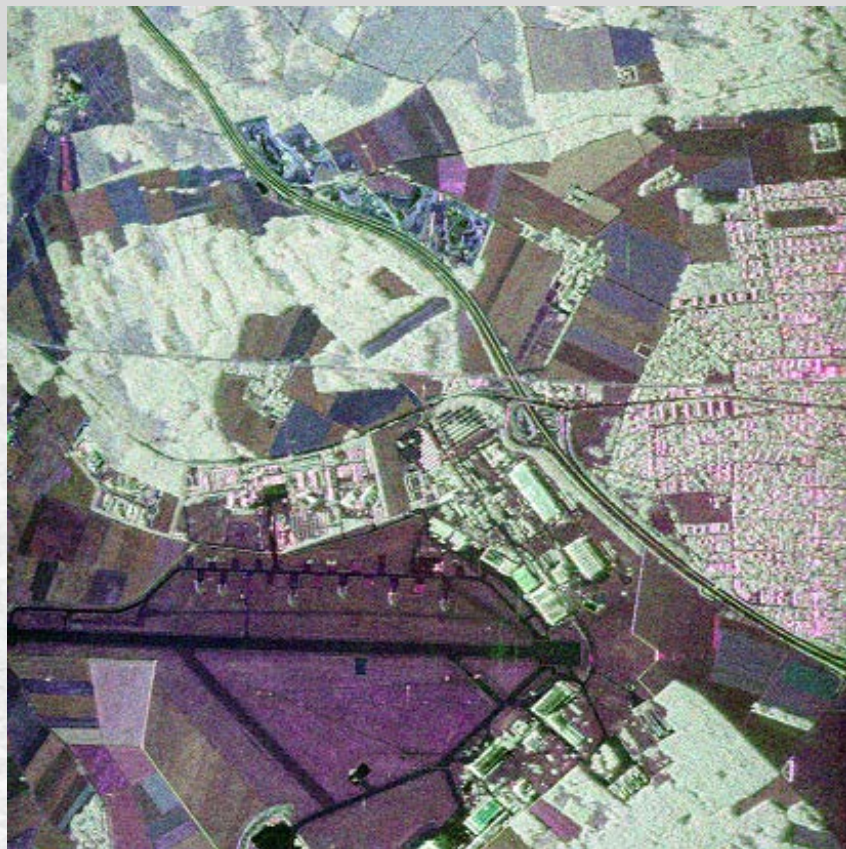


DLR E-SAR L Band
Pol-In SAR (1.5m x 3m) – Baseline 15m



POL-SAR INFORMATION

IN-SAR INFORMATION $\text{Arg}(\gamma)$



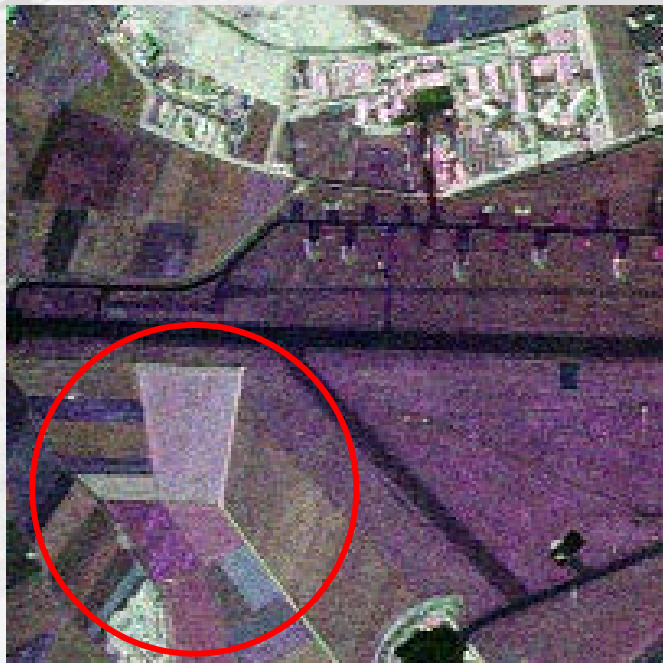
DLR E-SAR L Band
Pol-In SAR (1.5m x 3m) – Baseline 5m

POL-SAR INFORMATION

IN-SAR INFORMATION

$|\gamma|$

COMPLEMENTARY INFORMATION



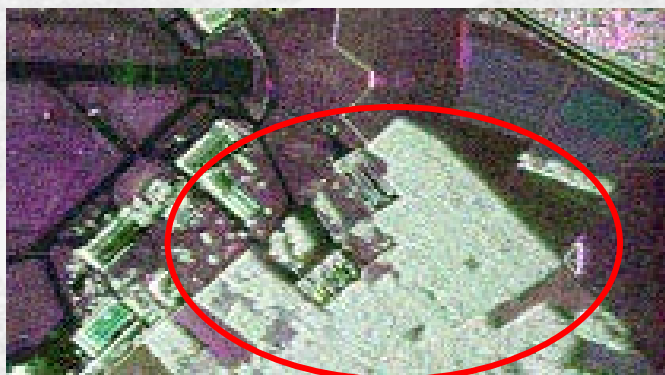
HETEROGENEOUS AREA

**DIFFERENT POLARIMETRIC
SCATTERING MECHANISMS**



HOMOGENEOUS AREA

**CONSTANT INTERFEROMETRIC
COHERENCE**

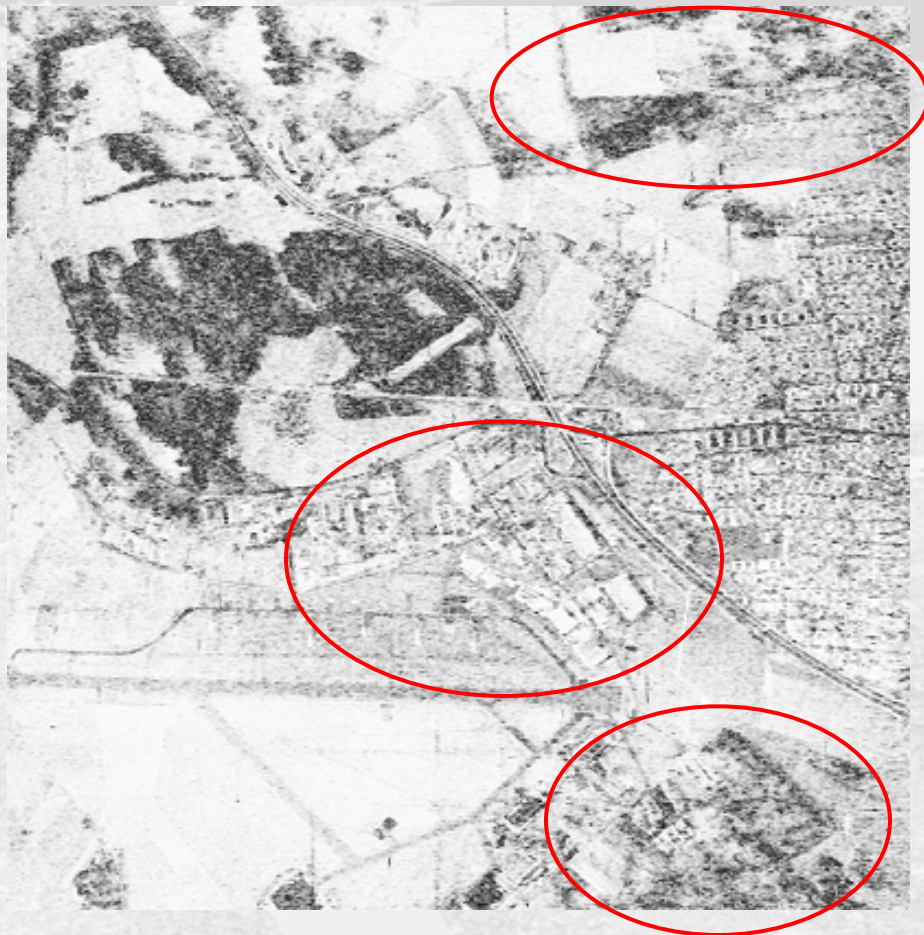


HOMOGENEOUS AREA

HETEROGENEOUS AREA

**SAME POLARIMETRIC
SCATTERING MECHANISMS**

**DIFFERENT INTERFEROMETRIC
COHERENCE**



INTERFEROMETRIC COHERENCE γ

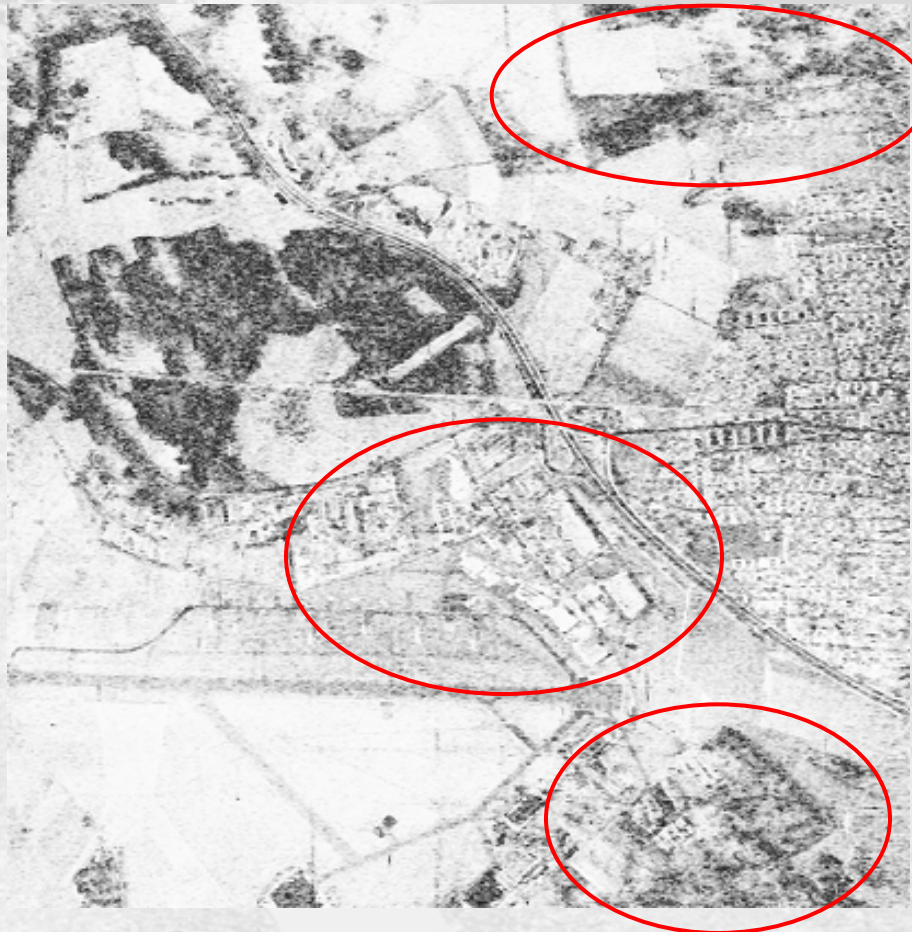


$2A_0$

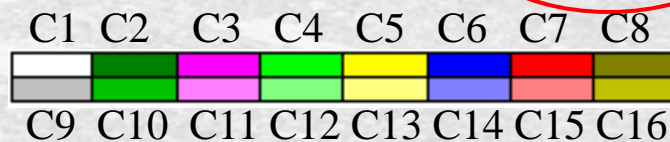
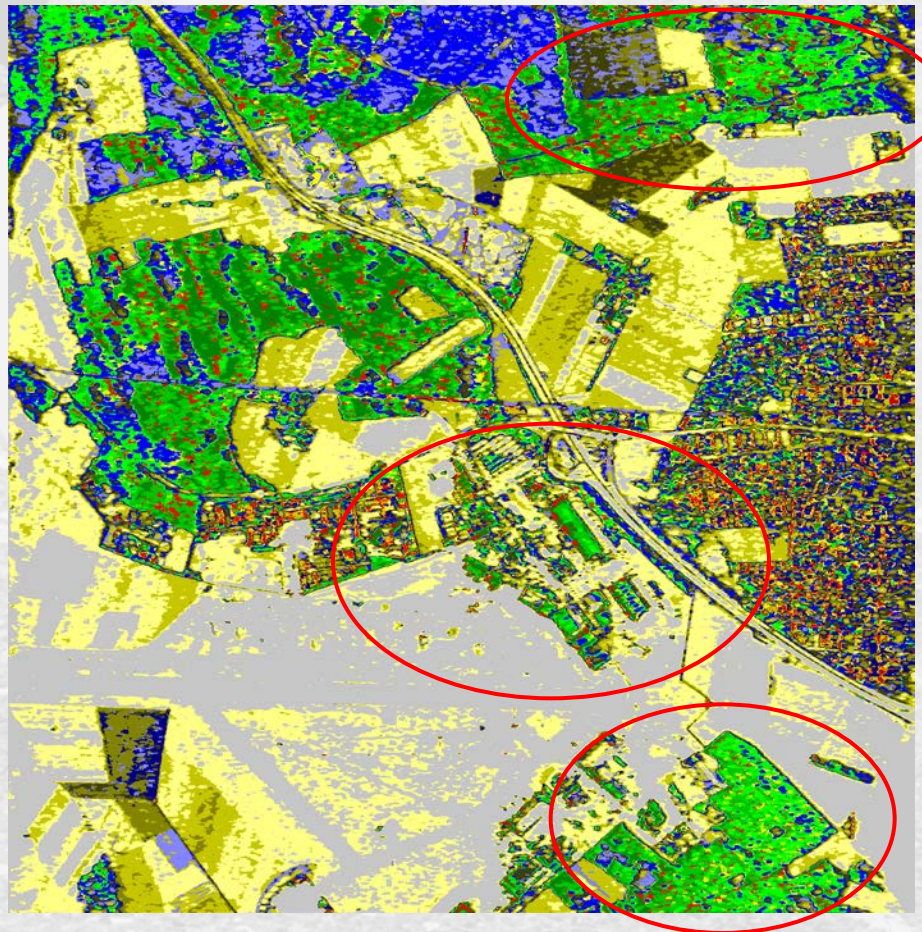
$B_0 + B$

$B_0 - B$

Wishart H-A- α segmentation



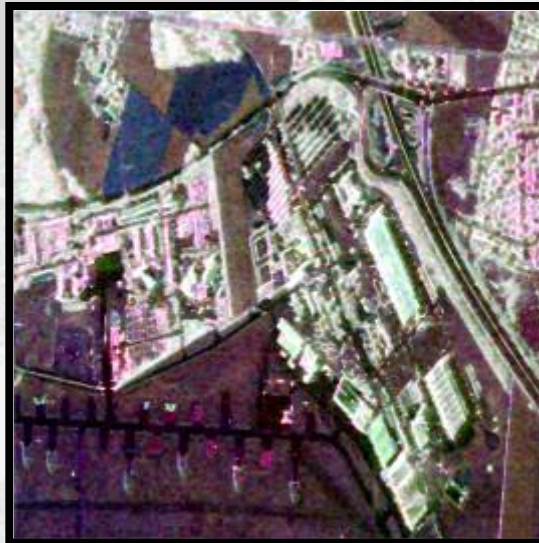
INTERFEROMETRIC COHERENCE γ



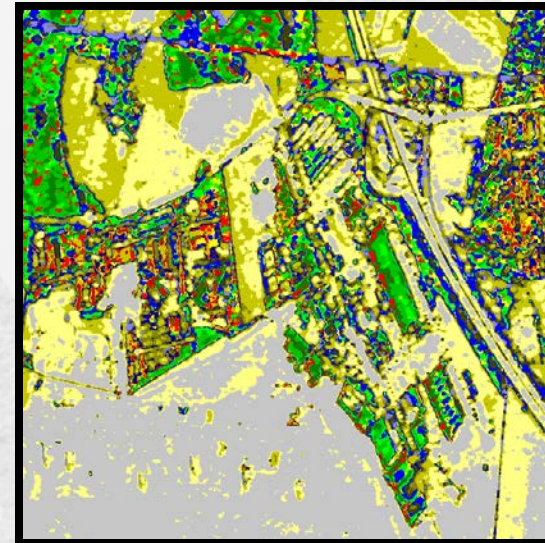
Optical Image



POLSAR Image



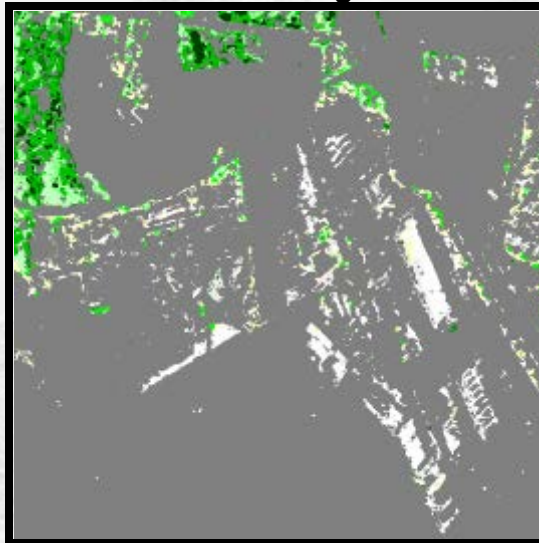
POLSAR Segmentation



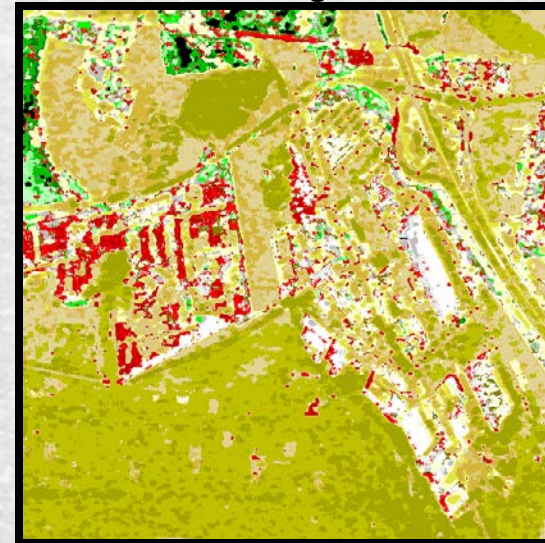
INSAR Image



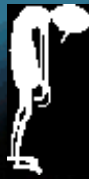
VOL POLINSAR Segmentation



POLINSAR Segmentation



Oriented buildings segmented from vegetated areas

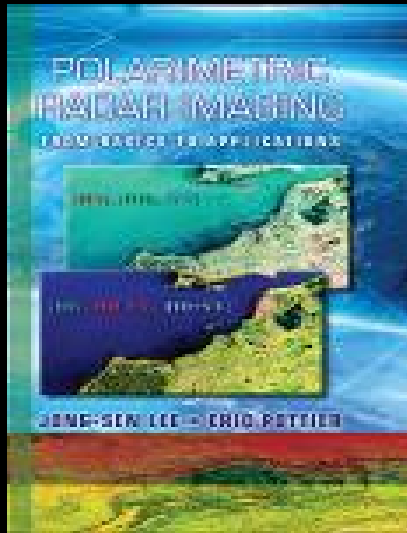


Questions ?



KODAK LAMBDA 100-UM 854029 L

Books On Polarimetric Radar SAR, Polarimetric Interferometry

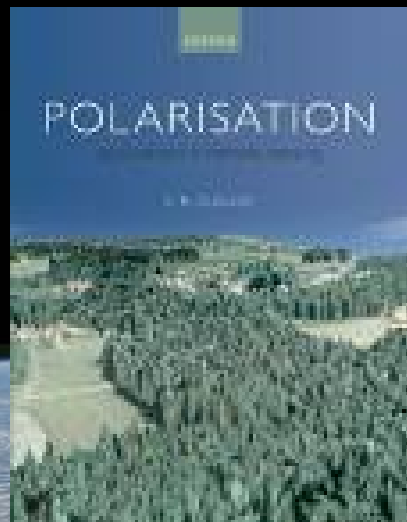


Polarimetric Radar Imaging: From basics to applications

Jong-Sen LEE – Eric POTTIER

CRC Press; 1st ed., February 2009, pp 422

ISBN: 978-1420054972



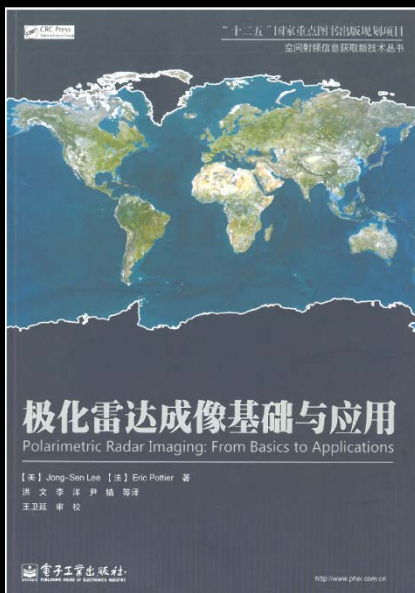
Polarisation: Applications in Remote Sensing

Shane R. CLOUDE

Oxford University Press, October 2009, pp 352

ISBN: 978-0199569731

Books On Polarimetric Radar SAR, Polarimetric Interferometry



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Prof. Wen HONG, Dr. Qiang YIN et al.



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