

## **GPS Data Capture With ArcPad**

#### Chris Wayne ESRI-Northwest, Seattle





Essentials of GPS

- GPS Data Capture with ArcPad
- ArcPad and GPS Integration Settings
- Field Mapping System Considerations
  HARDWARE!



#### **Essentials of GPS**

Evolving as a key component of GIS

- Works on trilateration of satellite radio signals from satellites
- "How Far?" = "How long did it take the radio waves to get from the satellite to the receiver?"
- All signals and positions have error



#### **GPS** Components

- Antenna-receiver
- Processor = The GPS
  - Contain quartz clocks of varying quality
- Data Logger
- Computer Software
- Various Grades of GPS
  - Recreational
  - Resource Mapping
  - Sub-meter
  - Survey





## **GIS-GPS** Integration Workflow

- Build an enterprise database
- Determine field data collection methodology
- Collect the field data: geometry and attributes
- Import field data into GIS format
- Analyze and interpret new data in GIS



#### **GPS Mission Planning**

 Objective: Integrate your field data with your enterprise GIS
 What is the Enterprise?

- Pick a study area and environment
- Plan to update certain features on the ground using GPS
- Plan feature and attribute data models



### Planning for attribute capture

- Design in Attribute fields: Always include a Notes field (text, 256 width)
  - GDB Domains = allowable values for each field: Always include "other"
    - + GDB Subtypes  $\rightarrow$  Default values
  - Geodatabase & ArcPad Studio Build forms
- Maintains data value consistency, saves time
- Other Examples: Trimble Pathfinder Office, Rite in the Rain Notebooks
- Possible but not easy to modify in field



#### Planning for feature capture

Feature geometry may depend on scale
Polygon size: meters, acres, miles?

Land cover ("fuzzy") vs. parking lot ("sharp")

Douglas Co. Parks Example

Parks as points for locator map
Features as points, line, polygons



#### Data Life Cycle : ArcPad in ArcGIS 8.3

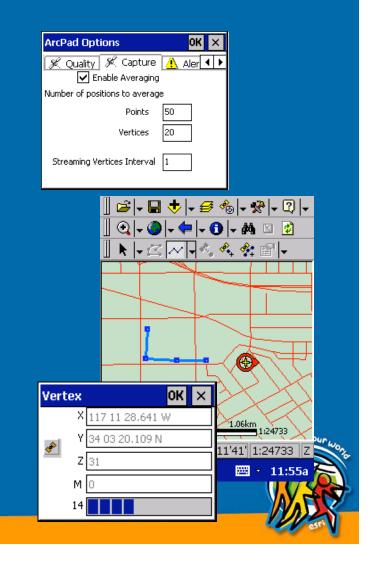
- Start with GeoDatabase (personal or SDE)
- Make an ArcMap and export to ArcPad
   GDB → .shp + scripts and forms
- Update/add features to shapefiles
- Upload .shp data to PC and check updated features back into GDB



#### GPS data capture in ArcPad

- Capture points, lines, polys
- Point and streaming mode digitizing
- Edit geometry
  - Add, move
  - Features or vertex
  - Append to lines
- Specify streaming vertices interval
- Position averaging for points and vertices
- Quality Thresholds





#### Accuracy

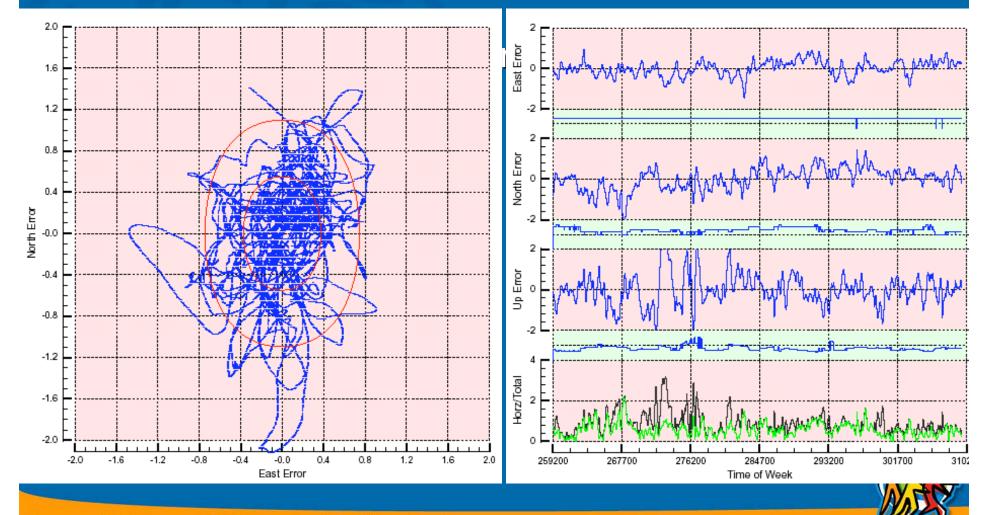
 GPS position accuracy is established by the GPS receiver - Autonomous Real-Time differential correction Post-processing - Supported via Trimble's GPScorrect extension for ArcPad 6 ArcPad and GPS data capture accuracy Controlled by quality thresholds Enhanced by position averaging



Static accuracy

- Characterized at known positions (truth)
- Data logged for 12+ hours
- Data logged in the open and under canopy
- Dynamic accuracy
  - Walk/drive between two known positions
  - Measure perpendicular error from straight line

- Often referred to as pass-to-pass accuracy





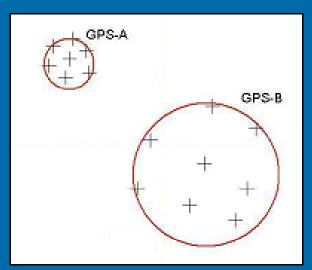
- Comparing two receivers
  - Data must be logged at the same time
  - Antennas must be <1m apart</li>
  - Settings must be identical
  - Turn off automatic features
  - Log in typical environment
  - Log close to where equipment will be used
  - Be sure of WGS84 coordinates of truth points
  - Log as much data as possible and repeat tests



#### Accuracy versus Precision Accuracy is an absolute measure against truth Precision is a relative measure of variability Need accuracy for Collecting data for a GIS Relocating assets Need precision for Measuring lengths and areas Vehicle guidance

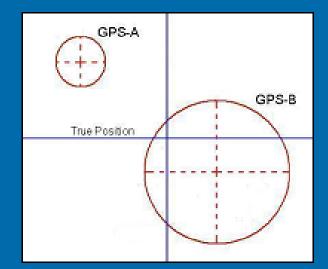


 GPS-A is more <u>precise</u> than GPS-B





 After averaging, GPS-B is more <u>accurate</u> than GPS-A





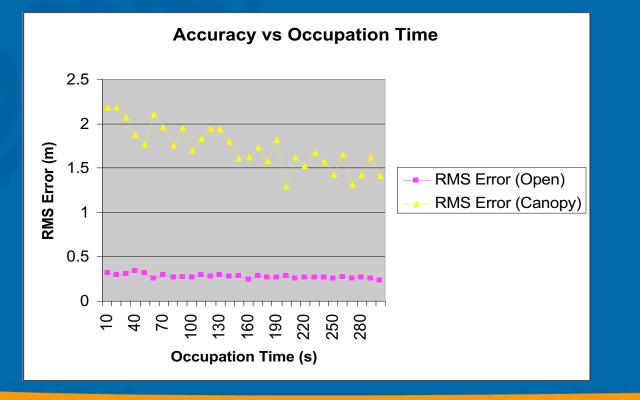
# What factors affect GPS accuracy

 Receiver and antenna type Data collection and processing techniques - Occupation time, settings Differential correction Satellite geometry – DOP -Varies over time, but predictable - In-field mission planning Environment Ionospheric conditions Obstructions and multipath EVEREST multipath rejection



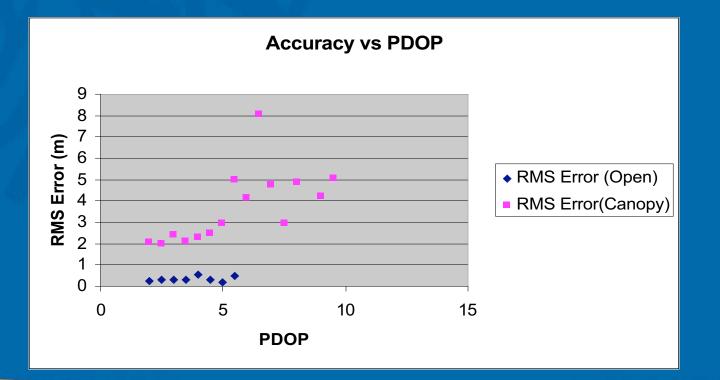
#### What factors affect GPS accuracy

- Accuracy improves marginally with occupation time
- Improvement more significant in tough environments



#### What factors affect GPS accuracy

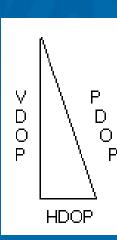
- Error increases with DOP, linearly for higher DOPs
- Impact is more significant in tough environments

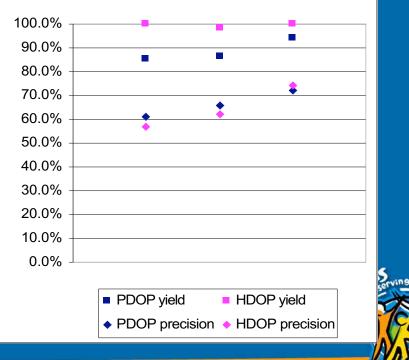


#### What factors affect GPS accuracy

Use PDOP mask (6) for 3D
Use HDOP mask (4) for 2D (i.e. no need for heights) – gives better yield for similar horizontal precision

•  $PDOP^2 = HDOP^2 + VDOP^2$ 



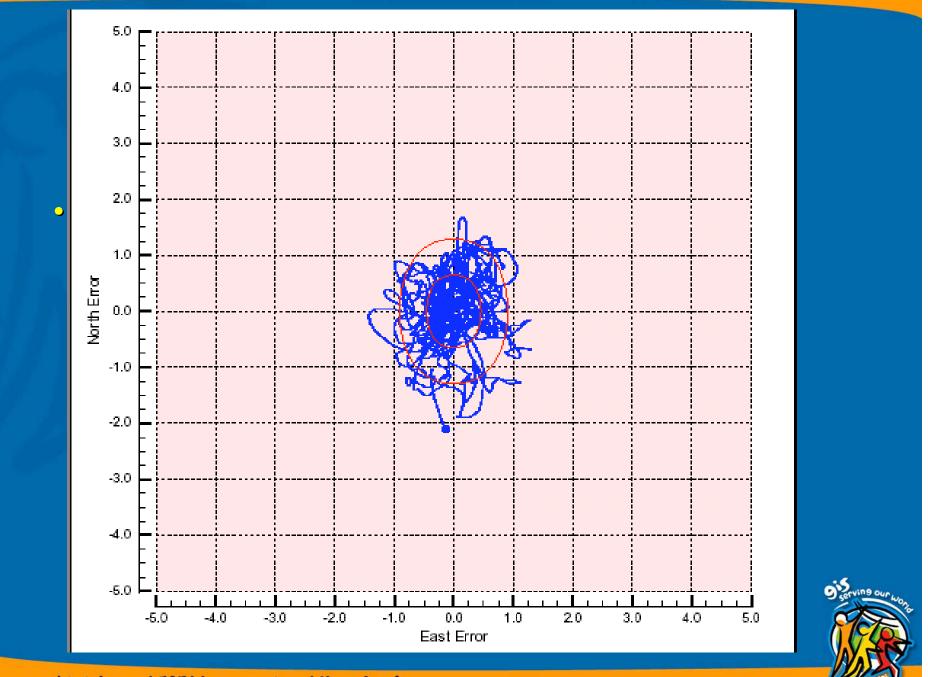


# How accurate is real-time differential GPS

#### Depends on receiver type

- Submeter
- 2-5m
- 3-15m
- And correction source
  - Satellite differential
  - Beacon
  - WAAS
  - Other RTCM source
- RTCM age limit is a yield / accuracy trade-off
- Velocity filtering helps in tough environments





#### What is WAAS

- Wide Area Augmentation System
- Created by US Federal Aviation Administration to improve efficiency of aviation operations
- Augments GPS with correction signal from geostationary satellite on GPS frequency
- Initial Operation Capability not yet declared
- Free to use
- 7m vertical / horizontal



# Is accuracy improved by postprocessing???

Real-time DGPS can be postprocessed to further improve accuracy by

GPS Pathfinder Office
GPS Pathfinder Express
Using closer base stations
Filling in any real-time gaps

Log velocity records for line / area smoothing



#### Differential Correction – Better GPS



Green = GPS after differential correction with GPScorrect



#### Quality Thresholds

- Quality controls
- Warnings
  - Non-compulsory
  - Compulsory
- Alerts
  - Message box
  - Sound alarm

| ArcPad Options  | ок 🗙          |
|---|---------------|
| K Quality <u>K Ca</u><br>O No Warnings<br>Non-Compuls<br>Compulsory | sory Warnings |
| Maximum PDOP Maximum EPE DGPS Mode Only SD Mode Only                | 6             |



## Accuracy vs. Yield vs. Storage

- It may be more important to get ANY GPS position...
- Than to get a good position
- Most accurate settings =/= most receptive
- Adjustable as situation dictates: Bad reception, "canyon conditions,"
- Speed of travel $\rightarrow$ point interval time
- Run stats on precision



#### **Real-time correction**

- Corrects positions before they are collected
- Broadcast from three sources
  - Beacon- USCG Navigation beacon, free
  - Commercial Satellite- By subscription
  - WAAS- Free, line of site, avaiation
- GPS unit must be enabled
   – each source is a separate feature



#### ArcPad GPS connectivity

#### Support GPS protocols

- NMEA 0183
- TSIP
- Delorme Earthmate
- Federal PLGR
- Works with almost all GPS receivers that output these protocols
- Key to success: understanding the relationship between GPS Setting and ArcPad Settings



## **GPS** navigation

 Basic navigation Shows current GPS location and direction of travel Automatically centers map on GPS position Shows distance and bearing to destination GPS Tracklog - "bread crumb" trail Captures GPS Tracklog as shapefile with no attributes



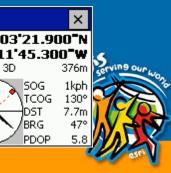
#### **GPS Position Window**

- Displays info from GPS receiver
  Current X, Y, Z Position in different coordinate systems
- GPS Mode
  - 2D, 3D, DGPS, RTK
- Navigation information
- Satellite Skyplot
- Satellite signal strengths



| DMS                               |               | ×             |  |  |
|-----------------------------------|---------------|---------------|--|--|
| 34°03'21.540"N<br>117°11'45.480"W |               |               |  |  |
| 3D                                | 4J.40         | 384m          |  |  |
| 1<br>4<br>13                      | SOG (<br>TCOG | ).2kph<br>50° |  |  |
| 20<br>22<br>21                    | DST<br>BRG    | 19.3m<br>32°  |  |  |
| 29                                | PDOP          | 5.8           |  |  |

DMS



#### I can't see the GPS on my ArcPad Map!

#### 1. Check the GPS receiver

- Power on? set to output NMEA messages? Make sure all messages that can be sent are turned on.
- 2. Check Connections:
  - Make sure a NULL modem adaptor is used when attaching the GPS receiver to the CE device if necessary.
  - Put ArcPad in GPS Debug mode to verify that something is being sent to the CE device from the GPS receiver.
  - Check the GPS manual to determine the COM port settings (port number, baud rate, data bits, stop bits, parity) ;make sure the ArcPad Options are set accordingly.

#### **3.** Check Satellites

- If you are getting a signal in GPS Debug, open the skyplot and look at satellite signals
- 4. Check Coordinate System
  - Make sure your map has a coordinate system
  - GPS Output Datum set correctly?



# GPS Setting vs. ArcPad Settings

| PS<br>PS – WGS is usually<br>fault<br>PS – NMEA is usually<br>fault | ArcPad<br>ArcPad<br>ArcPad               |
|---|--|
| fault<br>PS – NMEA is usually                                       |  |
|   |  |
|   |  |
| Pad   | GPS – Usually Default of 1 second        |
| cPad  | GPS – Usually Default of 1               |
| cPad - Device   | N/A                                      |
| PS Defaults   | ArcPad                                   |
| cPad - Data   |  |
| PS – must be enabled  | ArcPad – Quality Options & Warning       |
|   | Pad - Device<br>S Defaults<br>Pad - Data |

### Building a Field GIS System

- GPS Receiver
- ArcPad Software
- ArcPad Hardware
- ArcGIS
- GIS Data
- Auxiliary devices and software



#### A Field Mapping System Must Enable You to...

Navigate:

to the site, back to base, then back to the features at a later date

• Record:

Capture new and/or Update existing data:

– location and/or attributes

Display:

Data you are recording + other map layers.

# Choosing a Field Mapping System: Hardware

| Determining Factors  |
|--|
| Proximity to infrastructure, vehicles. Carrying capability.                          |
| Physical carrying restrictions.  |
| Operating time frame, cost, added weight.  |
| Amount and type of background data to be used, and amount of data to be captured.    |
| Scale of mapping project.  |
| Number of peripheral devices to be used (GPS, laser rangefinder, etc.).              |
| Readability in low-light and bright light conditions, available screen display size. |
| Environment (tropics/desert).  |
| Budget.  |
|  |

#### Other Hardware and Gear

Auxiliary devices

 Transit -- Laser range finder
 Bar code scanner -- Hydrolab
 Digital camera -- voice recorder
 802.11
 CDPD/GPRS Wireless Internet

 Map and Compass



## **Other ESRI GPS Solutions**

ArcMap GPS Extension
ArcGIS Tracking Analyst
ArcIMS Tracking Server
Map Objects



### HARDWARE!

Look at the toys





Arcpad Interface
GPS Tools
GPS Editing
Hooking up a GPS
Collecting data!





